Multiple comparison correction

Methods & models for fMRI data analysis 23 October 2018

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Overview of SPM



Inference at a single voxel



NULL hypothesis H_0 : activation is zero

 $\alpha = p(T > u \mid H_0)$

We can choose u to set a voxel-wise significance level of α .

p-value: probability of getting a value of the test statistic t , or a more extreme value, under the null hypothesis.

If the p-value is smaller than u, we reject the null hypothesis.

 t_{N-p}

Types of error		Actual condition		
		H ₀ true	H ₀ false	
Test result	Reject H ₀	False positive (FP) Type I error α	True positive (TP)	
	Failure to reject H ₀	True negative (TN)	False negat Type II erro	tive (FN) or β

specificity: 1-α = TN / (TN + FP) = proportion of actual negatives which are correctly identified sensitivity (power): $1-\beta$

= TP / (TP + FN)
= proportion of actual positives which are correctly identified

Assessing SPMs

High Threshold



Good Specificity

Poor Power (risk of false negatives)

Med. Threshold



Low Threshold



Poor Specificity (risk of false positives)

Good Power

Inference on images



Signal+Noise





Using an 'uncorrected' p-value of 0.1 will lead us to conclude on average that 10% of voxels are active when they are not.

This is clearly undesirable. To correct for this we can define a null hypothesis for images of statistics.

Family-wise null hypothesis

FAMILY-WISE NULL HYPOTHESIS: Activation is zero <u>everywhere</u>.

If we reject a voxel null hypothesis at <u>any</u> voxel, we reject the family-wise null hypothesis

A false-positive <u>anywhere</u> in the image gives a Family Wise Error (FWE).

Family-Wise Error (FWE) rate = 'corrected' p-value

Use of 'uncorrected' p-value, α =0.1



Use of 'corrected' p-value, α =0.1





The Bonferroni correction

The family-wise error rate (FWE), α , for a family of N independent voxels is

 $\alpha = Nv$

where v is the voxel-wise error rate.

Therefore, to ensure a particular FWE, we can use

 $v = \alpha / N$

BUT ...

The Bonferroni correction

Independent voxels

Spatially correlated voxels



 Bonferroni correction assumes independence of voxels
 → this is too conservative for brain images, which always have a degree of smoothness

Smoothness (inverse roughness)

- roughness = 1/smoothness
- intrinsic smoothness
 - MRI signals are aquired in k-space (Fourier space); after projection on anatomical space, signals have continuous support
 - diffusion of vasodilatory molecules has extended spatial support
- extrinsic smoothness
 - resampling during preprocessing
 - matched filter theorem
 - \rightarrow deliberate additional smoothing to increase SNR
- described in resolution elements: "resels"
- resel = size of image part that corresponds to the FWHM (full width half maximum) of the Gaussian convolution kernel that would have produced the observed image if it had been applied to independent voxel values
- # resels is similar, but not identical to # independent observations
- can be computed from spatial derivatives of the residuals

Random Field Theory

- Consider a statistic image as a discretisation of a continuous underlying random field with a certain smoothness
- Use results from continuous random field theory



Discretisation ("lattice approximation")



Euler characteristic (EC)

Topological measure threshold an image at $u \rightarrow EC \propto \#$ blobs

At high u: p (blob) = E [EC], therefore (under H_0): FWE rate: α = E [EC]



Euler characteristic (EC) for 2D images

 $E[EC] = R(4 \log 2)(2\pi)^{-3/2} Z_T \exp(-0.5Z_T^2)$

R= number of resels Z_T = Z value threshold

We can determine that Z threshold for which E[EC] = 0.05. At this threshold, every remaining peak represents a significant activation, corrected for multiple comparisons across the search volume.

Example: For 100 resels, E [EC] = 0.049 for a Z threshold of 3.8. That is, the probability of getting one or more blobs where Z is greater than 3.8, is 0.049.



Expected EC values for an image of 100 resels

Euler characteristic (EC) for any image

- Computation of E[EC] can be generalized to volumes of any dimension, shape and size (Worsley et al. 1996).
- When we have an *a priori* hypothesis about where an activation should be, we can (and should) reduce the search volume:
 - mask defined by (probabilistic) anatomical atlases
 - mask defined by separate "functional localisers"
 - mask defined by orthogonal contrasts
 - (spherical) search volume around previously reported coordinates





Worsley et al. 1996. A unified statistical approach for determining significant signals in images of cerebral activation. Human Brain Mapping, 4, 58–83.

Computing EC wrt. search volume and threshold

E(
$$\chi_u$$
) ≈ λ (Ω) | Λ |^{1/2} (u^2 -1) exp(- $u^2/2$) / (2π)²

- $\Omega \qquad \rightarrow \text{Search region } \Omega \subset \mathbb{R}^3$
- $-\lambda(\Omega) \rightarrow \text{volume}$
- $|\Lambda|^{1/2}$ \rightarrow roughness
- Assumptions:
 - Multivariate normal
 - Stationary*
 - ACF twice differentiable at 0
- * Stationarity
 - Results valid w/out stationarity
 - More accurate when stationarity holds

Height, cluster and set level tests





Further reading

- Friston KJ, Frith CD, Liddle PF, Frackowiak RS. Comparing functional (PET) images: the assessment of significant change. J Cereb Blood Flow Metab. 1991 Jul;11(4):690-9.
- Worsley KJ Marrett S Neelin P Vandal AC Friston KJ Evans AC. A unified statistical approach for determining significant signals in images of cerebral activation. Human Brain Mapping 1996;4:58-73.

Thank you