

DCM for fMRI – Advanced topics

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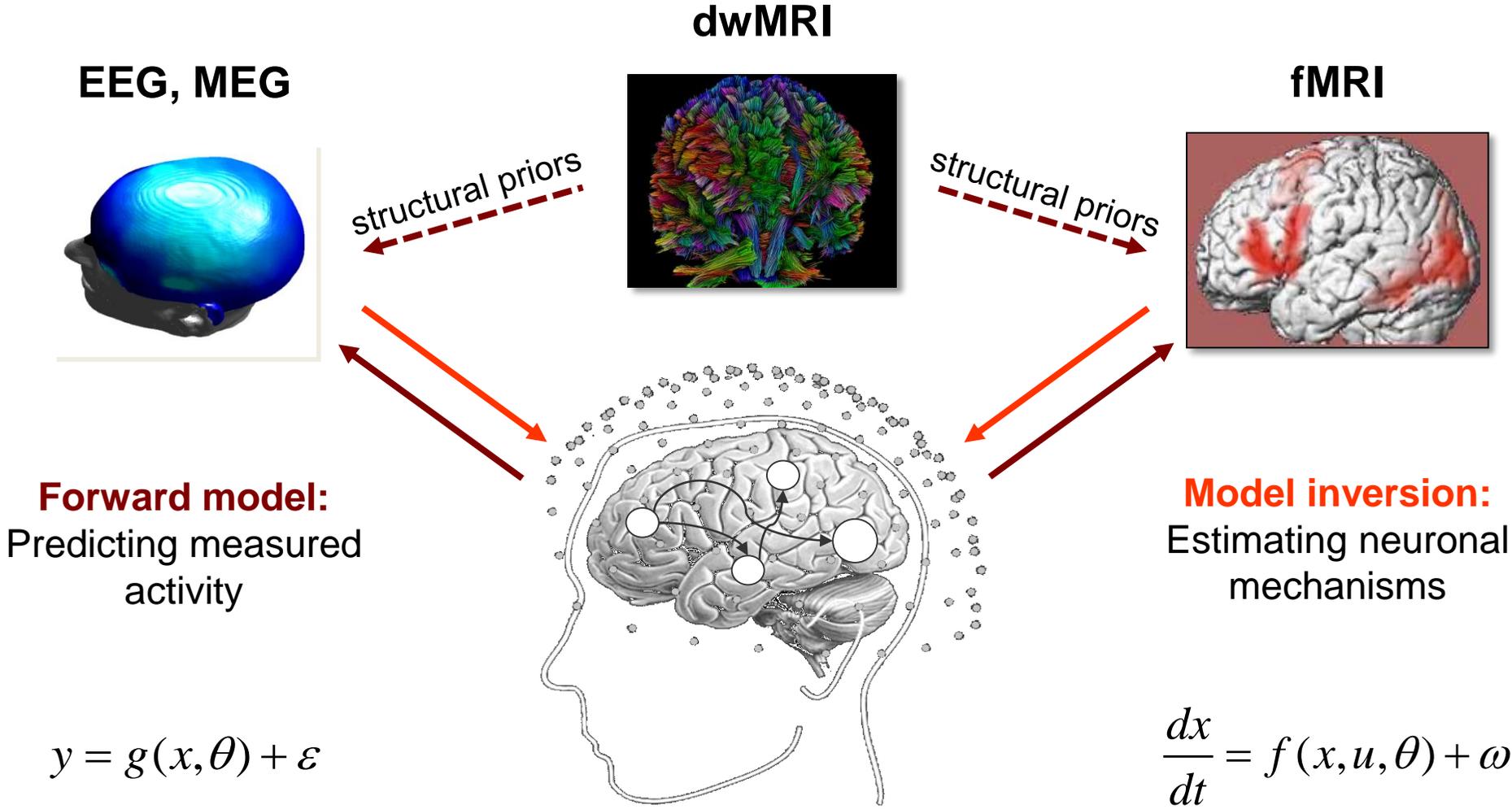
ETH

Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

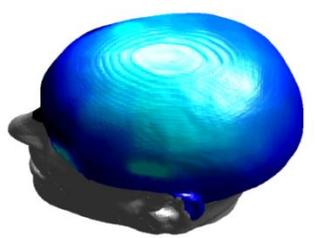
Overview

- DCM: basic concepts
- Evolution of DCM for fMRI
- Bayesian model selection (BMS)
- Translational Neuromodeling

Dynamic causal modeling (DCM)

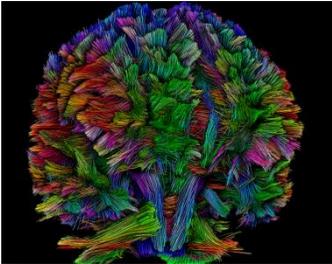


EEG, MEG



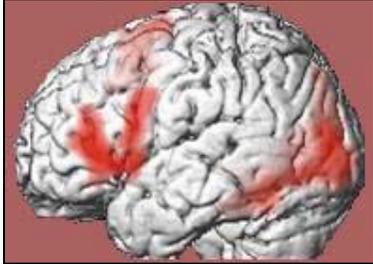
structural priors

dwMRI



structural priors

fMRI



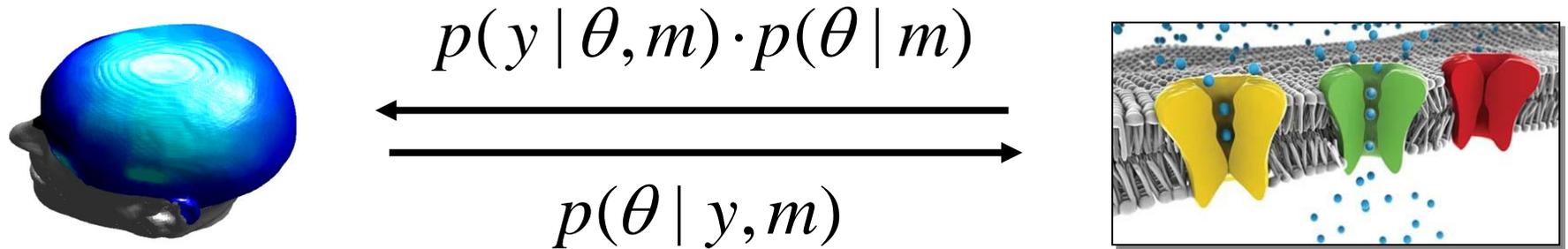
Forward model:
Predicting measured activity

$$y = g(x, \theta) + \varepsilon$$

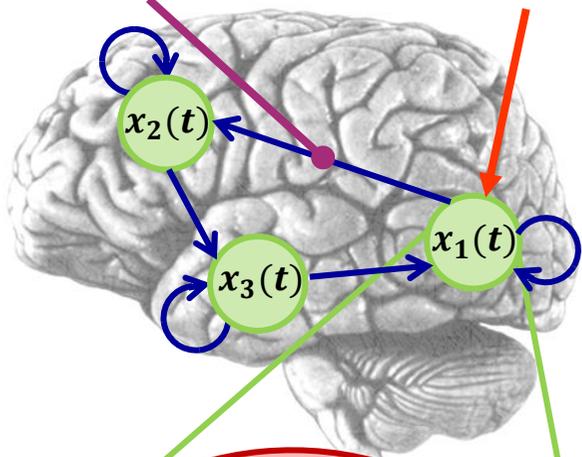
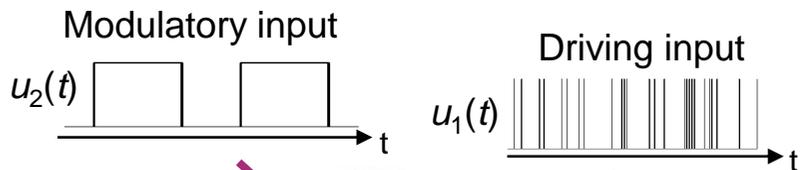
Model inversion:
Estimating neuronal mechanisms

$$\frac{dx}{dt} = f(x, u, \theta) + \omega$$

Generative model



1. enforces mechanistic thinking: how could the data have been caused?
2. generate synthetic data (observations) by sampling from the prior – can model explain certain phenomena at all?
3. inference about model structure: formal approach to disambiguating mechanisms $\rightarrow p(m|y)$ or $p(y|m)$
4. inference about parameters $\rightarrow p(\theta|y)$



Neuronal state equation

$$\dot{x} = \left(A + \sum u_j B^{(j)} \right) x + Cu$$

- endogenous connectivity $A = \frac{\partial \dot{x}}{\partial x}$
- modulation of connectivity $B^{(j)} = \frac{\partial}{\partial u_j} \frac{\partial \dot{x}}{\partial x}$
- direct inputs $C = \frac{\partial \dot{x}}{\partial u}$

Neuronal states $x_i(t)$

Hemodynamic model

$v_i(t)$ and $q_i(t)$

BOLD signal change equation

$$y = V_0 \left[k_1(1 - q) + k_2 \left(1 - \frac{q}{v} \right) + k_3(1 - v) \right] + e$$

with $k_1 = 4.3 \partial_0 E_0 TE$, $k_2 = \epsilon r_0 E_0 TE$, $k_3 = 1 - \epsilon$

Local hemodynamic state equations

$$\dot{s} = x - \kappa s - \gamma(f - 1)$$

vasodilatory signal and flow induction (rCBF)

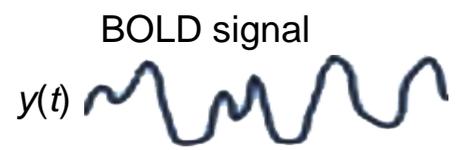
$$\dot{f} = s$$

Balloon model

$$\tau \dot{v} = f - v^{1/\alpha}$$

$$\tau \dot{q} = f E(f, E_0) / E_0 - v^{1/\alpha} q / v$$

Changes in volume (v) and dHb (q)



Bayesian system identification

Neural dynamics

$$\frac{dx}{dt} = f(x, u, \theta)$$

Observer function

$$y = g(x, \theta) + \varepsilon$$

$$p(y | \theta, m) = N(g(\theta), \Sigma(\theta))$$

$$p(\theta, m) = N(\mu_\theta, \Sigma_\theta)$$

Inference on model structure

$$p(y | m) = \int p(y | \theta, m) p(\theta) d\theta$$

Inference on parameters

$$p(\theta | y, m) = \frac{p(y | \theta, m) p(\theta, m)}{p(y | m)}$$

$u(t)$



Design experimental inputs

Define likelihood model

Specify priors

Invert model

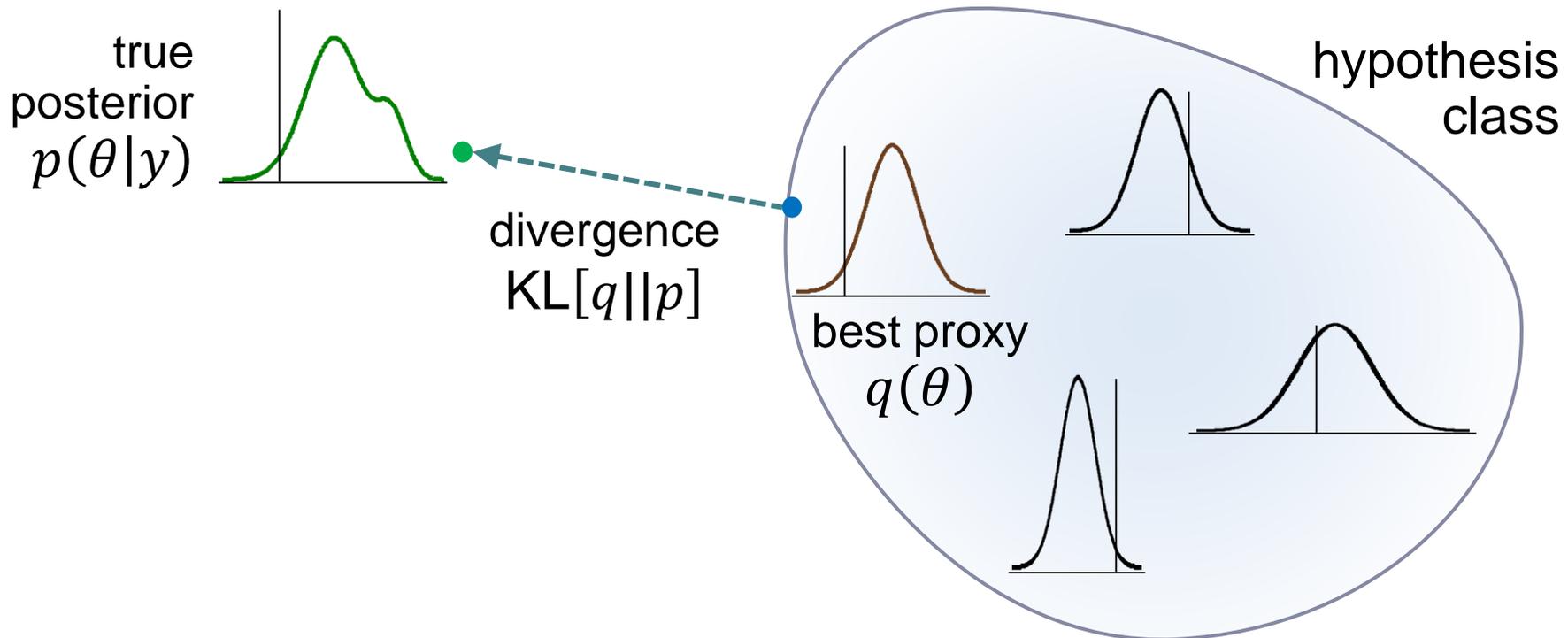
Make inferences



Variational Bayes (VB)

Idea: find an approximate density $q(\theta)$ that is maximally similar to the true posterior $p(\theta|y)$.

This is often done by assuming a particular form for q (fixed form VB) and then optimizing its sufficient statistics.



Variational Bayes

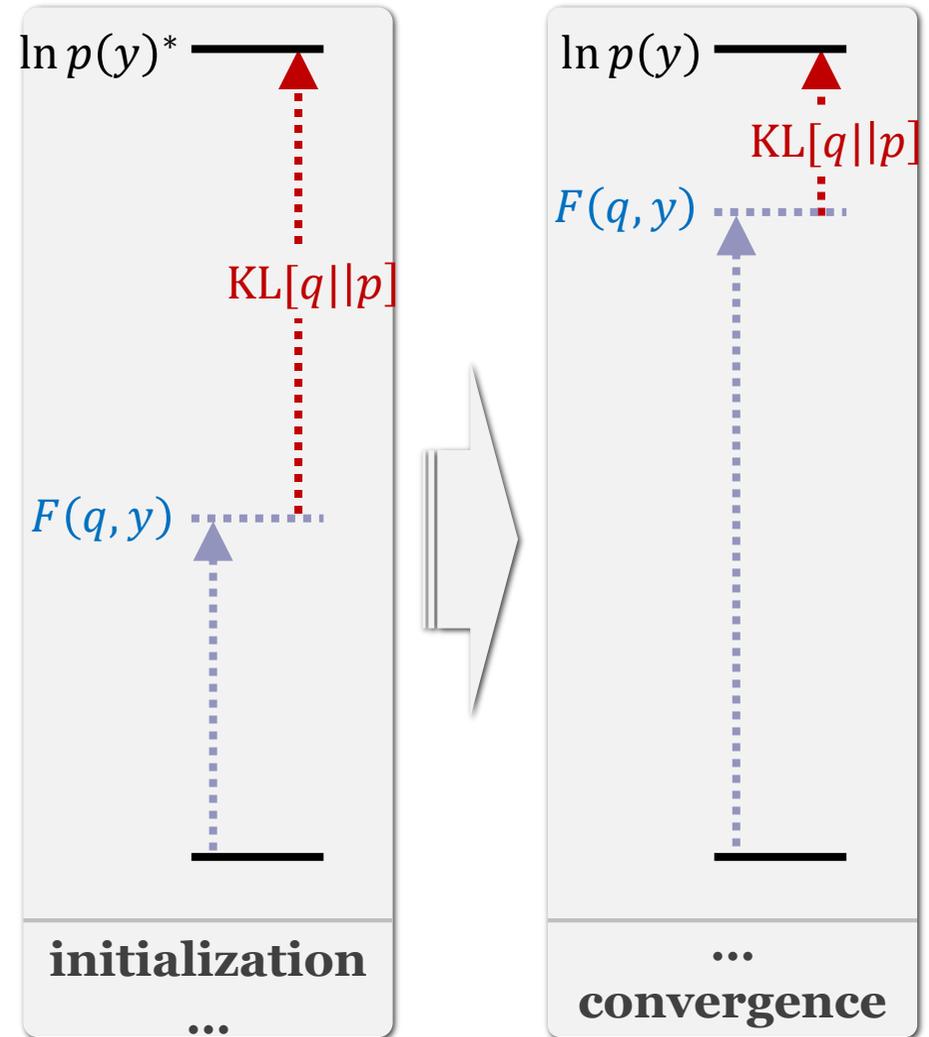
$$\ln p(y) = \underbrace{\text{KL}[q||p]}_{\substack{\text{divergence} \\ \geq 0 \\ \text{(unknown)}}} + \underbrace{F(q, y)}_{\substack{\text{neg. free} \\ \text{energy} \\ \text{(easy to evaluate} \\ \text{for a given } q\text{)}}}$$

$F(q, y)$ is a functional wrt. the approximate posterior $q(\theta)$.

Maximizing $F(q, y)$ is equivalent to:

- minimizing $\text{KL}[q||p]$
- tightening $F(q, y)$ as a lower bound to the log model evidence

When $F(q, y)$ is maximized, $q(\theta)$ is our best estimate of the posterior.



Mean field assumption

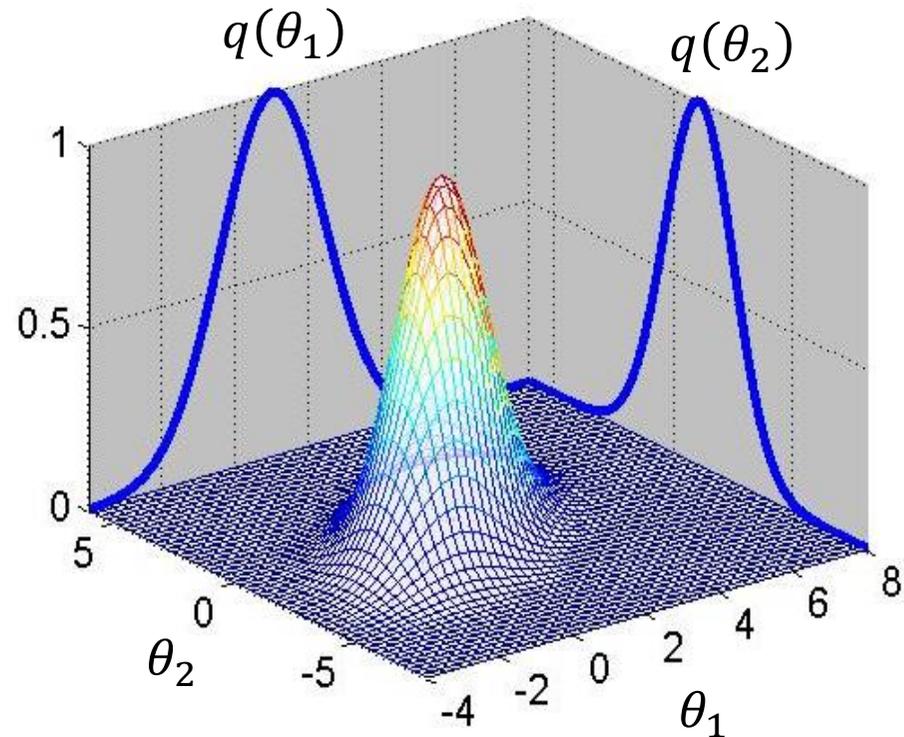
Factorize the approximate posterior $q(\theta)$ into independent partitions:

$$q(\theta) = \prod_i q_i(\theta_i)$$

where $q_i(\theta_i)$ is the approximate posterior for the i^{th} subset of parameters.

For example, split parameters and hyperparameters:

$$p(\theta, \lambda | y) \approx q(\theta, \lambda) = q(\theta)q(\lambda)$$



VB in a nutshell (mean-field approximation)

- ➊ Neg. free-energy approx. to model evidence.

$$\ln p(y|m) = F + KL[q(\theta, \lambda), p(\theta, \lambda | y)]$$

$$F = \langle \ln p(y, \theta, \lambda) \rangle_q - KL[q(\theta, \lambda), p(\theta, \lambda | m)]$$

- ➋ Mean field approx.

$$p(\theta, \lambda | y) \approx q(\theta, \lambda) = q(\theta)q(\lambda)$$

- ➌ Maximise neg. free energy wrt. q = minimise divergence, by maximising variational energies

$$q(\theta) \propto \exp(I_\theta) = \exp\left[\langle \ln p(y, \theta, \lambda) \rangle_{q(\lambda)}\right]$$

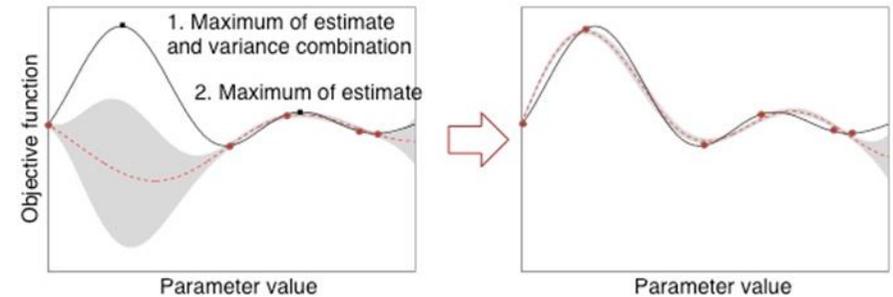
$$q(\lambda) \propto \exp(I_\lambda) = \exp\left[\langle \ln p(y, \theta, \lambda) \rangle_{q(\theta)}\right]$$

- ➍ Iterative updating of sufficient statistics of approx. posteriors by gradient ascent.

DCM: methodological developments

- **Local extrema → global optimisation schemes for model inversion**

- **MCMC**
(Gupta et al. 2015, NeuroImage)
- **Gaussian processes**
(Lomakina et al. 2015, NeuroImage)

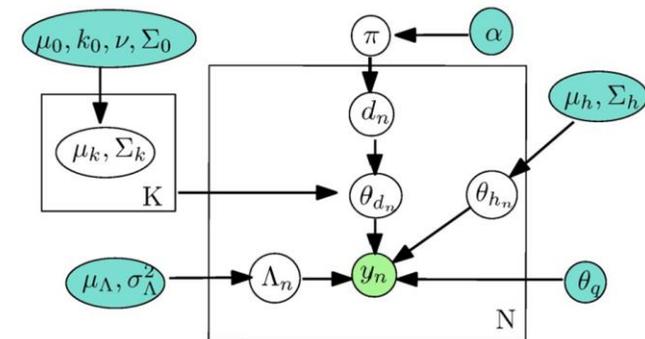


- **Sampling-based estimates of model evidence**

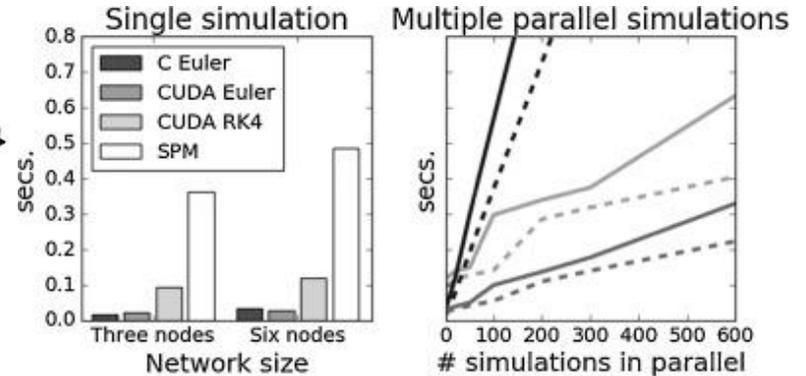
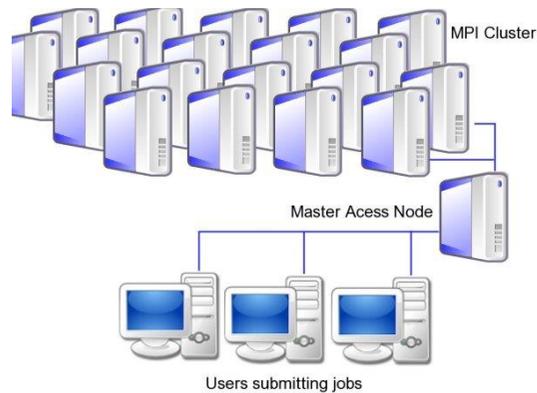
- Aponte et al. 2015, J. Neurosci. Meth.
- Raman et al., in preparation

- **Choice of priors → empirical Bayes**

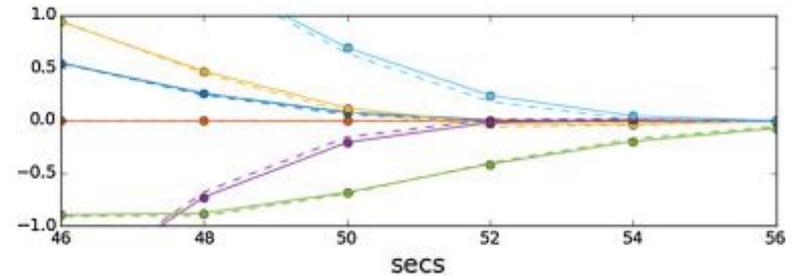
- Friston et al., submitted
- Raman et al., submitted



mpdcm: massively parallel DCM



$$\left. \begin{aligned} \dot{x} &= f(x, u_1, \theta_1) \\ \dot{x} &= f(x, u_2, \theta_2) \\ &\vdots \\ \dot{x} &= f(x, u_1, \theta_1) \end{aligned} \right\} \text{mpdcm_integrate(dcms)} \left\{ \begin{aligned} y_1 \\ y_2 \\ \vdots \\ y_3 \end{aligned} \right.$$



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The evolution of DCM in SPM

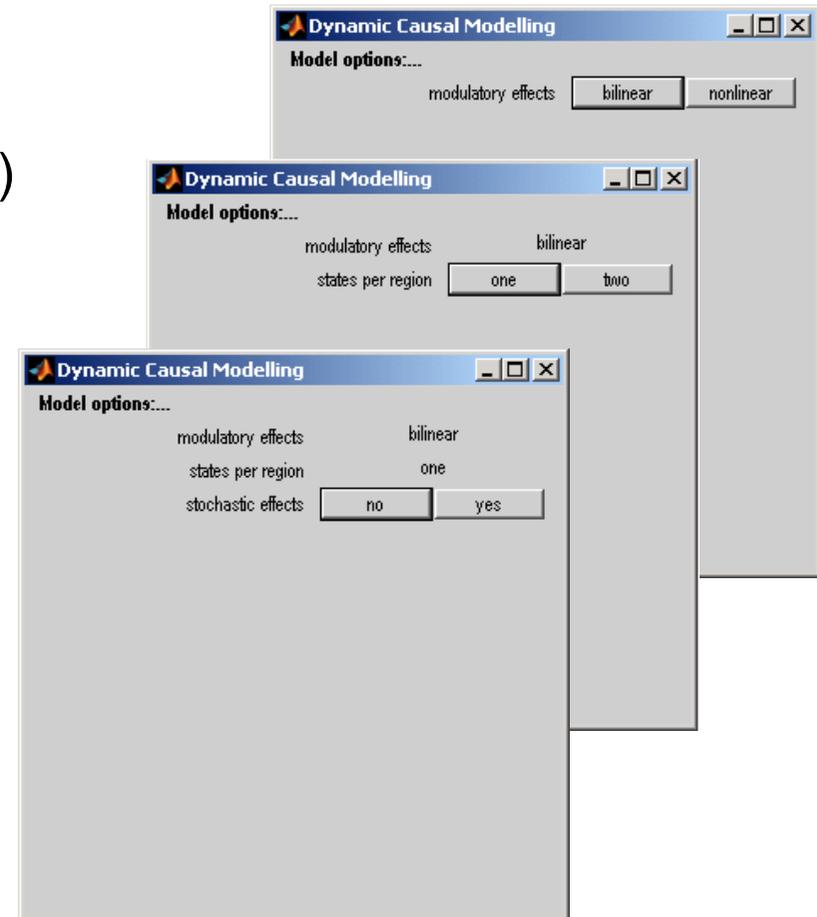
- DCM is not one specific model, but a framework for Bayesian inversion of dynamic system models
- The implementation in SPM has been evolving over time, e.g.
 - improvements of numerical routines (e.g., optimisation scheme)
 - change in priors to cover new variants (e.g., stochastic DCMs)
 - changes of hemodynamic model



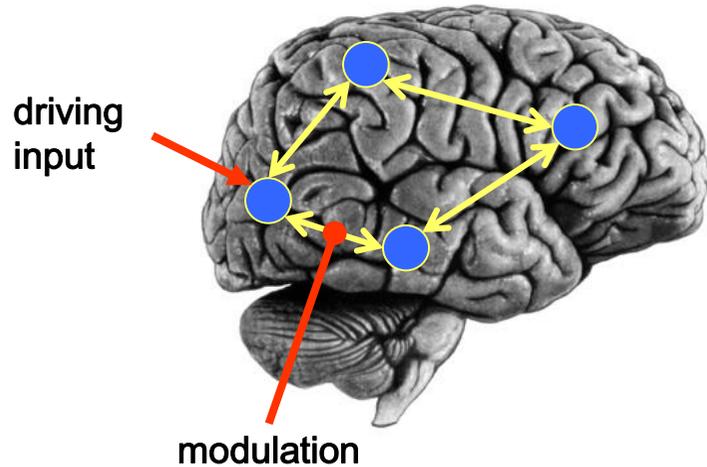
To enable replication of your results, you should ideally state which SPM version (release number) you are using when publishing papers.

Factorial structure of model specification

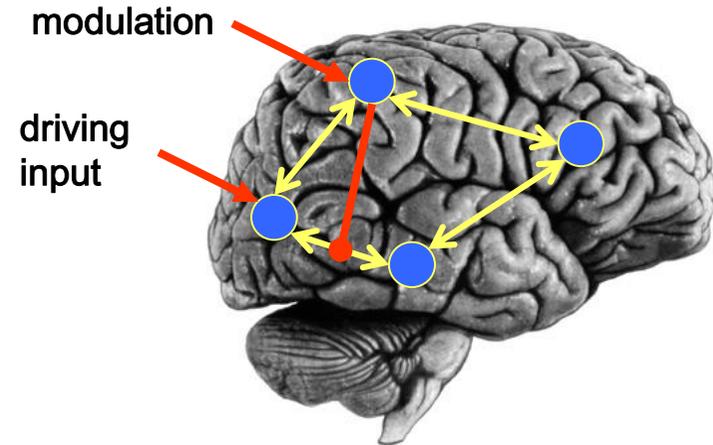
- Three dimensions of model specification:
 - bilinear vs. nonlinear
 - single-state vs. two-state (per region)
 - deterministic vs. stochastic



bilinear DCM



non-linear DCM



Two-dimensional Taylor series (around $x_0=0$, $u_0=0$):

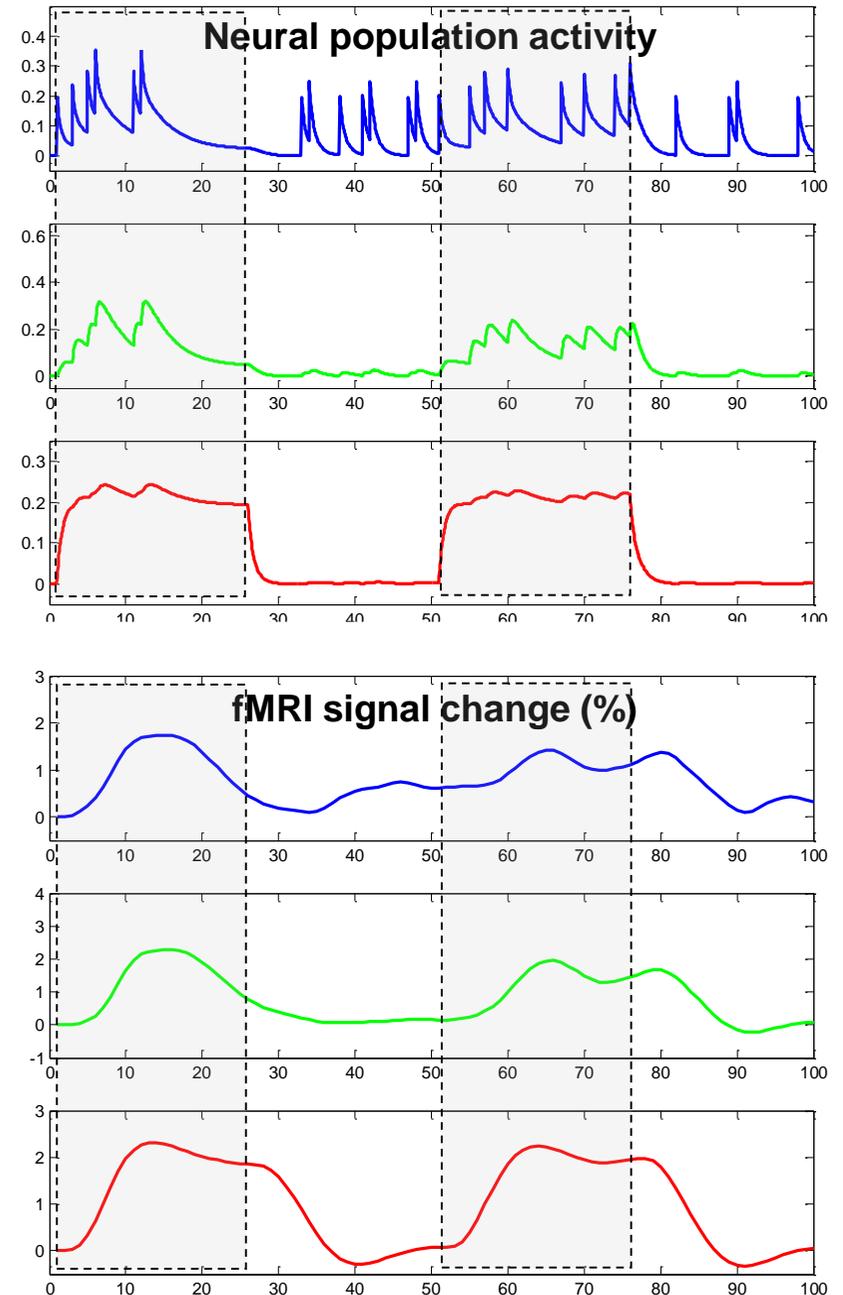
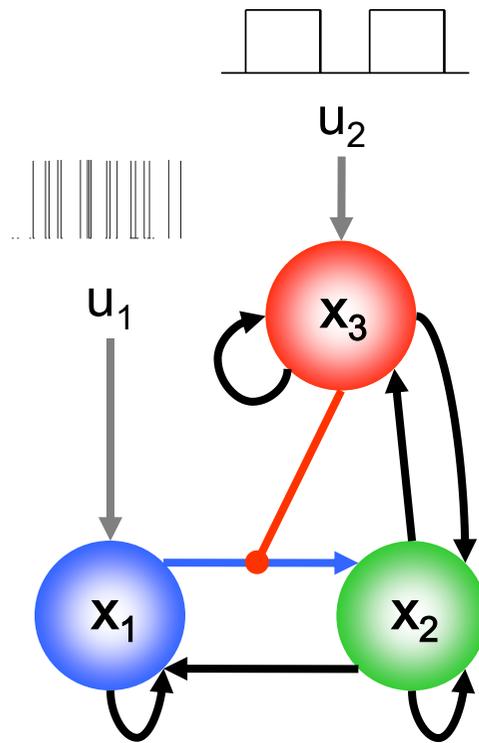
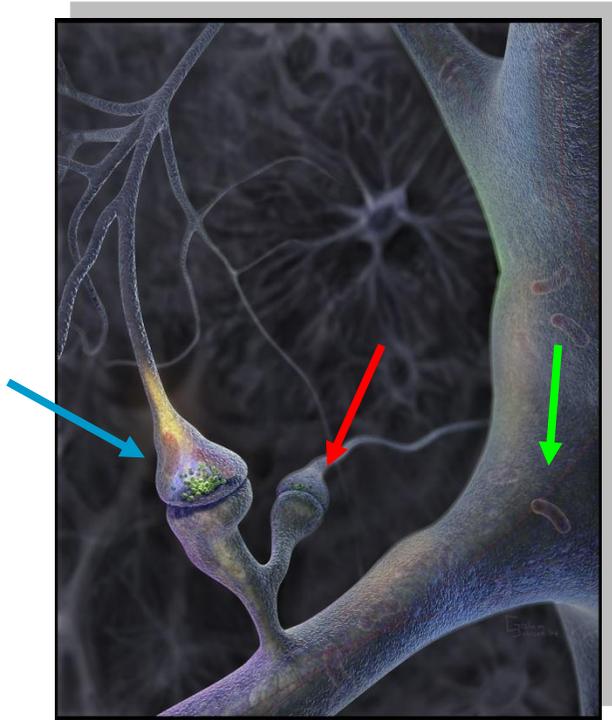
$$\frac{dx}{dt} = f(x, u) \approx f(x_0, 0) + \frac{\partial f}{\partial x} x + \frac{\partial f}{\partial u} u + \frac{\partial^2 f}{\partial x \partial u} ux + \frac{\partial^2 f}{\partial x^2} \frac{x^2}{2} + \dots$$

Bilinear state equation:

$$\frac{dx}{dt} = \left(A + \sum_{i=1}^m u_i B^{(i)} \right) x + Cu$$

Nonlinear state equation:

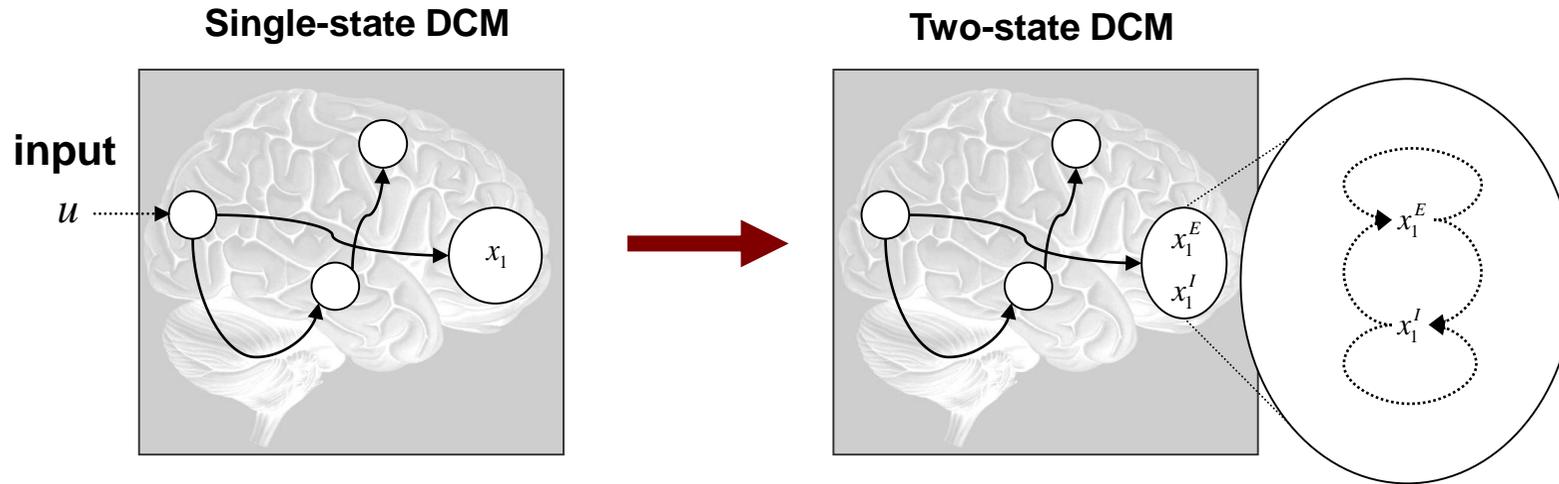
$$\frac{dx}{dt} = \left(A + \sum_{i=1}^m u_i B^{(i)} + \sum_{j=1}^n x_j D^{(j)} \right) x + Cu$$



Nonlinear Dynamic Causal Model for fMRI

$$\frac{dx}{dt} = \left(A + \sum_{i=1}^m u_i B^{(i)} + \sum_{j=1}^n x_j D^{(j)} \right) x + Cu$$

Two-state DCM



$$\dot{x} = \mathfrak{S}x + Cu$$

$$\mathfrak{S}_{ij} = A_{ij} + uB_{ij}$$

$$\mathfrak{S} = \begin{bmatrix} \mathfrak{S}_{11} & \cdots & \mathfrak{S}_{1N} \\ \vdots & \ddots & \vdots \\ \mathfrak{S}_{N1} & \cdots & \mathfrak{S}_{NN} \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix}$$

$$\dot{x} = \mathfrak{S}x + Cu$$

$$\mathfrak{S}_{ij}^{\bullet\bullet} = \mu_{ij}^{\bullet\bullet} \exp(A_{ij}^{\bullet\bullet} + uB_{ij}^{\bullet\bullet})$$

$$\mathfrak{S} = \begin{bmatrix} \mathfrak{S}_{11}^{EE} & \mathfrak{S}_{11}^{EI} & \cdots & \mathfrak{S}_{1N}^{EE} & 0 \\ \mathfrak{S}_{11}^{IE} & \mathfrak{S}_{11}^{II} & & 0 & 0 \\ \vdots & & \ddots & & \vdots \\ \mathfrak{S}_{N1}^{EE} & 0 & & \mathfrak{S}_{NN}^{EE} & \mathfrak{S}_{NN}^{EE} \\ 0 & 0 & \cdots & \mathfrak{S}_{NN}^{IE} & \mathfrak{S}_{NN}^{II} \end{bmatrix} \quad x = \begin{bmatrix} x_1^E \\ x_1^I \\ \vdots \\ x_N^E \\ x_N^I \end{bmatrix}$$

**Extrinsic
(between-region)
coupling**

**Intrinsic
(within-region)
coupling**

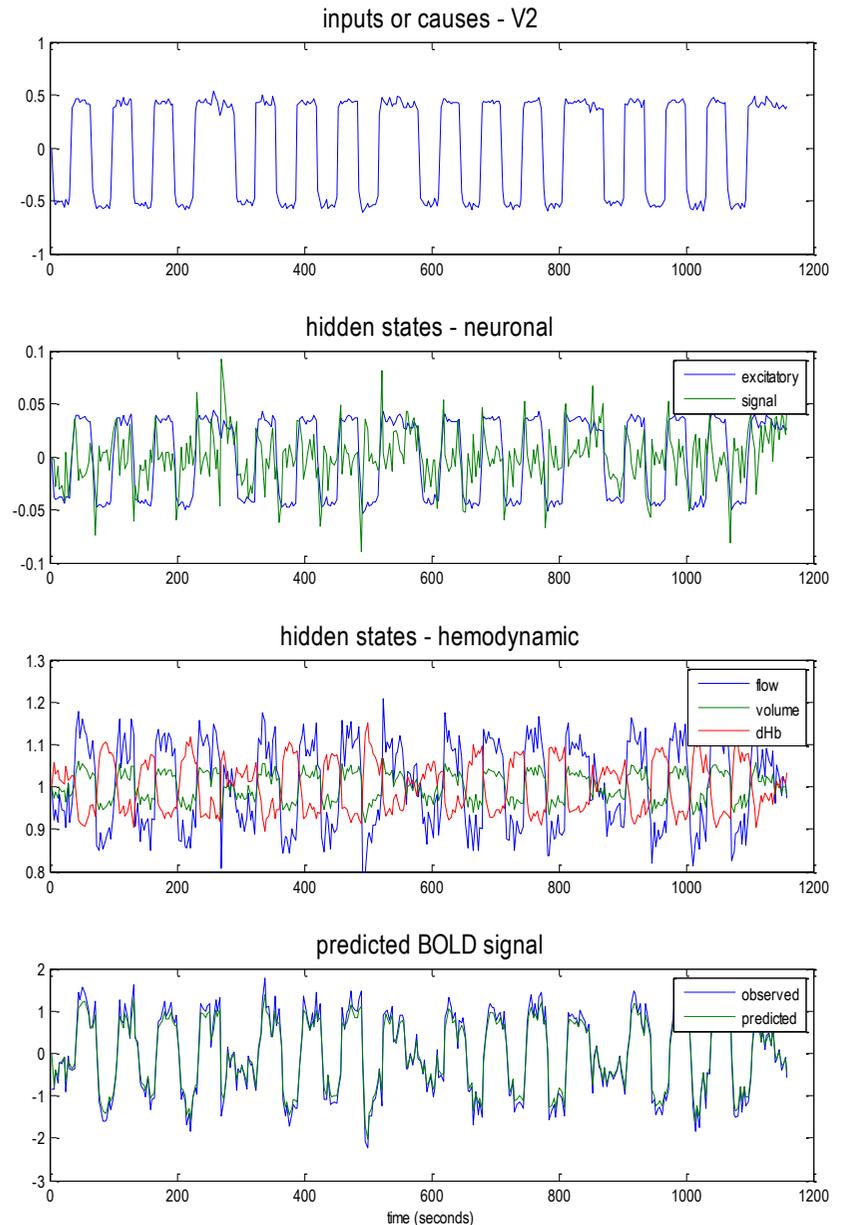
Stochastic DCM

$$\frac{dx}{dt} = (A + \sum_j u_j B^{(j)})x + Cv + \omega^{(x)}$$

$$v = u + \omega^{(v)}$$

- all states are represented in generalised coordinates of motion
- random state fluctuations $w^{(x)}$ account for endogenous fluctuations, have unknown precision and smoothness → two hyperparameters
- fluctuations $w^{(v)}$ induce uncertainty about how inputs influence neuronal activity
- can be fitted to resting state data

Estimates of hidden causes and states (Generalised filtering)



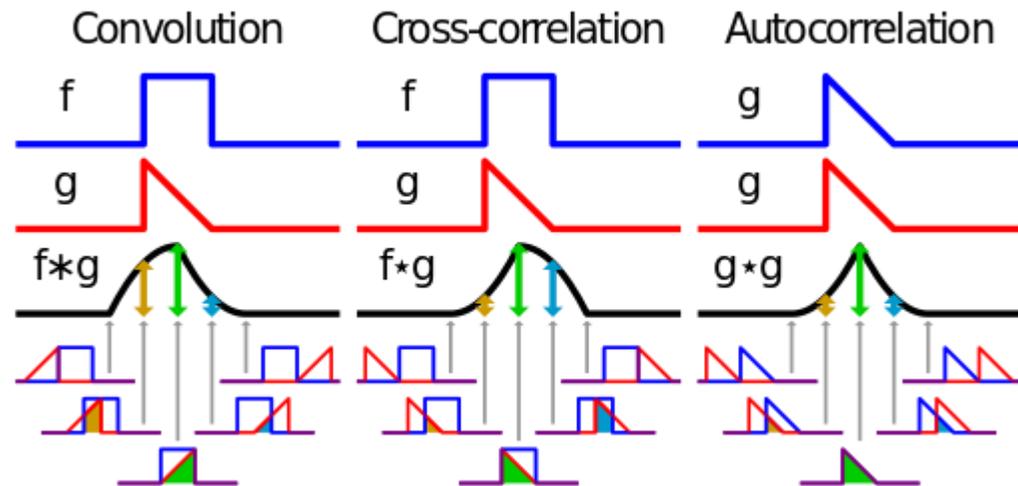
Spectral DCM

- deterministic model that generates predicted cross-spectra in a distributed neuronal network or graph
- finds the effective connectivity among hidden neuronal states that best explains the observed functional connectivity among hemodynamic responses
- advantage:
 - replaces an optimisation problem wrt. stochastic differential equations with a deterministic approach from linear systems theory
→ computationally very efficient
- disadvantages:
 - assumes stationarity

Cross-correlation & convolution

- cross-correlation = measure of similarity of two waveforms as a function of the time-lag of one relative to the other
 - slide two functions over each other and measure overlaps at all lags
- related to the pdf of the difference between two random variables
 - a general measure of similarity between two time series

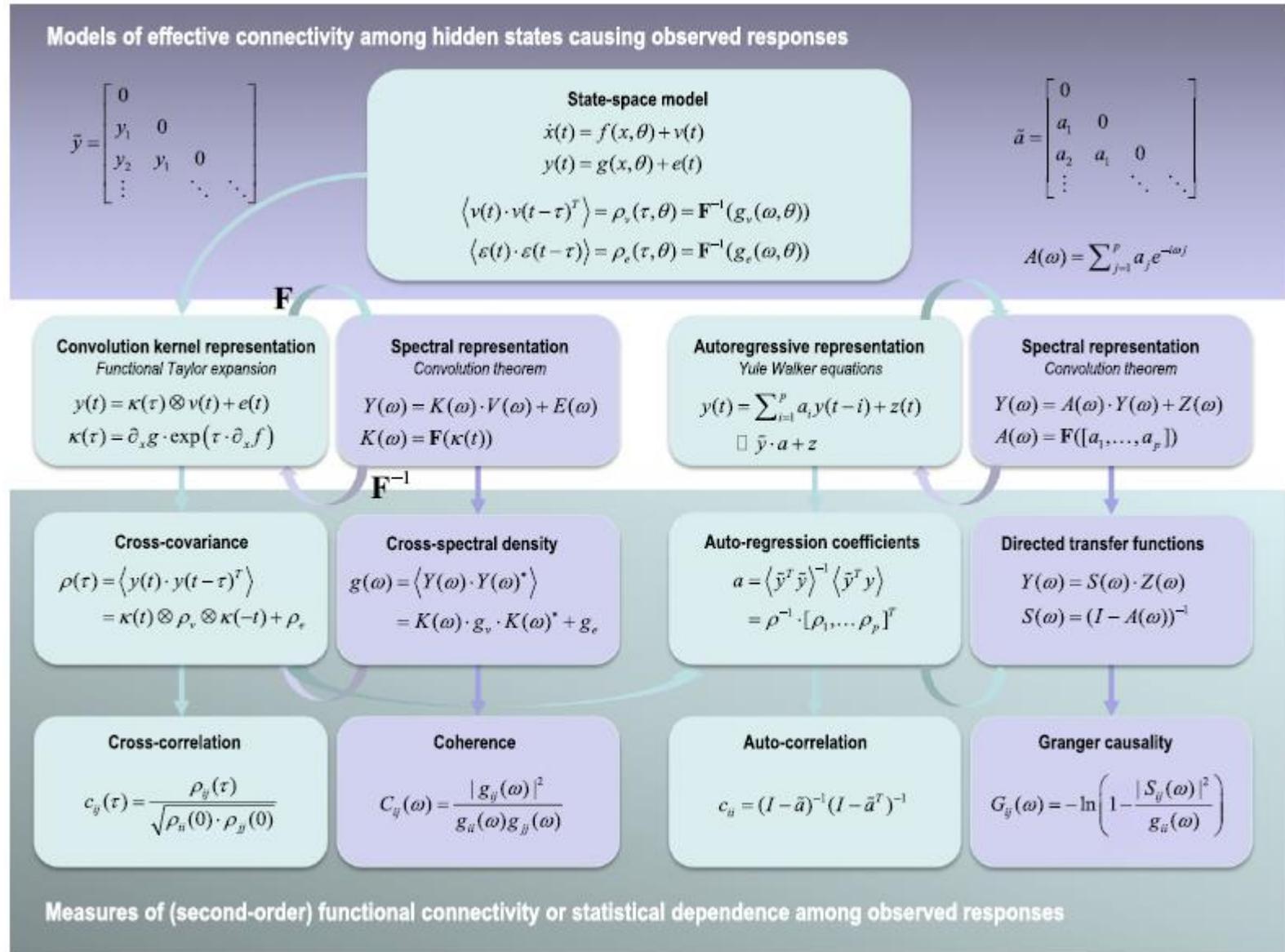
$$(f \star g)(\tau) \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} f^*(t) g(t + \tau) dt$$



Source: *Wikipedia*

cross-spectra
= Fourier transform of cross-correlation

cross-correlation
= generalized form of correlation (at zero lag, this is the conventional measure of functional connectivity)



**“All models are wrong,
but some are useful.”**

George E.P. Box (1919-2013)



Hierarchical strategy for model validation

1 in silico

numerical analysis &
simulation studies

2 humans

cognitive experiments

3 animals &
humans

experimentally controlled
system perturbations

4 patients

clinical utility

**For DCM: >15 published
validation studies
(incl. 6 animal studies):**

- infers site of seizure origin (David et al. 2008)
- infers primary recipient of vagal nerve stimulation (Reyt et al. 2010)
- infers synaptic changes as predicted by microdialysis (Moran et al. 2008)
- infers fear conditioning induced plasticity in amygdala (Moran et al. 2009)
- tracks anaesthesia levels (Moran et al. 2011)
- predicts sensory stimulation (Brodersen et al. 2010)

Overview

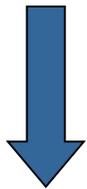
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Generative models & model selection

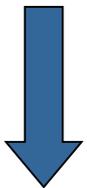
- any DCM = a particular generative model of how the data (may) have been caused
- generative modelling: comparing competing hypotheses about the mechanisms underlying observed data
 - a priori definition of hypothesis set (model space) is crucial
 - determine the most plausible hypothesis (model), given the data
- model selection \neq model validation!
 - model validation requires external criteria (external to the measured data)

Model comparison and selection

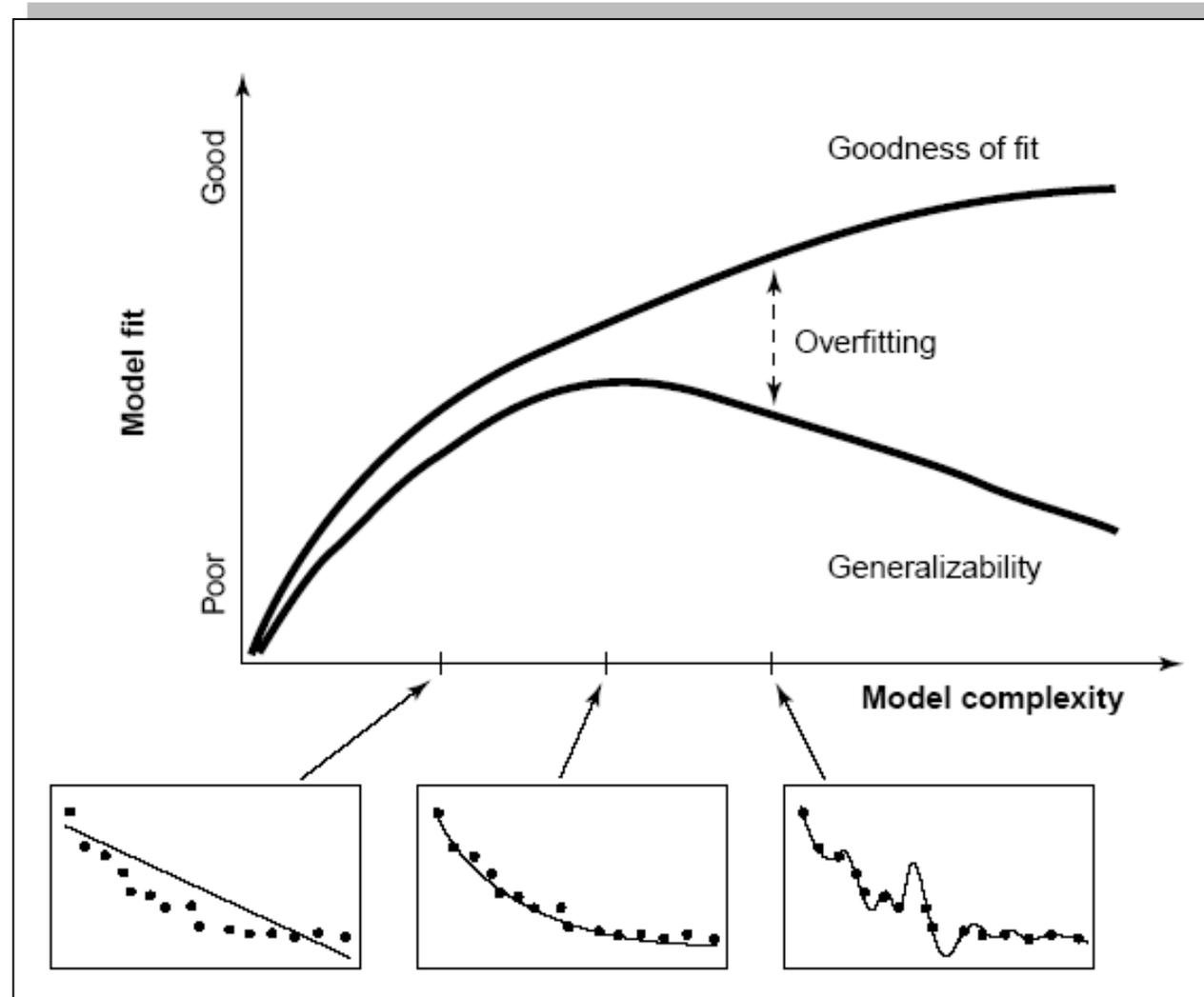
Given competing hypotheses on structure & functional mechanisms of a system, which model is the best?



Which model represents the best balance between model fit and model complexity?



For which model m does $p(y|m)$ become maximal?



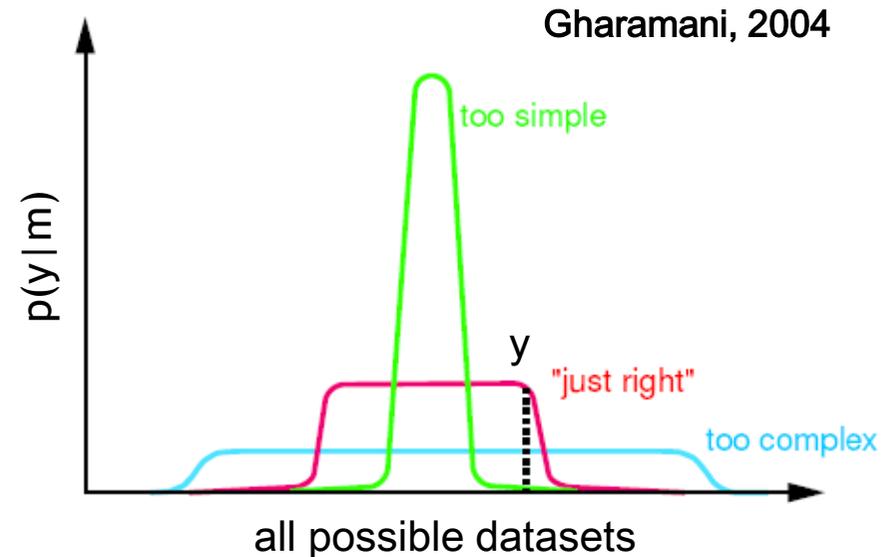
Bayesian model selection (BMS)

Model evidence (marginal likelihood):

$$p(y | m) = \int p(y | \theta, m) p(\theta | m) d\theta$$

➔ accounts for both accuracy and complexity of the model

➔ “If I randomly sampled from my prior and plugged the resulting value into the likelihood function, how close would the predicted data be – on average – to my observed data?”



Various approximations, e.g.:

- negative free energy, AIC, BIC

Model space (hypothesis set) M

Model space M is defined by prior on models.

Usual choice: flat prior over a small set of models.

$$p(m) = \begin{cases} 1/|M| & \text{if } m \in M \\ 0 & \text{if } m \notin M \end{cases}$$

In this case, the posterior probability of model i is:

$$p(m_i | y) = \frac{p(y | m_i) p(m_i)}{\sum_{j=1}^{|M|} p(y | m_j) p(m_j)} = \frac{p(y | m_i)}{\sum_{j=1}^{|M|} p(y | m_j)}$$

Approximations to the model evidence in DCM

Logarithm is a
monotonic function



Maximizing log model evidence
= Maximizing model evidence

Log model evidence = balance between fit and complexity

$$\begin{aligned}\log p(y | m) &= \textit{accuracy}(m) - \textit{complexity}(m) \\ &= \log p(y | \theta, m) - \textit{complexity}(m)\end{aligned}$$

Akaike Information Criterion:

$$AIC = \log p(y | \theta, m) - p$$

No. of
parameters

No. of
data points

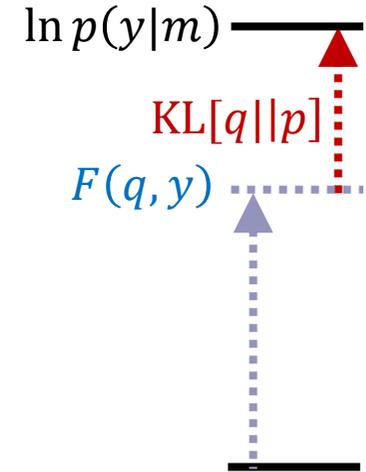
Bayesian Information Criterion:

$$BIC = \log p(y | \theta, m) - \frac{p}{2} \log N$$

The (negative) free energy approximation F

F is a lower bound on the log model evidence, where the bound is determined by the KL divergence between an approximate posterior q and the true posterior::

$$\log p(y | m) = F + KL[q(\theta), p(\theta | y, m)]$$



Like AIC/BIC, F is an accuracy/complexity tradeoff:

$$F = \underbrace{\langle \log p(y | \theta, m) \rangle}_{\text{accuracy}} - \underbrace{KL[q(\theta), p(\theta | m)]}_{\text{complexity}}$$

The complexity term in F

- In contrast to AIC & BIC, the complexity term of the negative free energy F accounts for parameter interdependencies.

$$\begin{aligned} & KL[q(\theta), p(\theta | m)] \\ &= \frac{1}{2} \ln |C_\theta| - \frac{1}{2} \ln |C_{\theta|y}| + \frac{1}{2} (\mu_{\theta|y} - \mu_\theta)^T C_\theta^{-1} (\mu_{\theta|y} - \mu_\theta) \end{aligned}$$

- determinant = measure of “volume” (space spanned by the eigenvectors of the matrix)
- The complexity term of F is higher
 - the more independent the prior parameters (\uparrow effective DFs)
 - the more dependent the posterior parameters
 - the more the posterior mean deviates from the prior mean

Bayes factors

To compare two models, we could just compare their log evidences.

But: the log evidence is just some number – not very intuitive!

A more intuitive interpretation of model comparisons is made possible by Bayes factors:

$$B_{12} = \frac{p(y | m_1)}{p(y | m_2)}$$

positive value, $[0; \infty[$

Kass & Raftery classification:

B_{12}	$p(m_1 y)$	Evidence
1 to 3	50-75%	weak
3 to 20	75-95%	positive
20 to 150	95-99%	strong
≥ 150	$\geq 99\%$	Very strong

Fixed effects BMS at group level

Group Bayes factor (GBF) for $1 \dots K$ subjects:

$$GBF_{ij} = \prod_k BF_{ij}^{(k)}$$

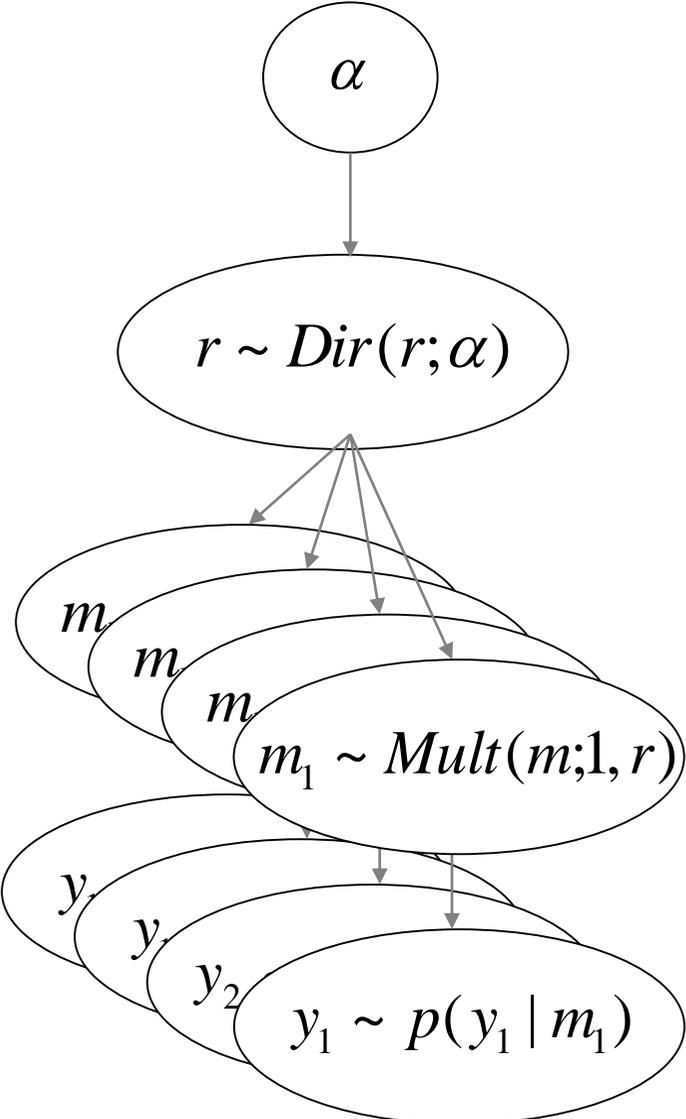
Average Bayes factor (ABF):

$$ABF_{ij} = \sqrt[K]{\prod_k BF_{ij}^{(k)}}$$

Problems:

- blind with regard to group heterogeneity
- sensitive to outliers

Random effects BMS for heterogeneous groups



Dirichlet parameters α
= “occurrences” of models in the population

Dirichlet distribution of model probabilities r

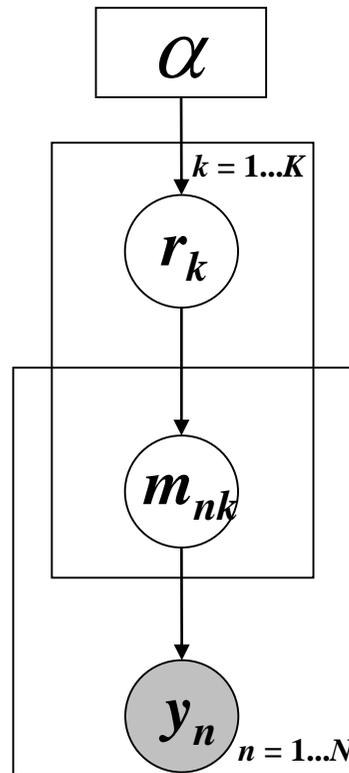
Multinomial distribution of model labels m

Measured data y

**Model inversion
by Variational
Bayes (VB) or
MCMC**

Stephan et al. 2009a, *NeuroImage*
Penny et al. 2010, *PLoS Comp. Biol.*

Random effects BMS for heterogeneous groups



Dirichlet parameters α
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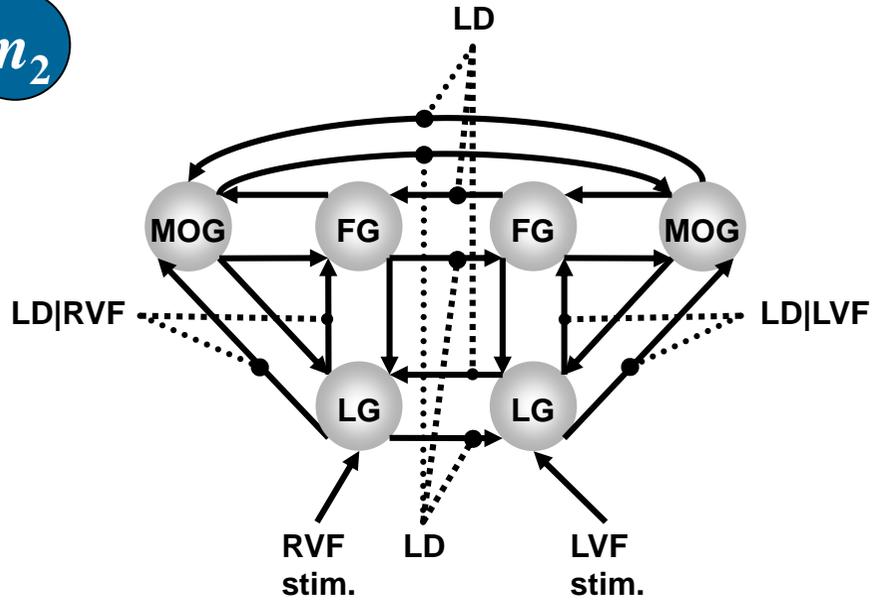
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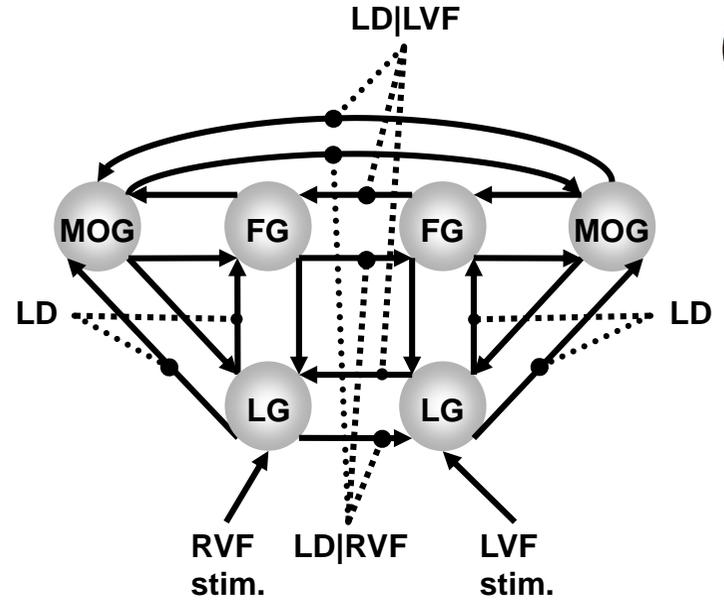
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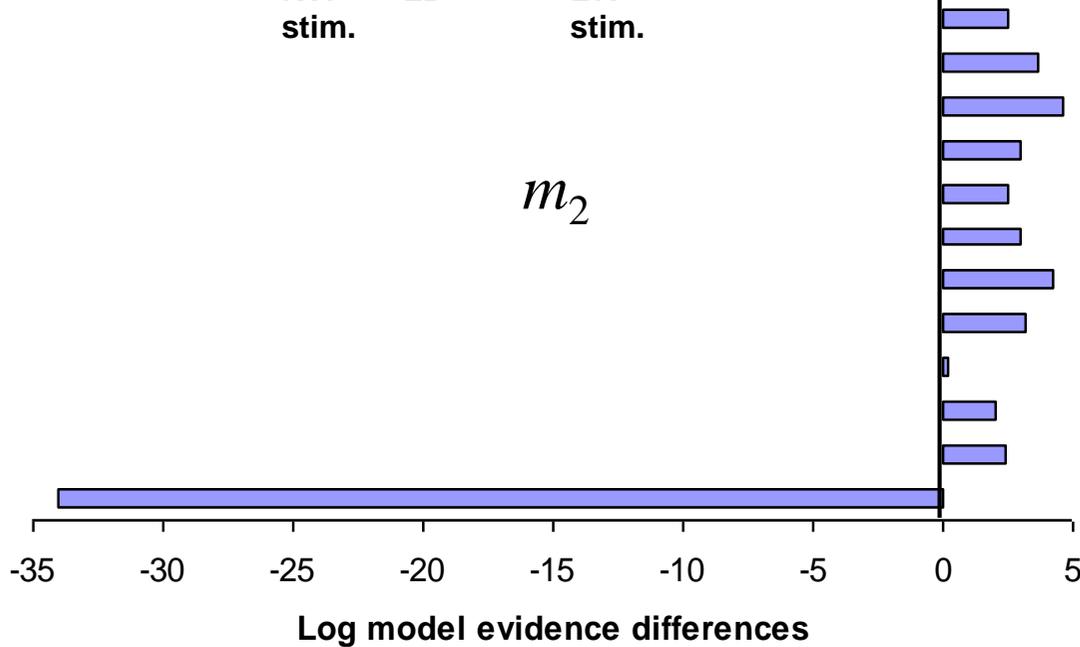
m_2



m_1

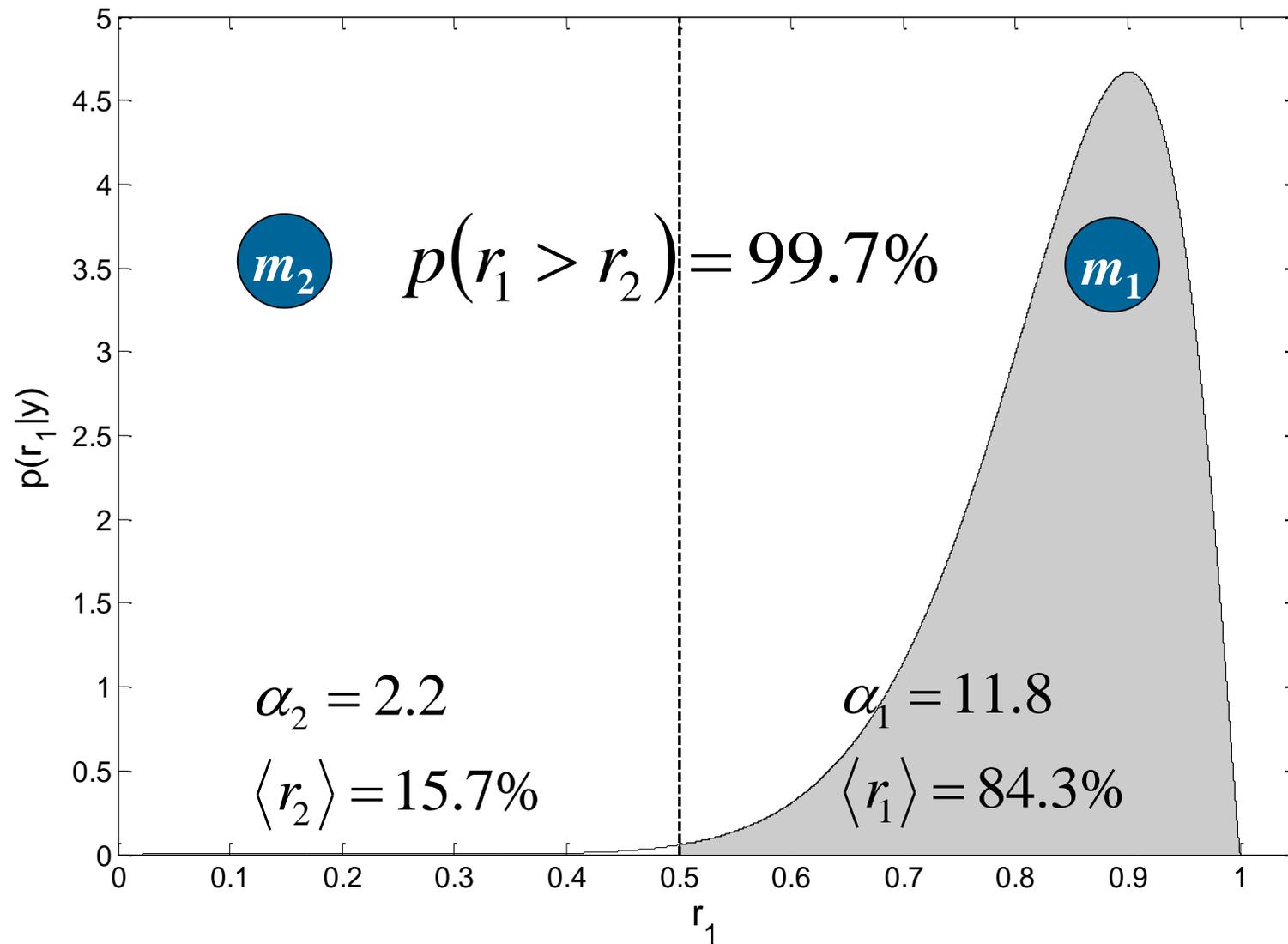


Subjects



m_1

Data: Stephan et al. 2003, *Science*
Models: Stephan et al. 2007, *J. Neurosci.*



How can we report the results of random effects BMS?

1. **Dirichlet parameter estimates**

α

2. **expected posterior probability** of obtaining the k -th model for any randomly selected subject

$$\langle r_k \rangle_q = \alpha_k / (\alpha_1 + \dots + \alpha_K)$$

3. **exceedance probability** that a particular model k is more likely than any other model (of the K models tested), given the group data

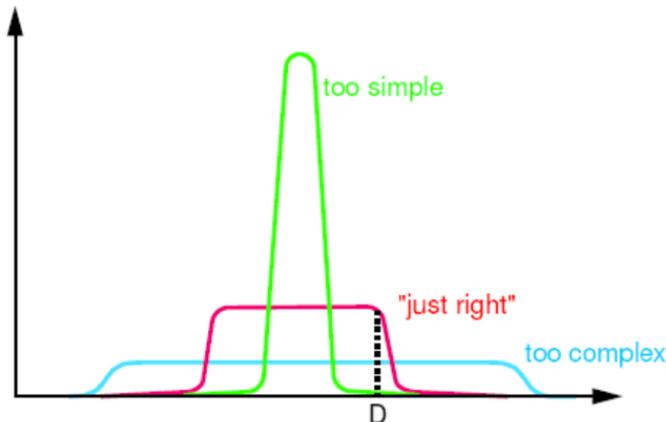
$$\exists k \in \{1 \dots K\}, \forall j \in \{1 \dots K \mid j \neq k\} :$$

$$\varphi_k = p(r_k > r_j \mid y; \alpha)$$

4. **protected exceedance probability:**
see below

Overfitting at the level of models

- \uparrow #models \Rightarrow \uparrow risk of overfitting
- solutions:
 - regularisation: definition of model space = choosing priors $p(m)$
 - family-level BMS
 - Bayesian model averaging (BMA)



posterior model probability:

$$p(m | y) = \frac{p(y | m) p(m)}{\sum_m p(y | m) p(m)}$$

BMA:

$$p(\theta | y) = \sum_m p(\theta | y, m) p(m | y)$$

Model space partitioning or: Comparing model families

- partitioning model space into K subsets or families:

$$M = \{f_1, \dots, f_K\}$$

- pooling information over all models in these subsets allows one to compute the probability of a model family, given the data

$$p(f_k)$$

- effectively removes uncertainty about any aspect of model structure, other than the attribute of interest (which defines the partition)

Family-level inference: fixed effects

- We wish to have a uniform prior at the family level:
- This is related to the model level via the sum of the priors on models:
- Hence the uniform prior at the family level is:
- The probability of each family is then obtained by summing the posterior probabilities of the models it includes:

$$p(f_k) = \frac{1}{K}$$

$$p(f_k) = \sum_{m \in f_k} p(m)$$

$$\forall m \in f_k : p(m) = \frac{1}{K |f_k|}$$

$$p(f_k | y_{1..N}) = \sum_{m \in f_k} p(m | y_{1..N})$$

Family-level inference: random effects

- The frequency of a family in the population is given by:
- In RFX-BMS, this follows a Dirichlet distribution, with a uniform prior on the parameters α (see above).
- A uniform prior over family probabilities can be obtained by setting:

$$s_k = \sum_{m \in f_k} r_m$$

$$p(s) = \text{Dir}(\alpha)$$

$$\forall m \in f_k : \alpha_{\text{prior}}(m) = \frac{1}{|f_k|}$$

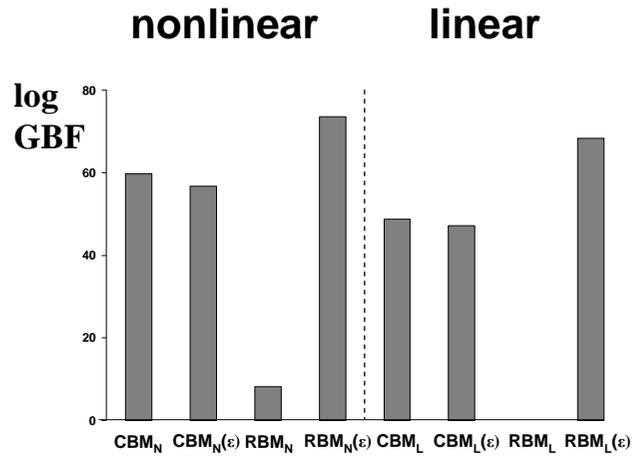
Family-level inference: random effects – a special case

- When the families are of equal size, one can simply sum the posterior model probabilities within families by exploiting the agglomerative property of the Dirichlet distribution:

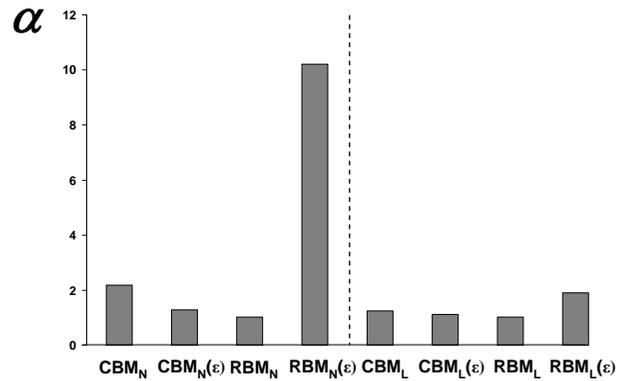
$$\begin{aligned} (r_1, r_2, \dots, r_K) &\sim \text{Dir}(\alpha_1, \alpha_2, \dots, \alpha_K) \\ \Rightarrow r_1^* &= \sum_{k \in N_1} r_k, r_2^* = \sum_{k \in N_2} r_k, \dots, r_J^* = \sum_{k \in N_J} r_k \\ &\sim \text{Dir} \left(\alpha_1^* = \sum_{k \in N_1} \alpha_k, \alpha_2^* = \sum_{k \in N_2} \alpha_k, \dots, \alpha_J^* = \sum_{k \in N_J} \alpha_k \right) \end{aligned}$$

Model space partitioning: comparing model families

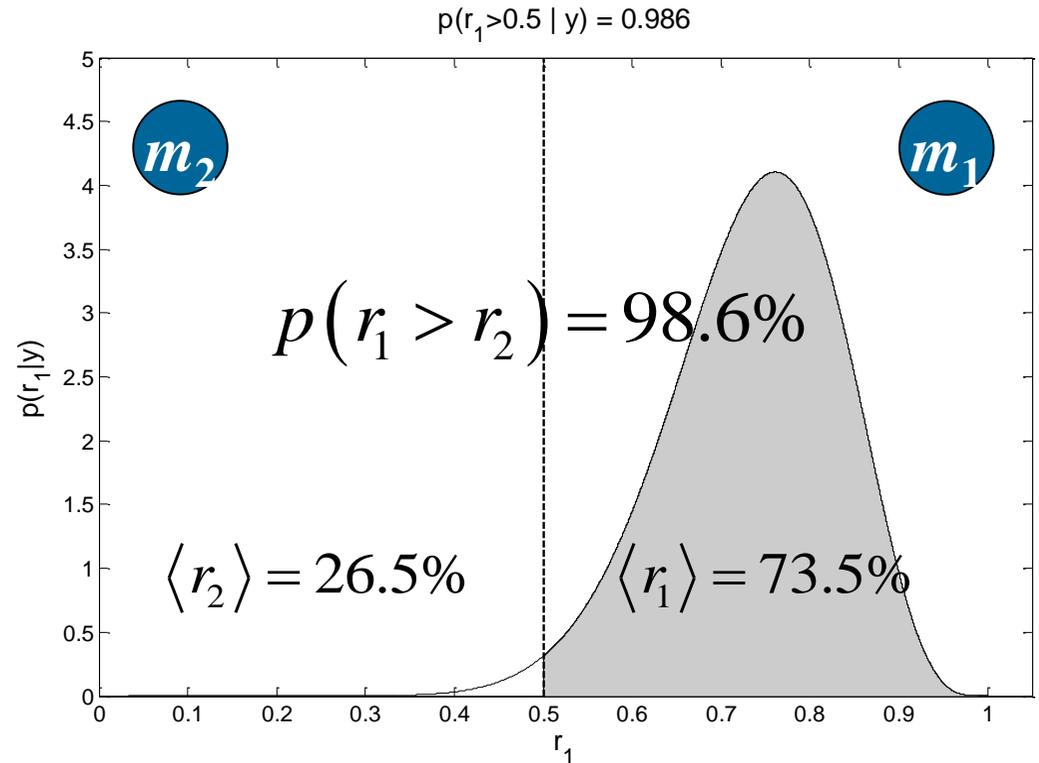
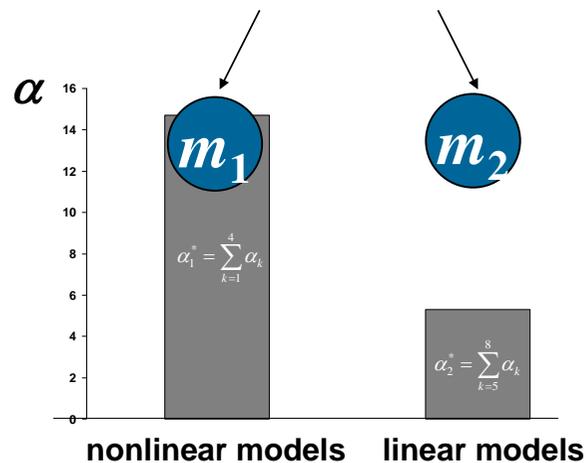
FFX



RFX



Model
space
partitioning



Bayesian Model Averaging (BMA)

- abandons dependence of parameter inference on a single model and takes into account model uncertainty
- represents a particularly useful alternative
 - when none of the models (or model subspaces) considered clearly outperforms all others
 - when comparing groups for which the optimal model differs

single-subject BMA:

$$p(\theta | y) \\ = \sum_m p(\theta | y, m) p(m | y)$$

group-level BMA:

$$p(\theta_n | y_{1..N}) \\ = \sum_m p(\theta_n | y_n, m) p(m | y_{1..N})$$

NB: $p(m|y_{1..N})$ can be obtained by either FFX or RFX BMS

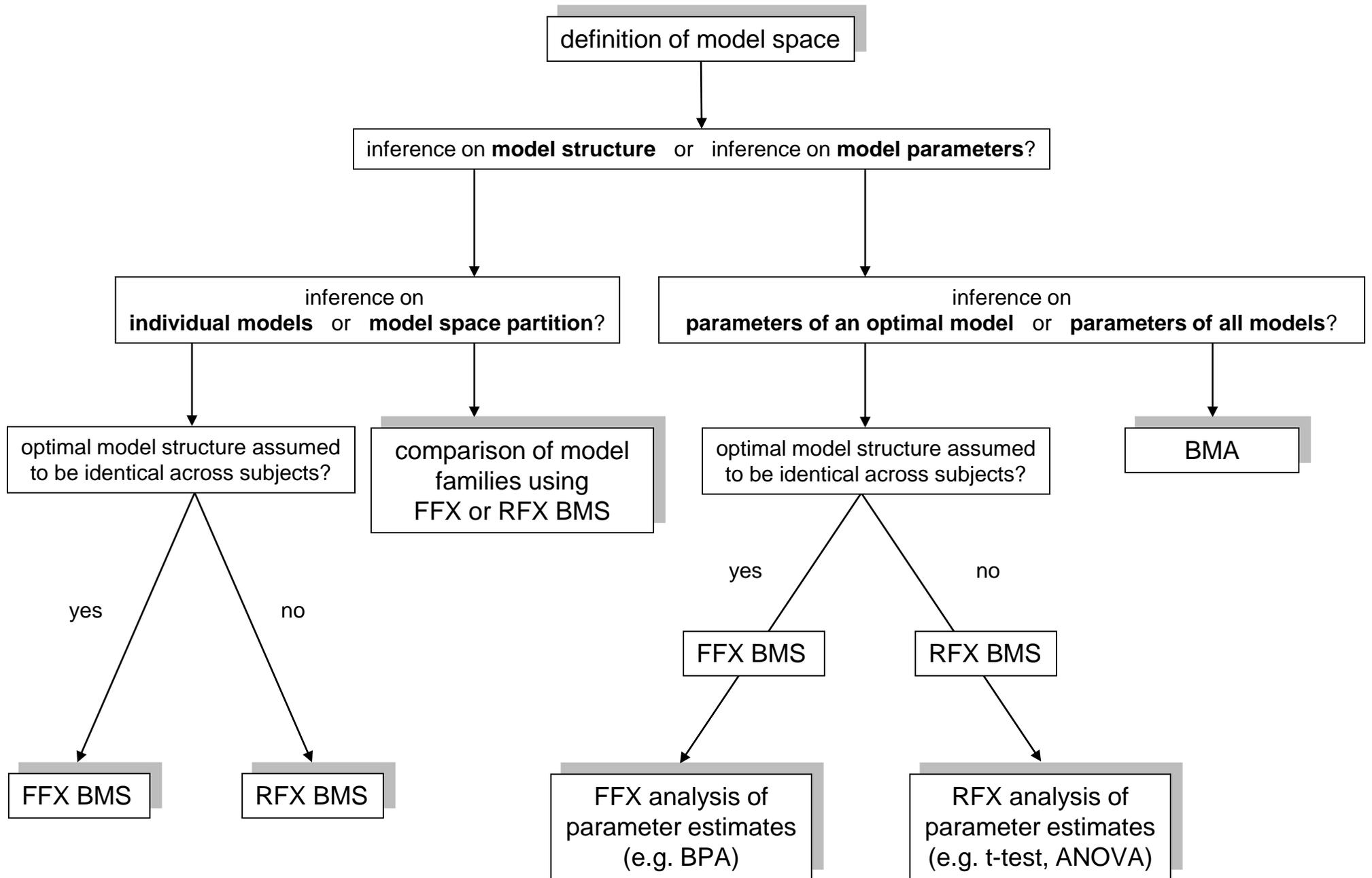
Protected exceedance probability: Using BMA to protect against chance findings

- EPs express our confidence that the posterior probabilities of models are different – under the hypothesis H_1 that models differ in probability: $r_k \neq 1/K$
- does not account for possibility "null hypothesis" H_0 : $r_k = 1/K$
- **Bayesian omnibus risk (BOR)** of wrongly accepting H_1 over H_0 :

$$P_0 = \frac{1}{1 + \frac{p(m|H_1)}{p(m|H_0)}}.$$

- **protected EP**: Bayesian model averaging over H_0 and H_1 :

$$\begin{aligned}\tilde{\varphi}_k &= P(r_k \geq r_{k' \neq k} | y) \\ &= P(r_k \geq r_{k' \neq k} | y, H_1)P(H_1 | y) + P(r_k \geq r_{k' \neq k} | y, H_0)P(H_0 | y) \\ &= \varphi_k(1 - P_0) + \frac{1}{K}P_0\end{aligned}$$



Two empirical example applications

doi:10.1093/brain/awv261 BRAIN 2015: Page 1 of 13 | 1

BRAIN
A JOURNAL OF NEUROLOGY

Network dysfunction of emotional and cognitive processes in those at genetic risk of bipolar disorder

Michael Breakspear,^{1,2,3,*} Gloria Roberts,^{3,4,*} Melissa J. Green,^{3,4,5,6} Vinh T. Nguyen,¹ Andrew Frankland,^{3,4} Florence Levy,³ Rhoshel Lenroot^{3,6} and Philip B. Mitchell^{3,4}

Breakspear et al. 2015,
Brain

Original Investigation

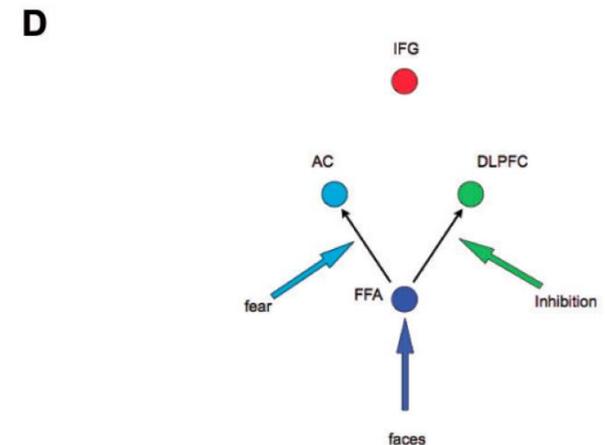
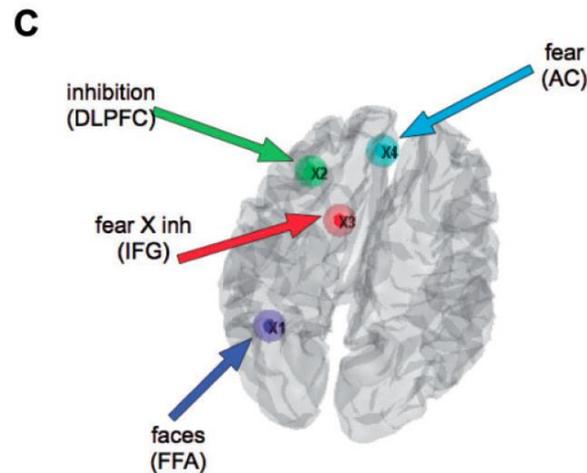
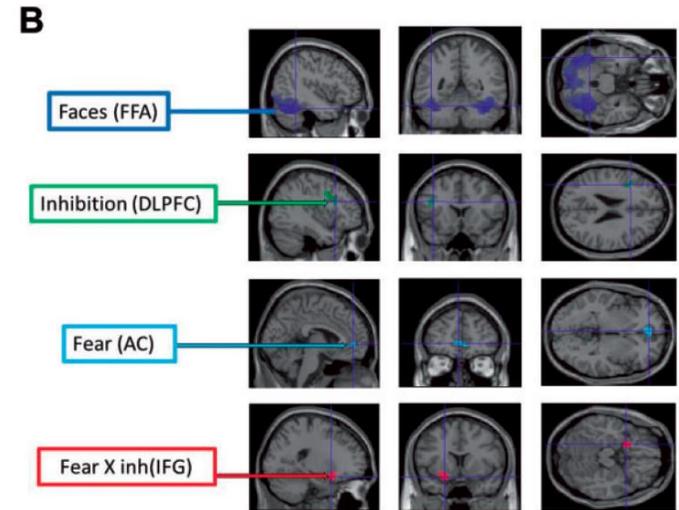
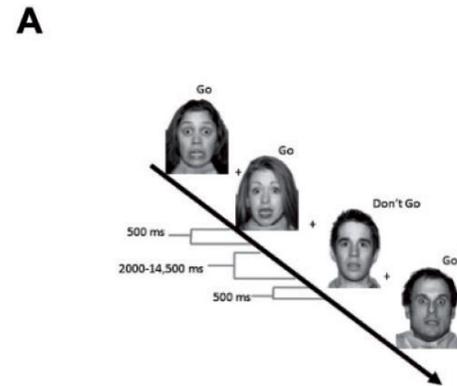
Brain Connectivity Abnormalities Predating the Onset of Psychosis Correlation With the Effect of Medication

André Schmidt, PhD; Renata Smieskova, PhD; Jacqueline Aston, MD; Andor Simon, MD; Paul Allen, PhD; Paolo Fusar-Poli, MD, PhD; Philip K. McGuire, MD, PhD; Anita Riecher-Rössler, MD, PhD; Klaas E. Stephan, MD, PhD; Stefan Borgwardt, MD, PhD

Schmidt et al. 2013,
JAMA Psychiatry

Go/No-Go task to emotional faces (bipolar patients, at-risk individuals, controls)

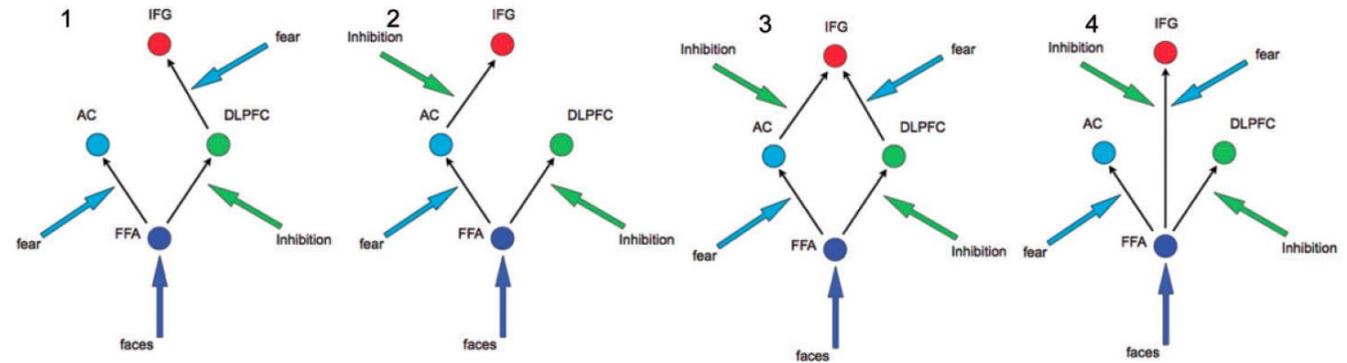
- Hypoactivation of left IFG in the at-risk group during fearful distractor trials
- DCM used to explain interaction of motor inhibition and fear perception
- That is: what is the most likely circuit mechanism explaining the fear x inhibition interaction in IFG?



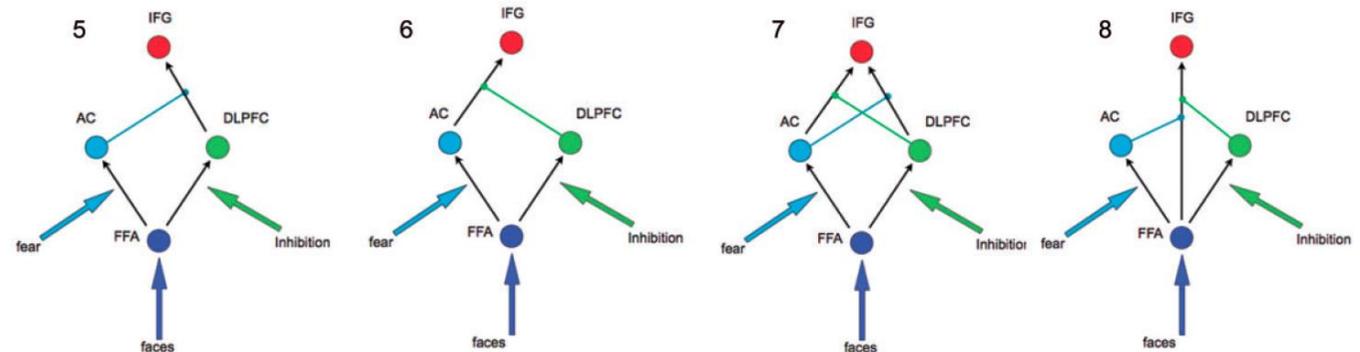
Model space

- models of serial (1-3), parallel (4) and hierarchical (5-8) processes

A: Bilinear models

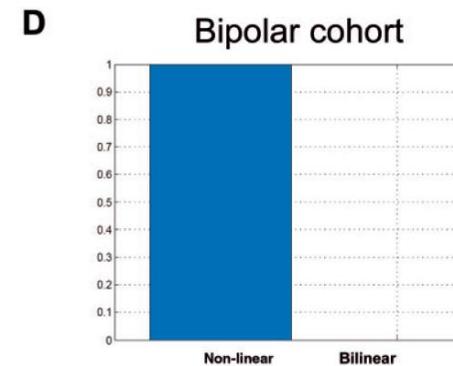
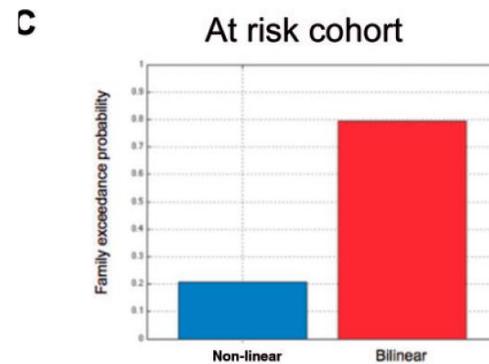
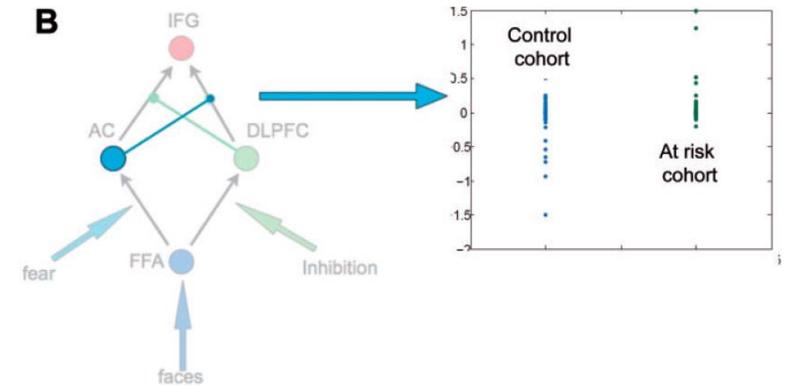
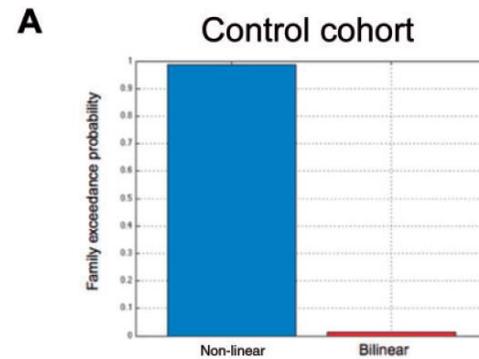


B: Non-linear models



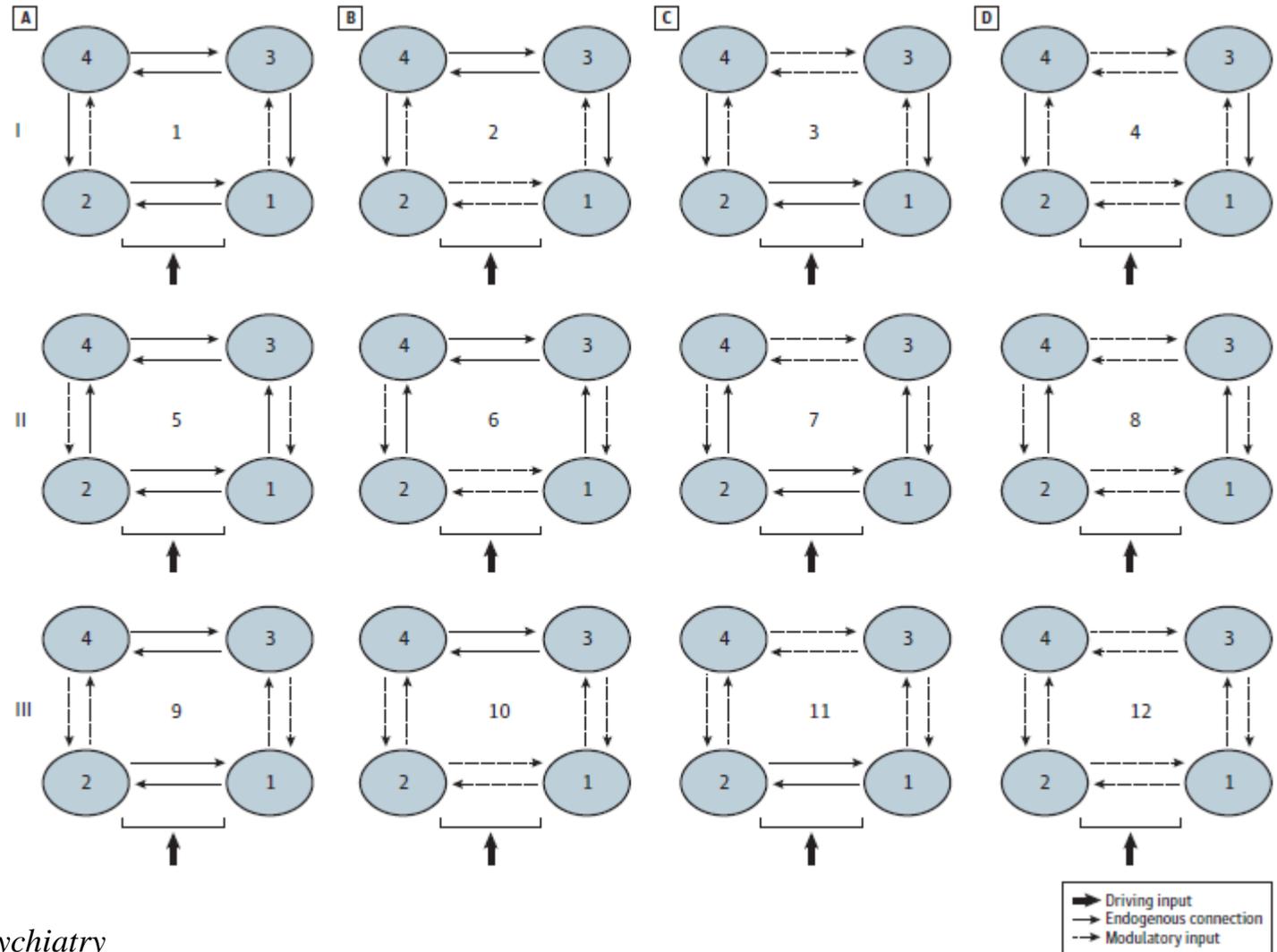
Family-level BMS

- family-level comparison: nonlinear models more likely than bilinear ones in both healthy controls and bipolar patients
- at-risk group: bilinear models more likely
- significant group difference in ACC modulation of DLPFC→IFG interaction



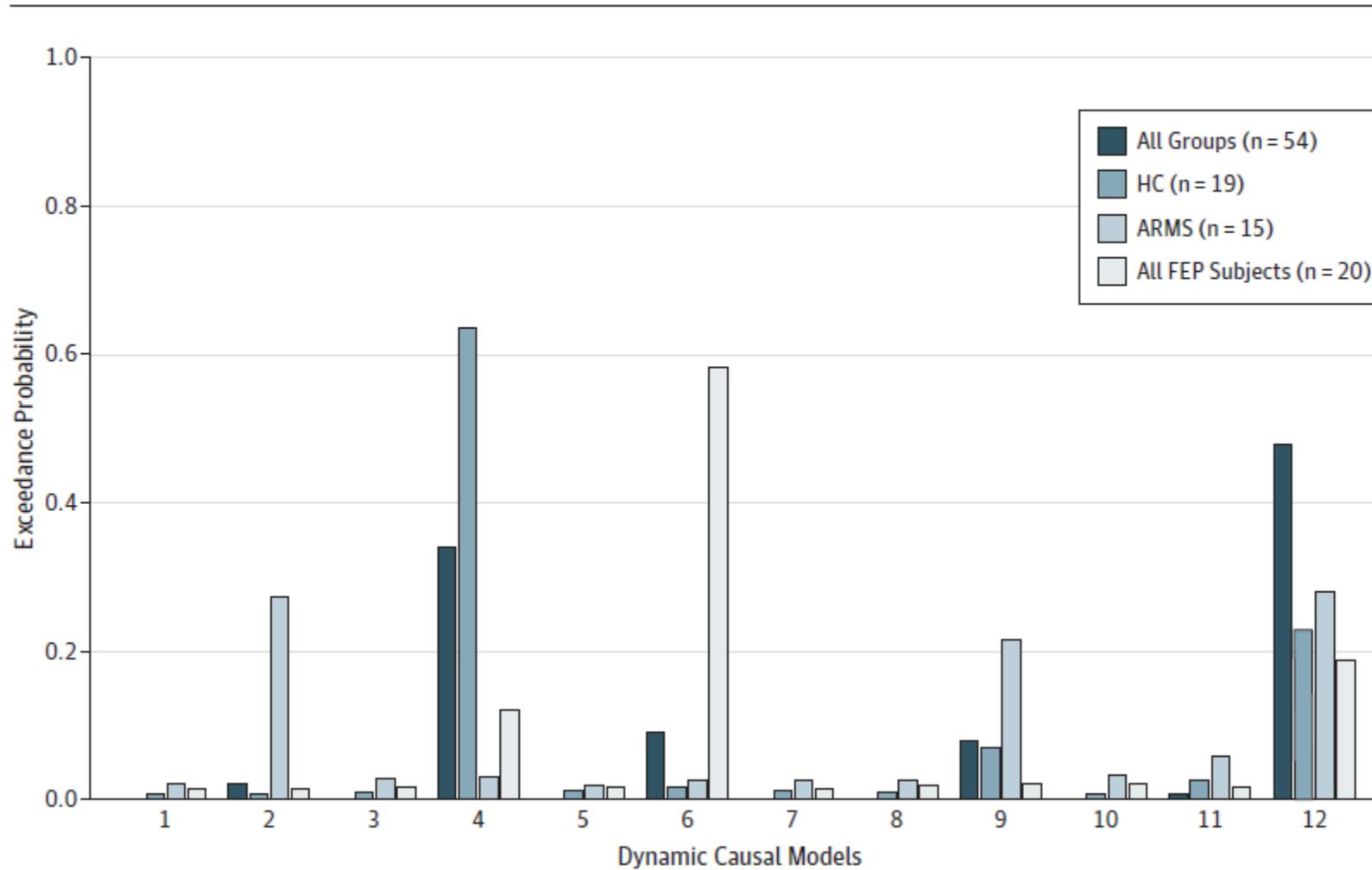


Prefrontal-parietal connectivity during working memory in schizophrenia

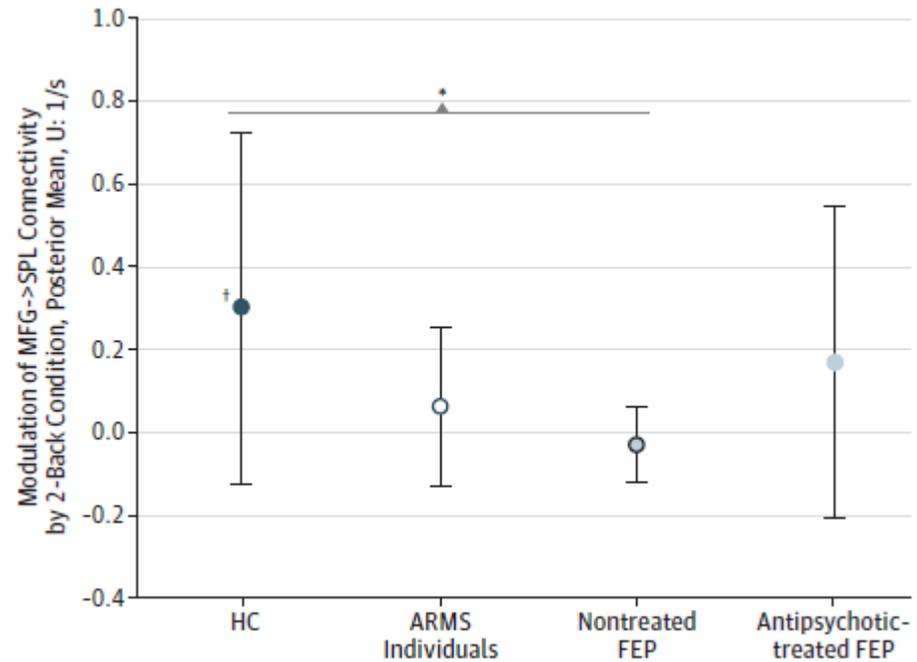
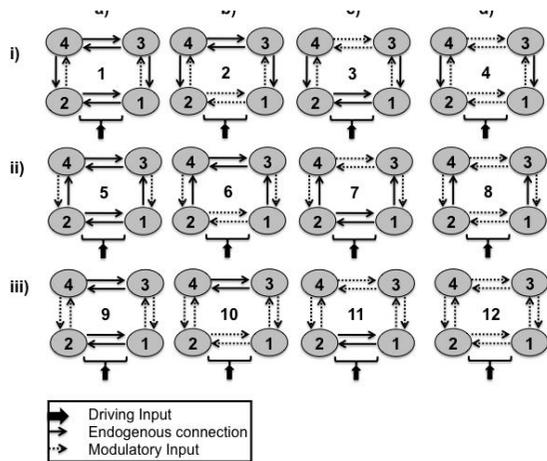
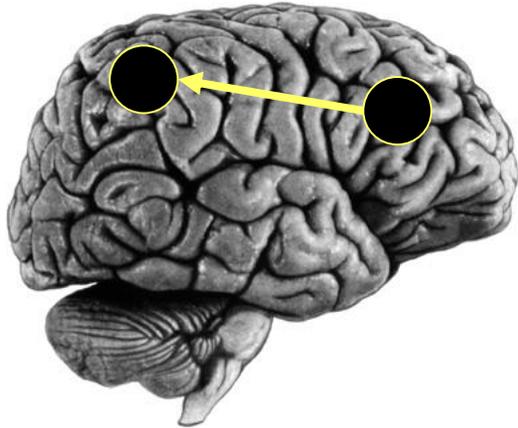


- 17 at-risk mental state (ARMS) individuals
- 21 first-episode patients (13 non-treated)
- 20 controls

BMS results for all groups



BMA results: PFC → PPC connectivity



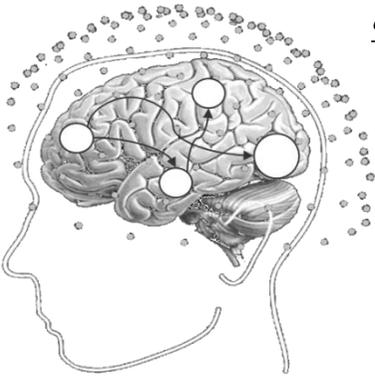
17 ARMS, 21 first-episode (13 non-treated),
20 controls

Overview

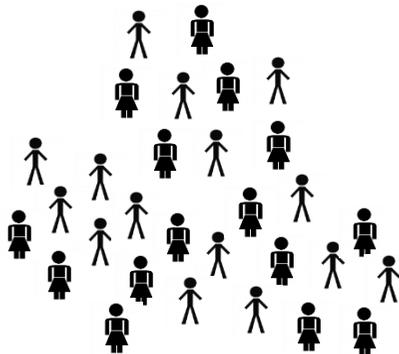
- DCM: basic concepts
- Evolution of DCM for fMRI
- Bayesian model selection (BMS)
- Translational Neuromodeling

Translational Neuromodeling

1 Computational assays: Models of disease mechanisms

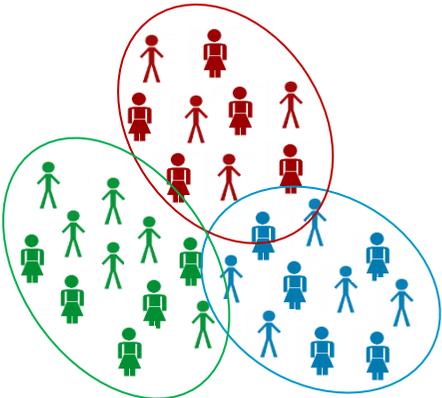


$$\frac{dx}{dt} = f(x, u, \theta) + \omega$$



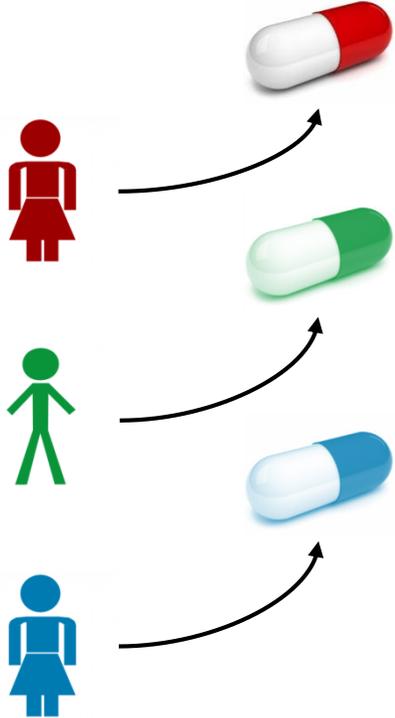
2 Application to brain activity and behaviour of individual patients

3 Detecting physiological subgroups (based on inferred mechanisms)

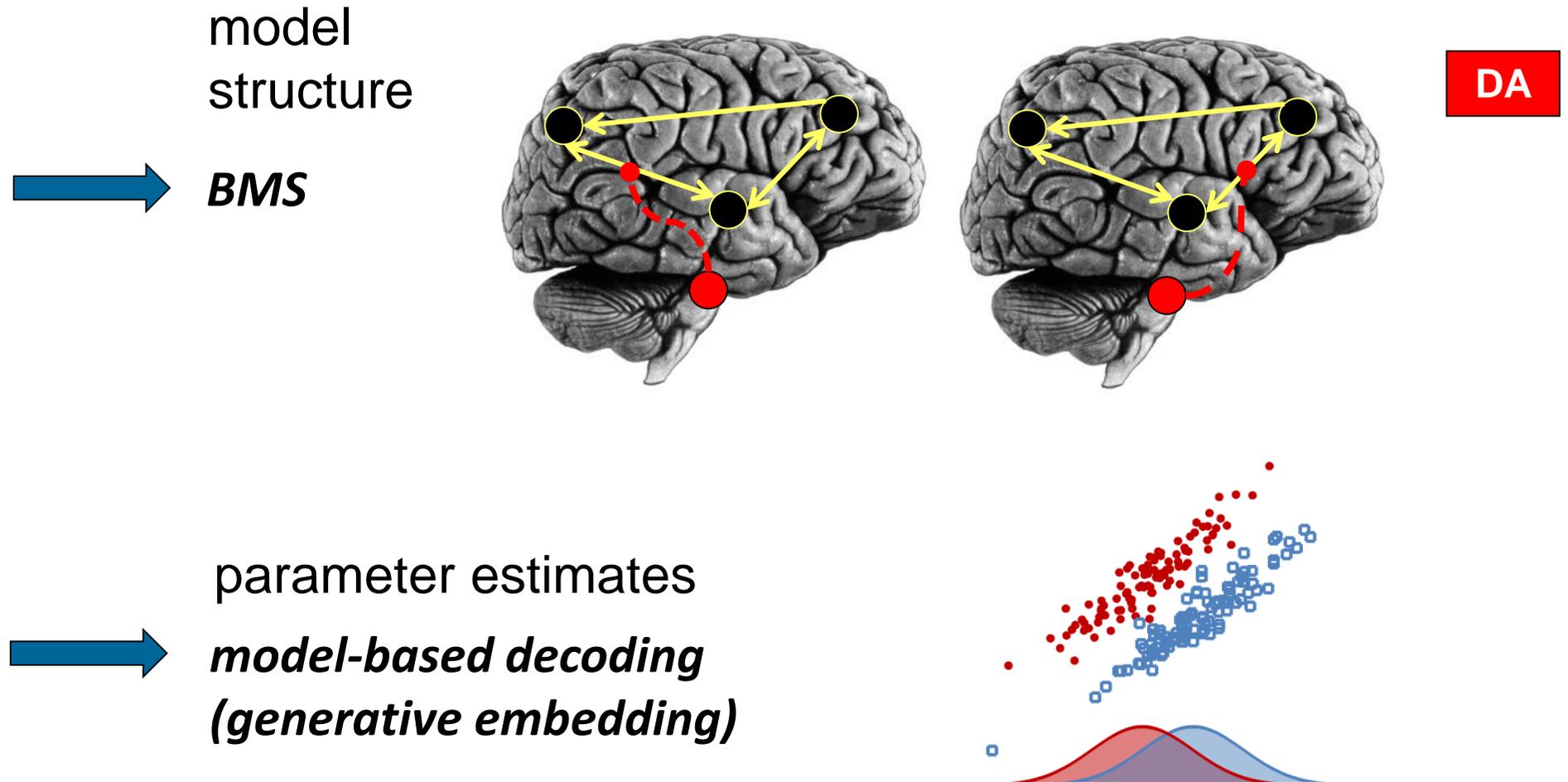


- disease mechanism A
- disease mechanism B
- disease mechanism C

4 Individual treatment prediction



Model-based predictions for single patients



Synaesthesia

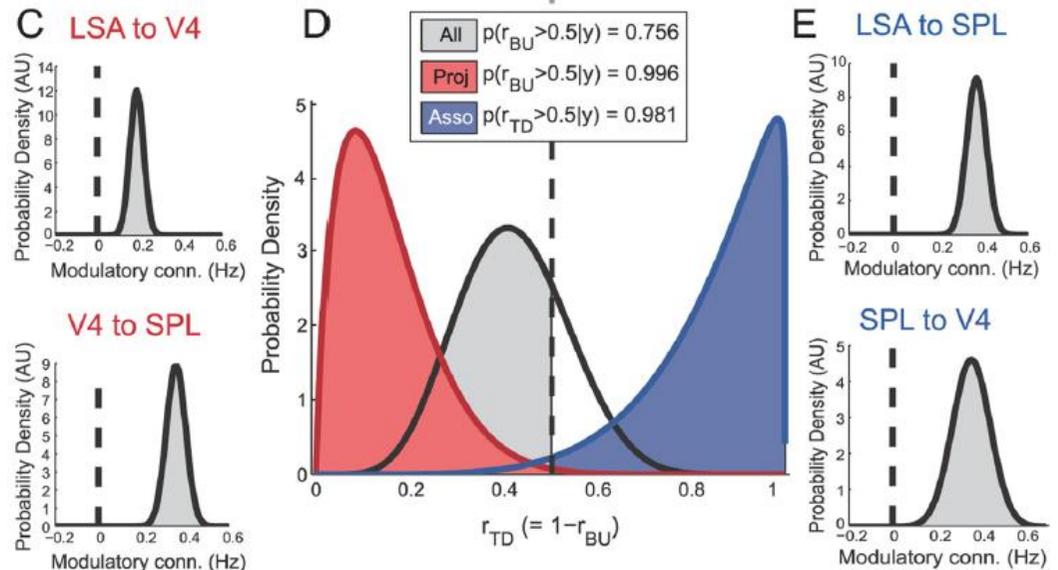
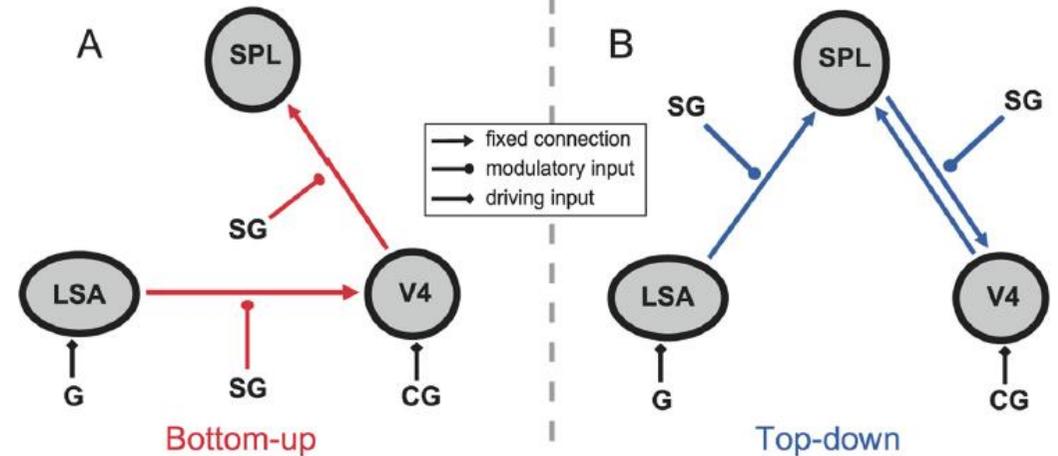
- “projectors” experience color externally colocalized with a presented grapheme
- “associators” report an internally evoked association
- across all subjects: no evidence for either model
- but BMS results map precisely onto projectors (bottom-up mechanisms) and associators (top-down)

PROJECTORS

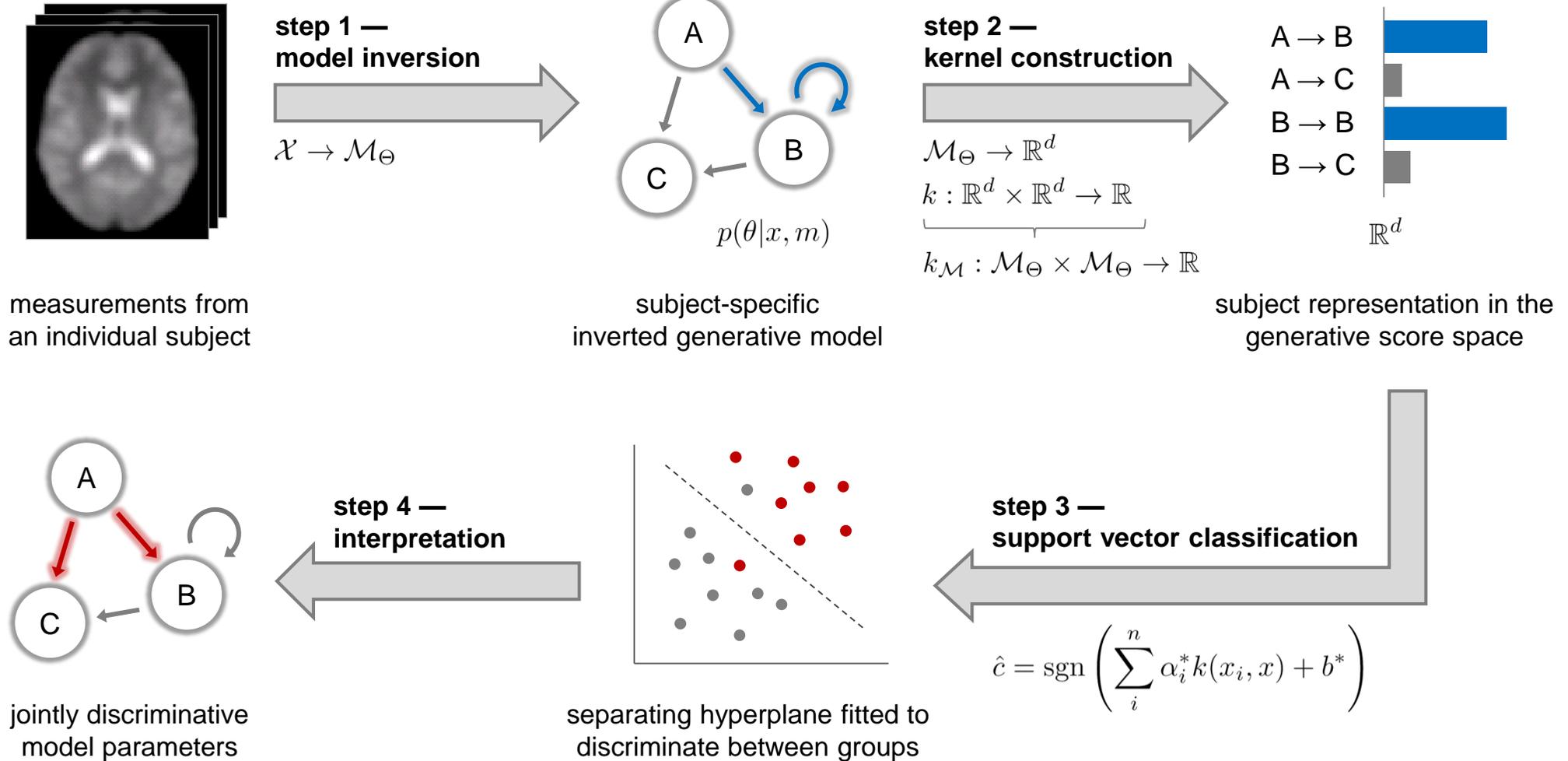
ASSOCIATORS

AB

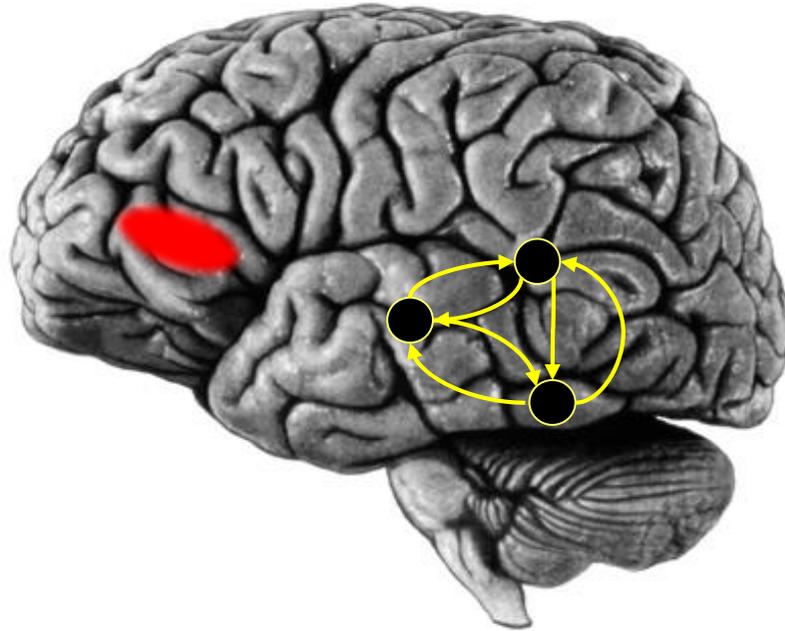
AB



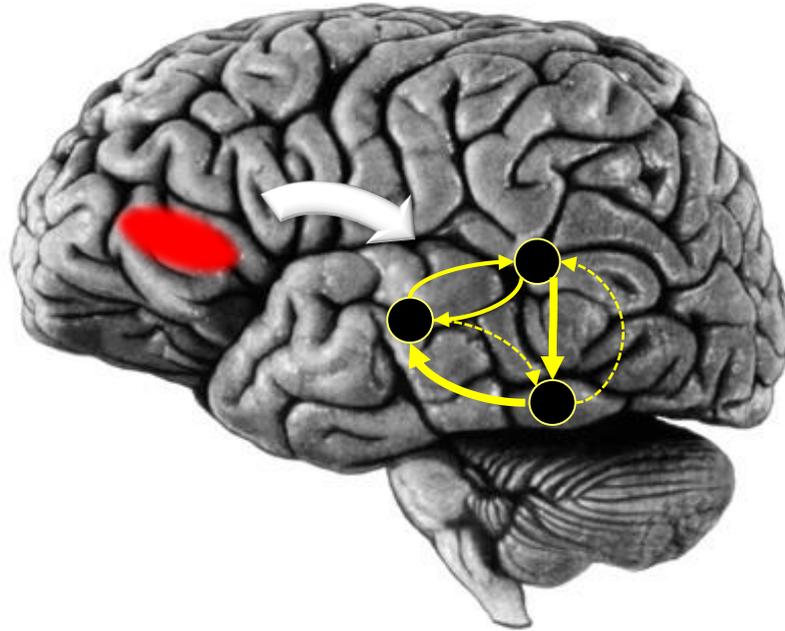
Generative embedding (supervised): classification



Discovering remote or “hidden” brain lesions

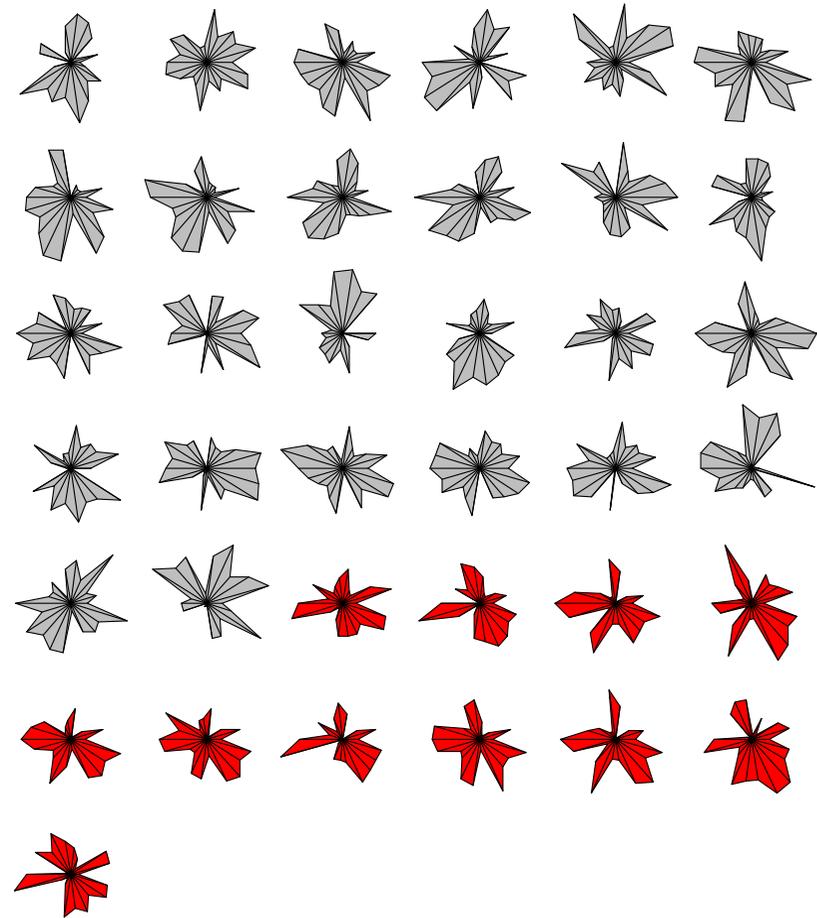
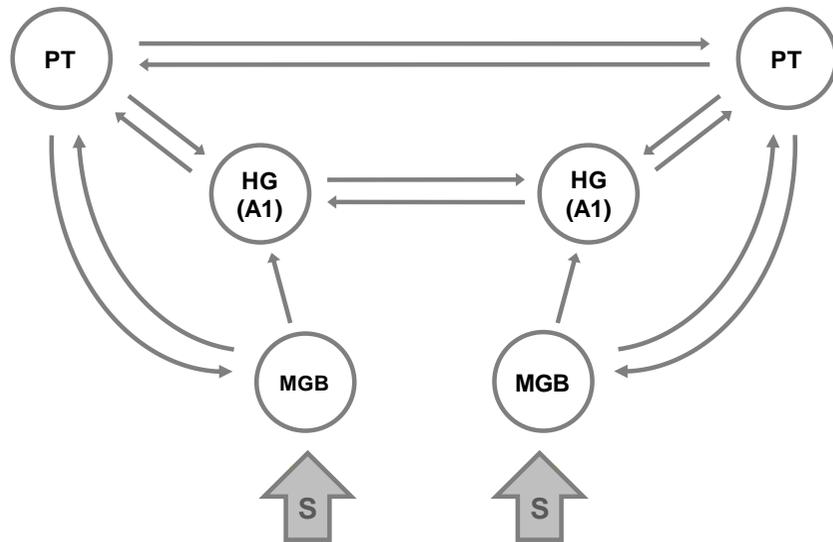


Discovering remote or “hidden” brain lesions

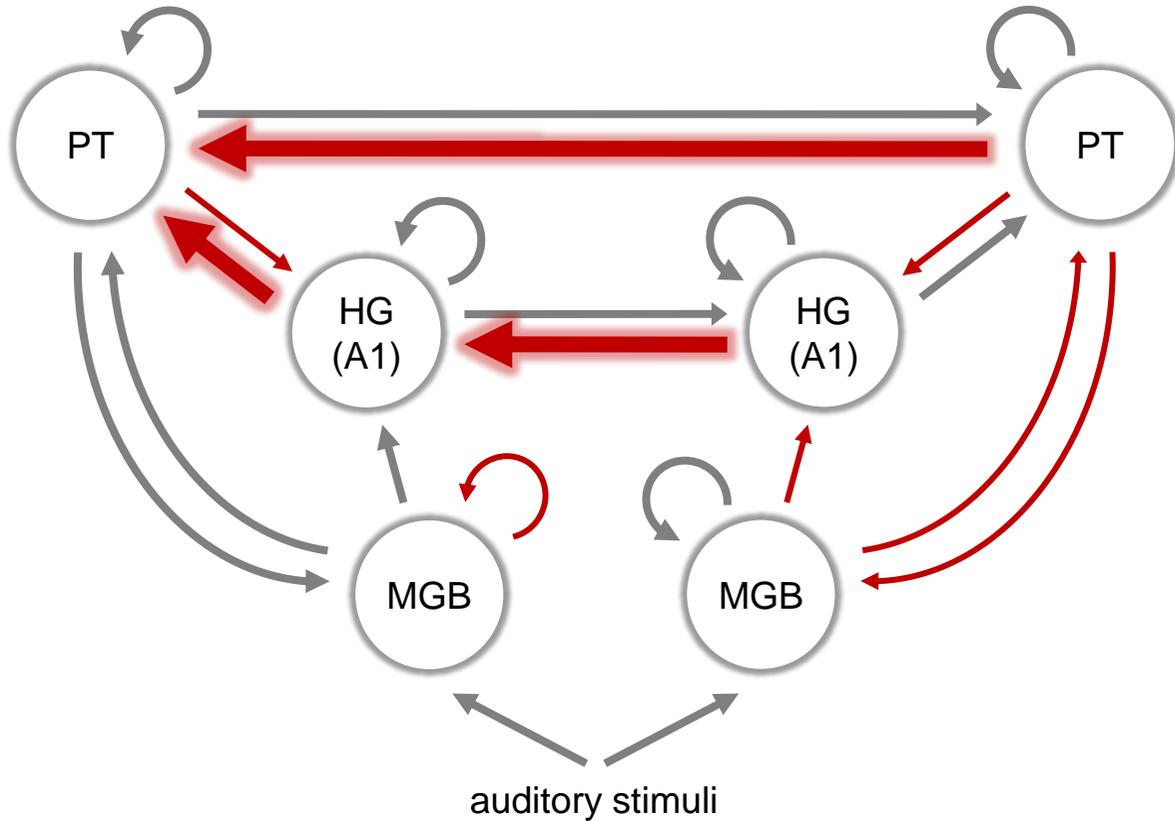


Connectional fingerprints : aphasic patients (N=11) vs. controls (N=26)

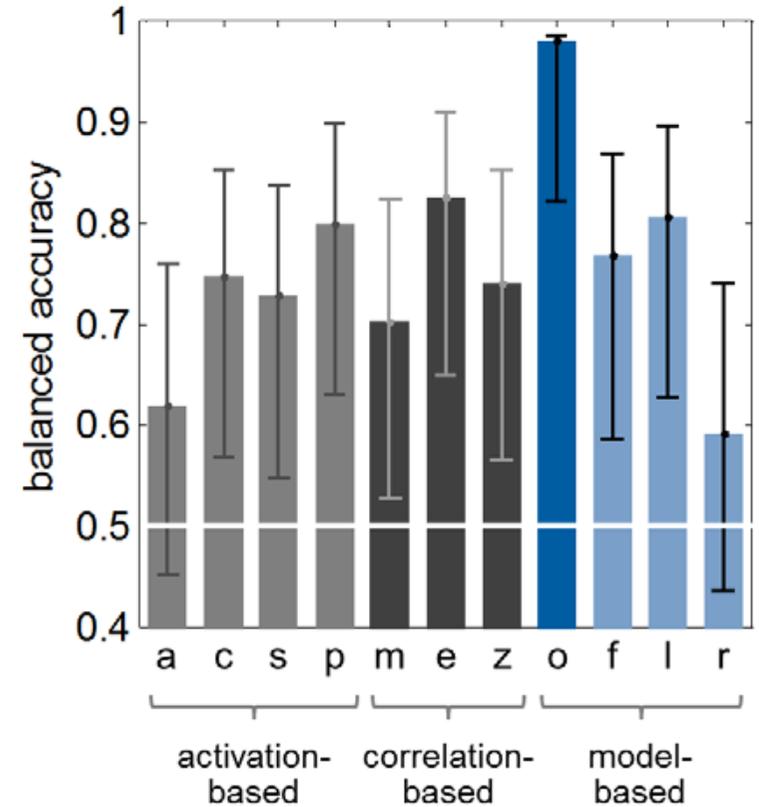
6-region DCM of auditory
areas during passive speech
listening



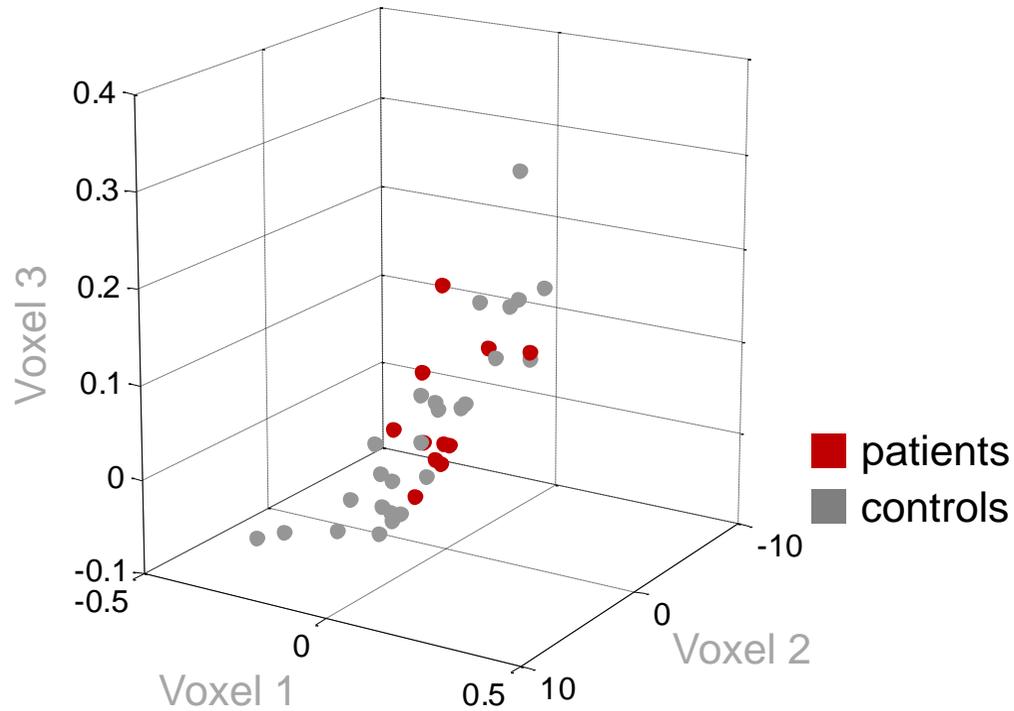
Can we predict presence/absence of the "hidden" lesion?



Classification accuracy

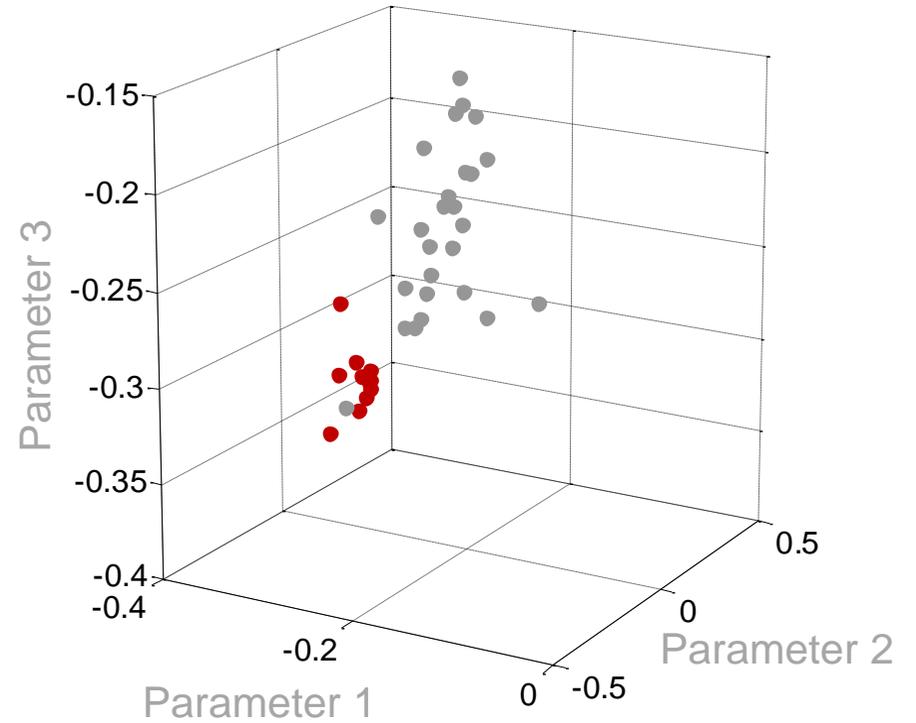


Voxel-based activity space

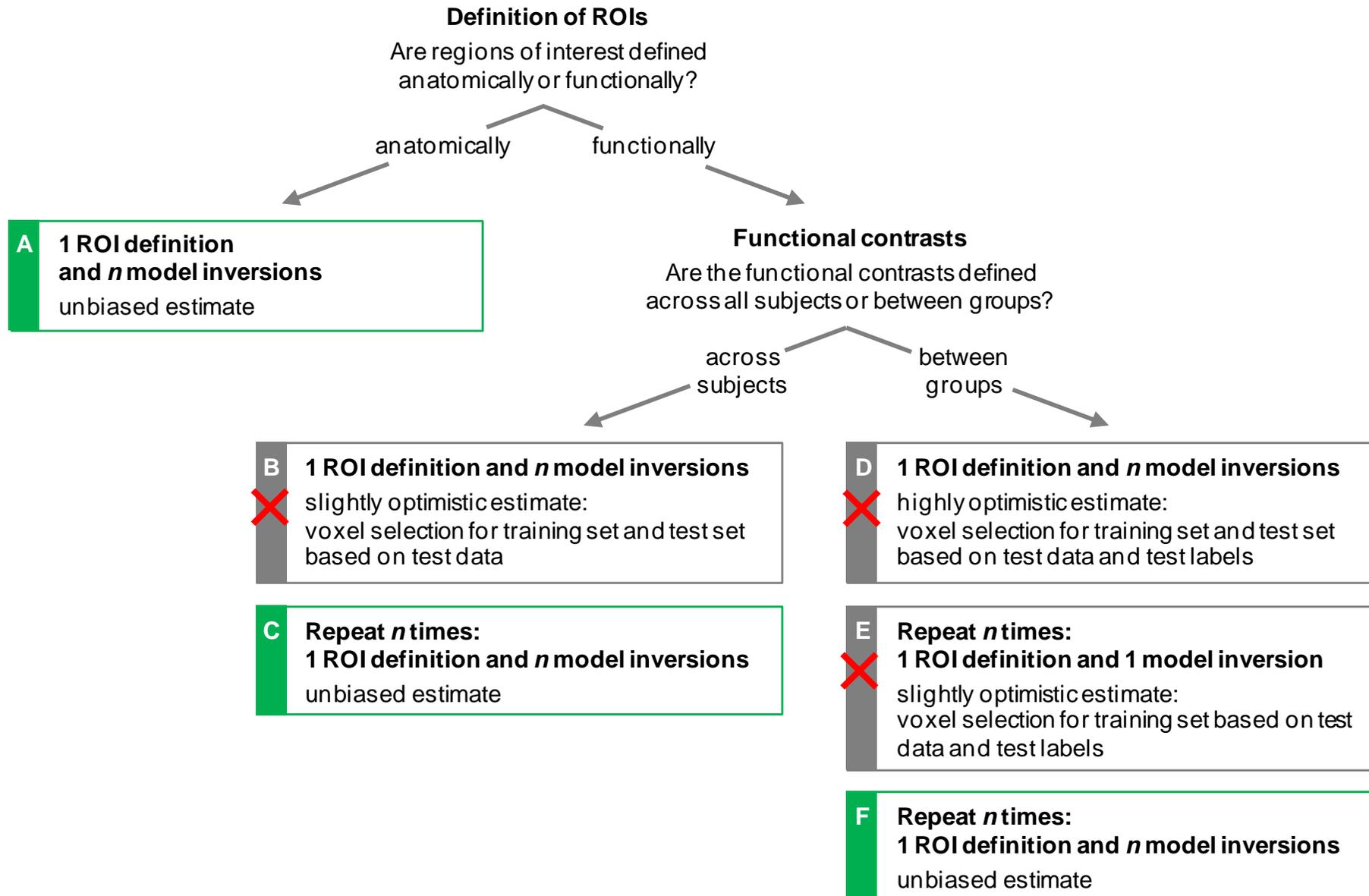


classification accuracy
75%

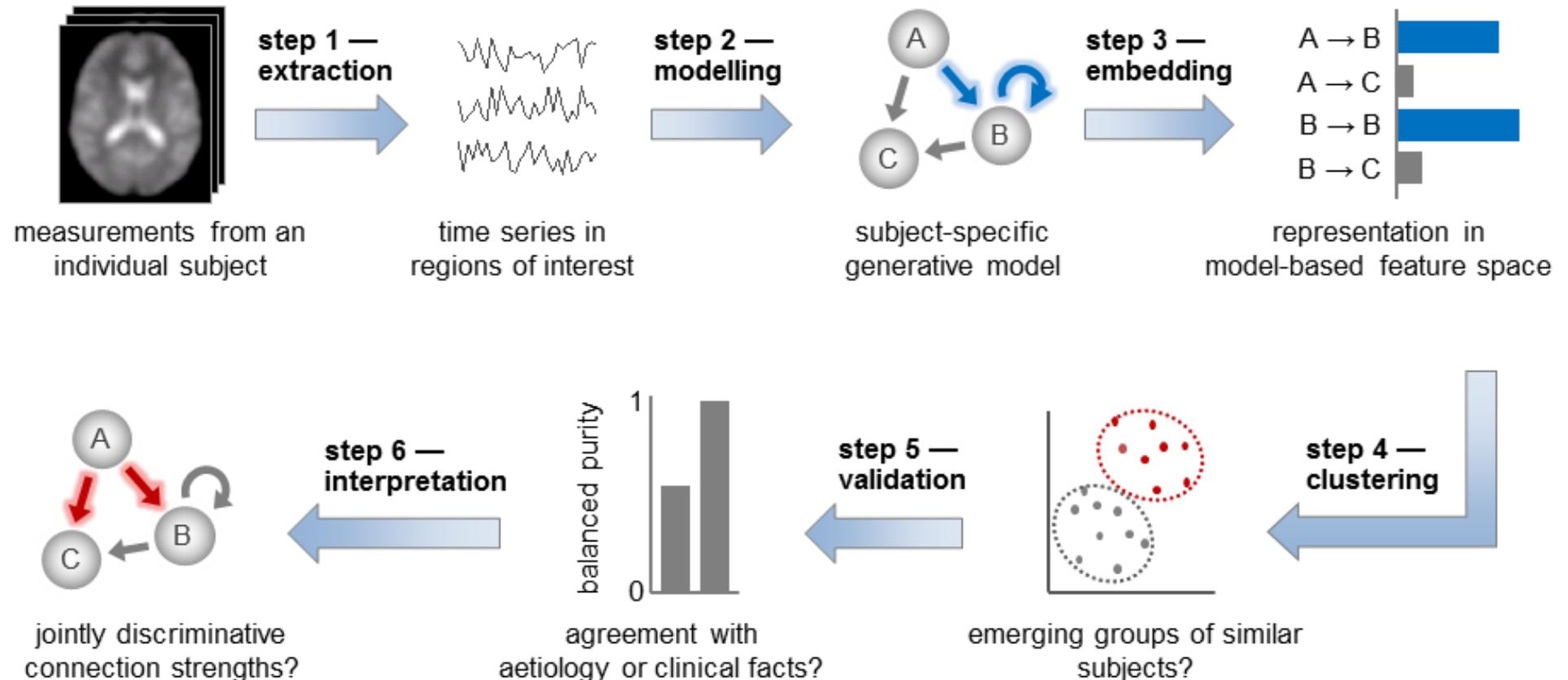
Model-based parameter space



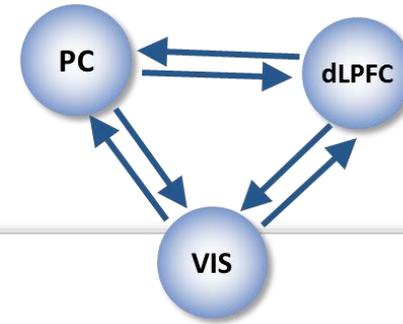
classification accuracy
98%



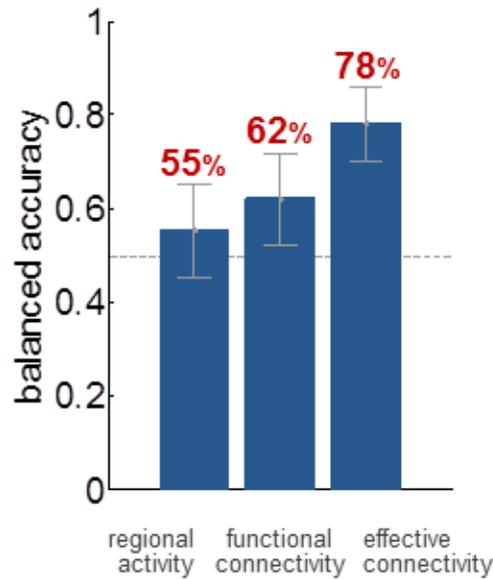
Generative embedding (unsupervised): detecting patient subgroups



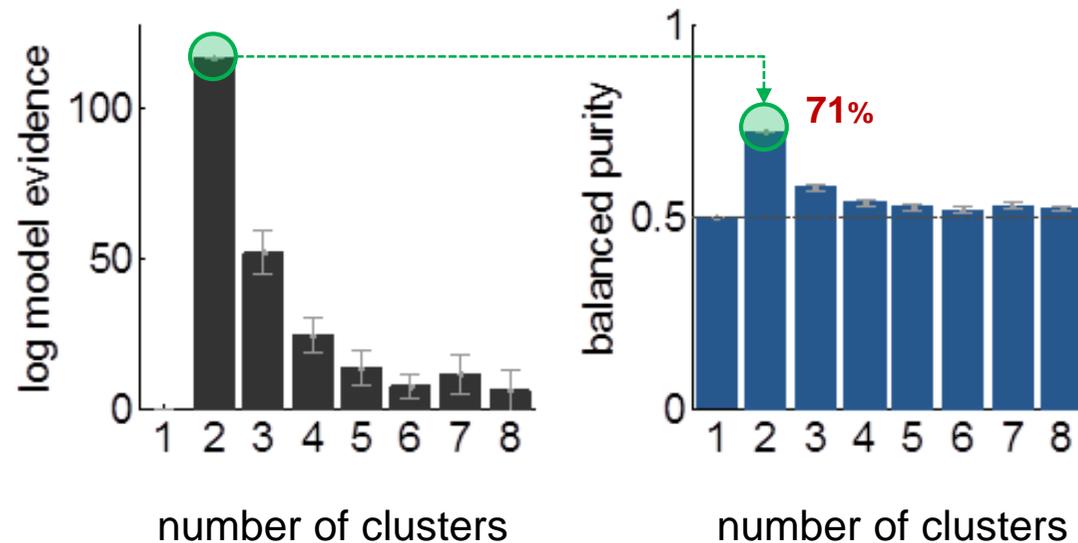
Generative embedding of variational Gaussian Mixture Models



Supervised: SVM classification



Unsupervised: GMM clustering

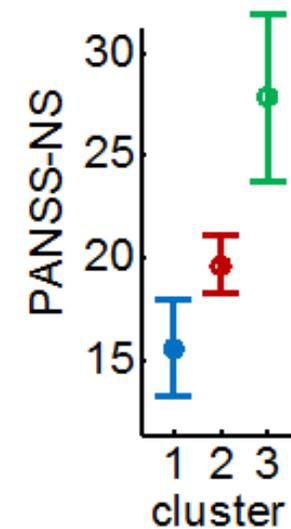
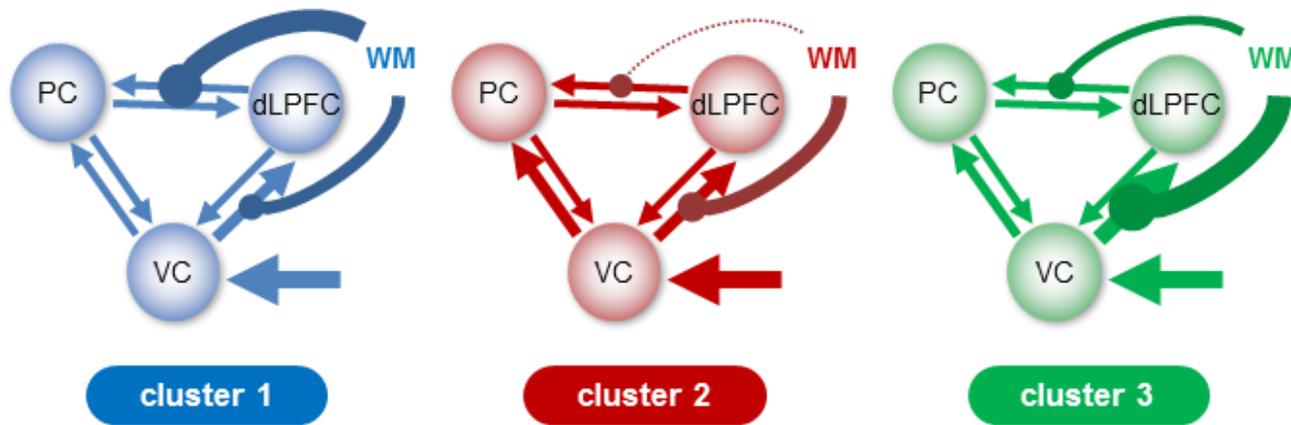
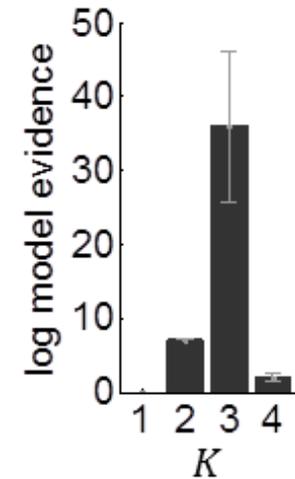


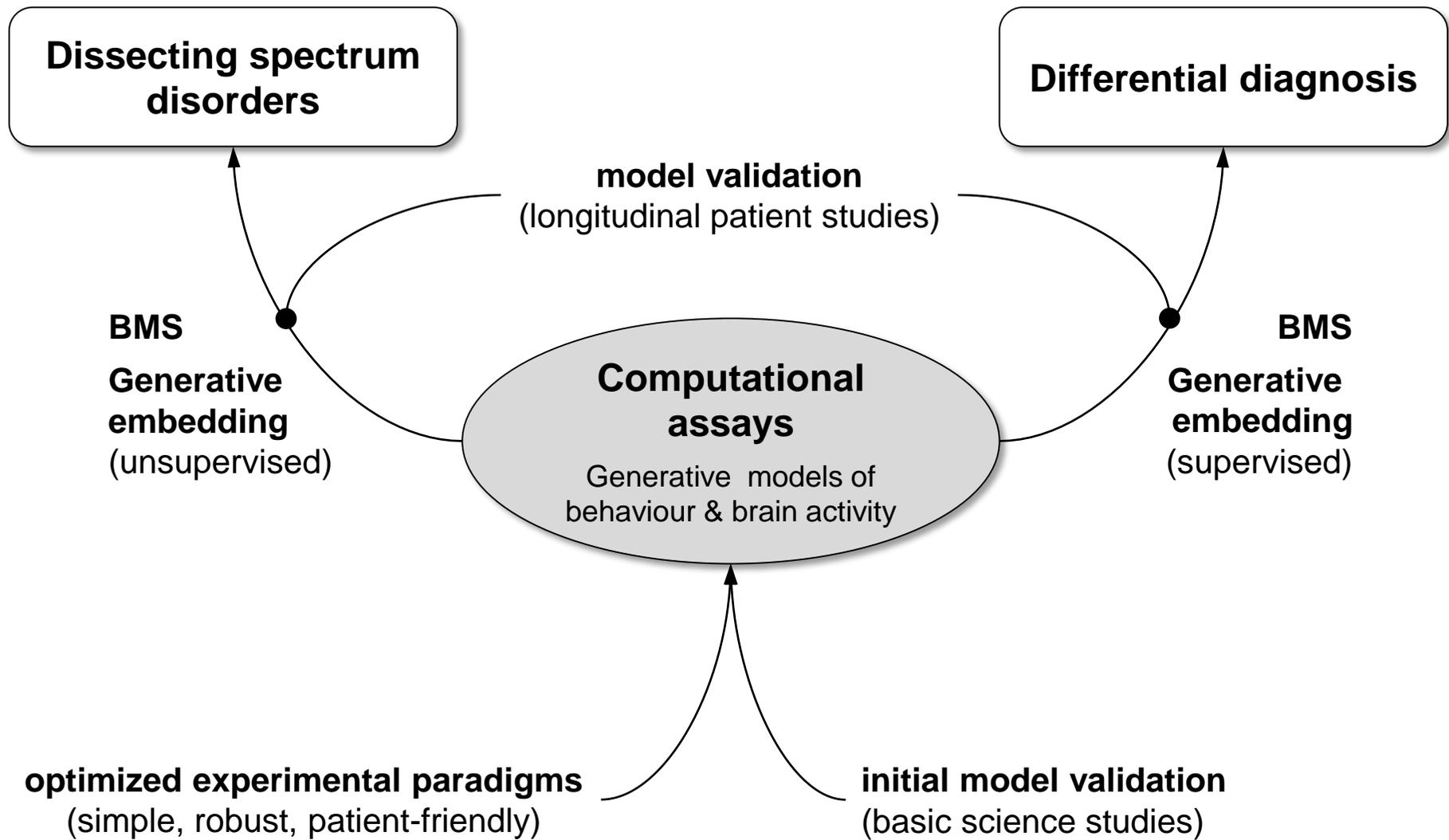
- 42 controls vs. 41 schizophrenic patients
- fMRI data from working memory task (Deserno et al. 2012, J. Neurosci)

Detecting subgroups of patients in schizophrenia

Optimal cluster solution

- three distinct subgroups (total N=41)
- subgroups differ ($p < 0.05$) wrt. negative symptoms on the *positive and negative symptom scale* (PANSS)





Further reading: DCM for fMRI and BMS – part 1

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- Breakspear M, Roberts G, Green MJ, Nguyen VT, Frankland A, Levy F, Lenroot R, Mitchell PB (2015) Network dysfunction of emotional and cognitive processes in those at genetic risk of bipolar disorder. *Brain*, in press.
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- Penny WD, Stephan KE, Mechelli A, Friston KJ (2004a) Comparing dynamic causal models. *NeuroImage* 22:1157-1172.
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Further reading: DCM for fMRI and BMS – part 2

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- Penny WD (2012) Comparing dynamic causal models using AIC, BIC and free energy. *Neuroimage* 59: 319-330.
- Rigoux L, Stephan KE, Friston KJ, Daunizeau J (2014) Bayesian model selection for group studies – revisited. *NeuroImage* 84: 971-985.
- Stephan KE, Harrison LM, Penny WD, Friston KJ (2004) Biophysical models of fMRI responses. *Curr Opin Neurobiol* 14:629-635.
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- Stephan KE, Harrison LM, Kiebel SJ, David O, Penny WD, Friston KJ (2007) Dynamic causal models of neural system dynamics: current state and future extensions. *J Biosci* 32:129-144.
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Thank you