

An introduction to Bayesian inference and model comparison

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Overview of the talk

- ✓ An introduction to probabilistic modelling
- ✓ Bayesian model comparison
- ✓ SPM applications

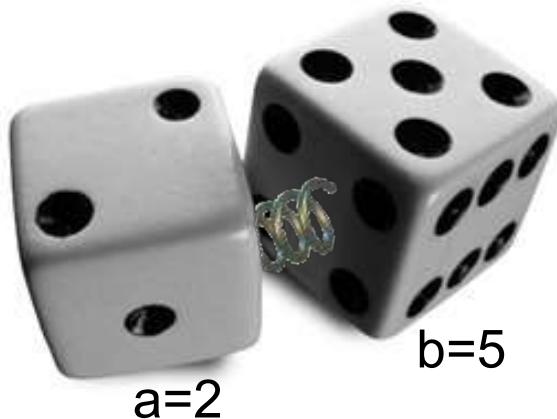
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Probability theory: basics

Degree of plausibility desiderata:

- should be represented using real numbers (D1)
- should conform with intuition (D2)
- should be consistent (D3)



- normalization:

$$\sum_a P(a) = 1$$

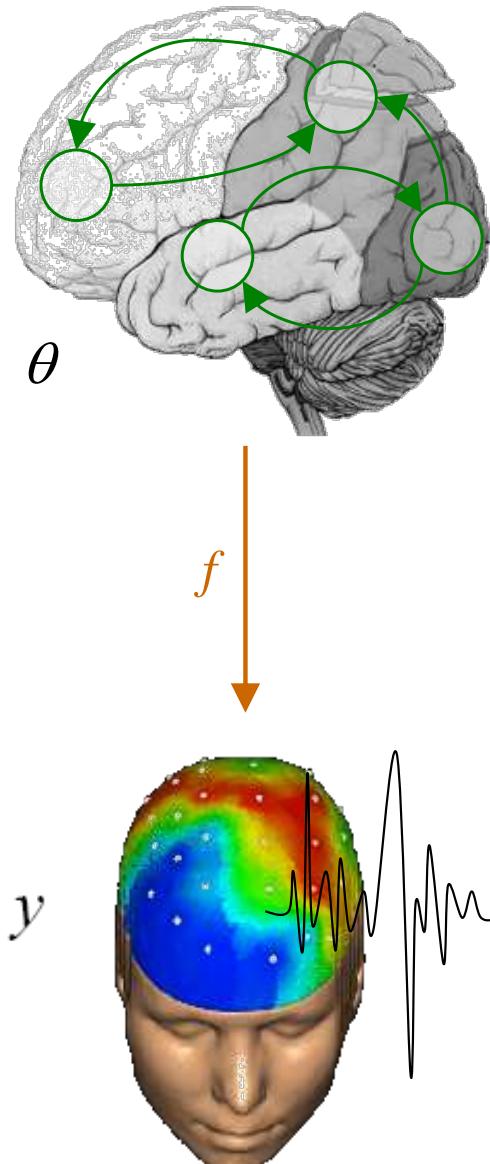
- marginalization:

$$P(b) = \sum_a P(a, b)$$

- conditioning :
(Bayes rule)

$$\begin{aligned} P(a, b) &= P(a|b)P(b) \\ &= P(b|a)P(a) \end{aligned}$$

Deriving the likelihood function



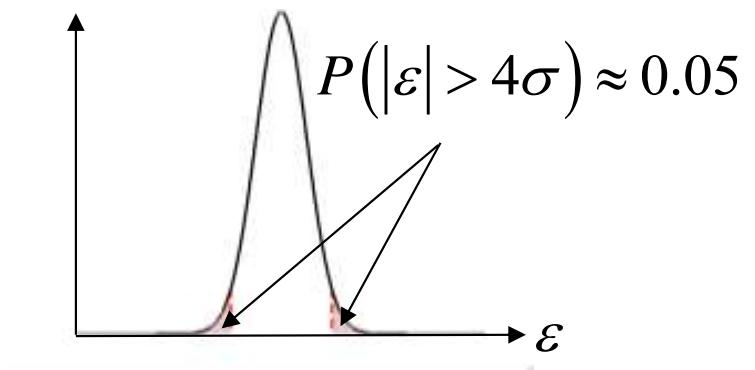
- Model of data with unknown parameters:

$$y = f(\theta) \quad \text{e.g., GLM: } f(\theta) = X\theta$$

- But data is noisy: $y = f(\theta) + \varepsilon$

- Assume noise/residuals is ‘small’:

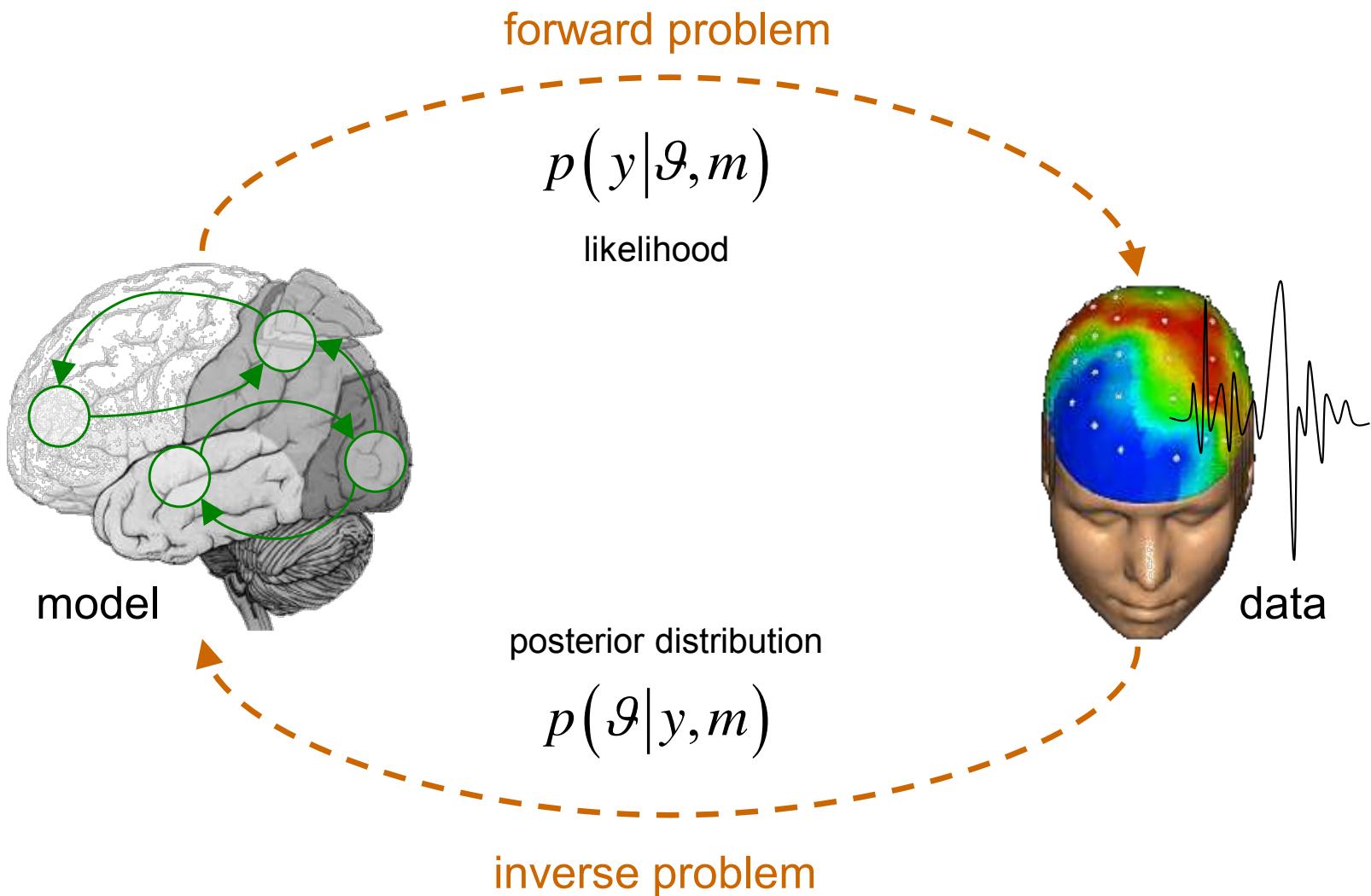
$$p(\varepsilon) \propto \exp\left(-\frac{1}{2\sigma^2} \varepsilon^2\right)$$



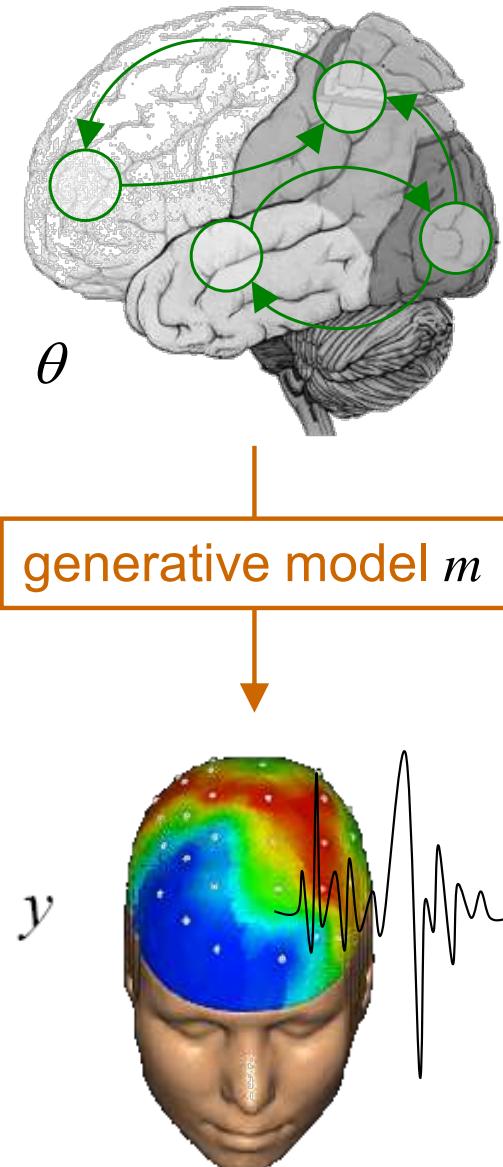
→ Distribution of data, *given fixed parameters*:

$$p(y|\theta) \propto \exp\left(-\frac{1}{2\sigma^2}(y - f(\theta))^2\right)$$

Forward and inverse problems



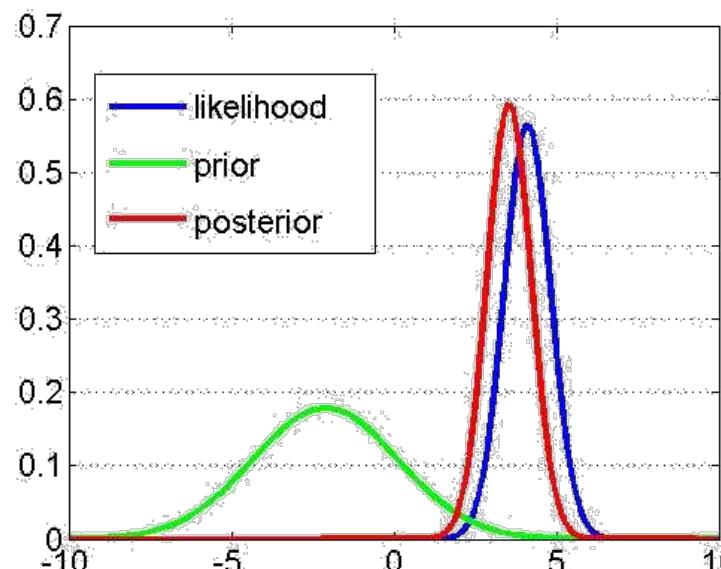
Likelihood, priors and the model evidence



Likelihood: $p(y|\theta, m)$

Prior: $p(\theta|m)$

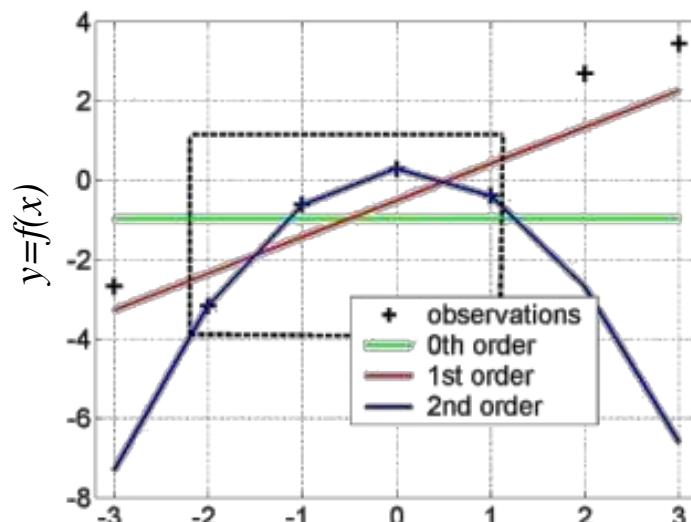
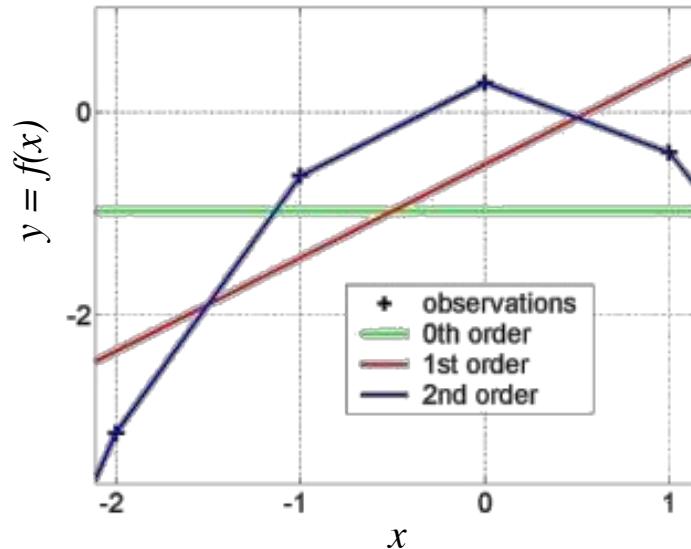
Bayes rule: $p(\theta|y, m) = \frac{p(y|\theta, m)p(\theta|m)}{p(y|m)}$



Bayesian model comparison

Principle of parsimony :

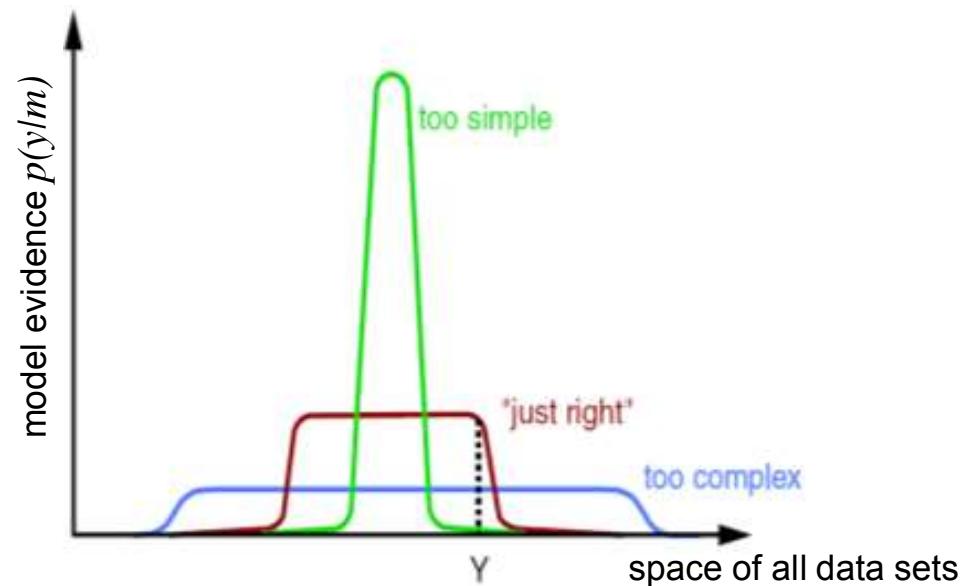
« plurality should not be assumed without necessity »



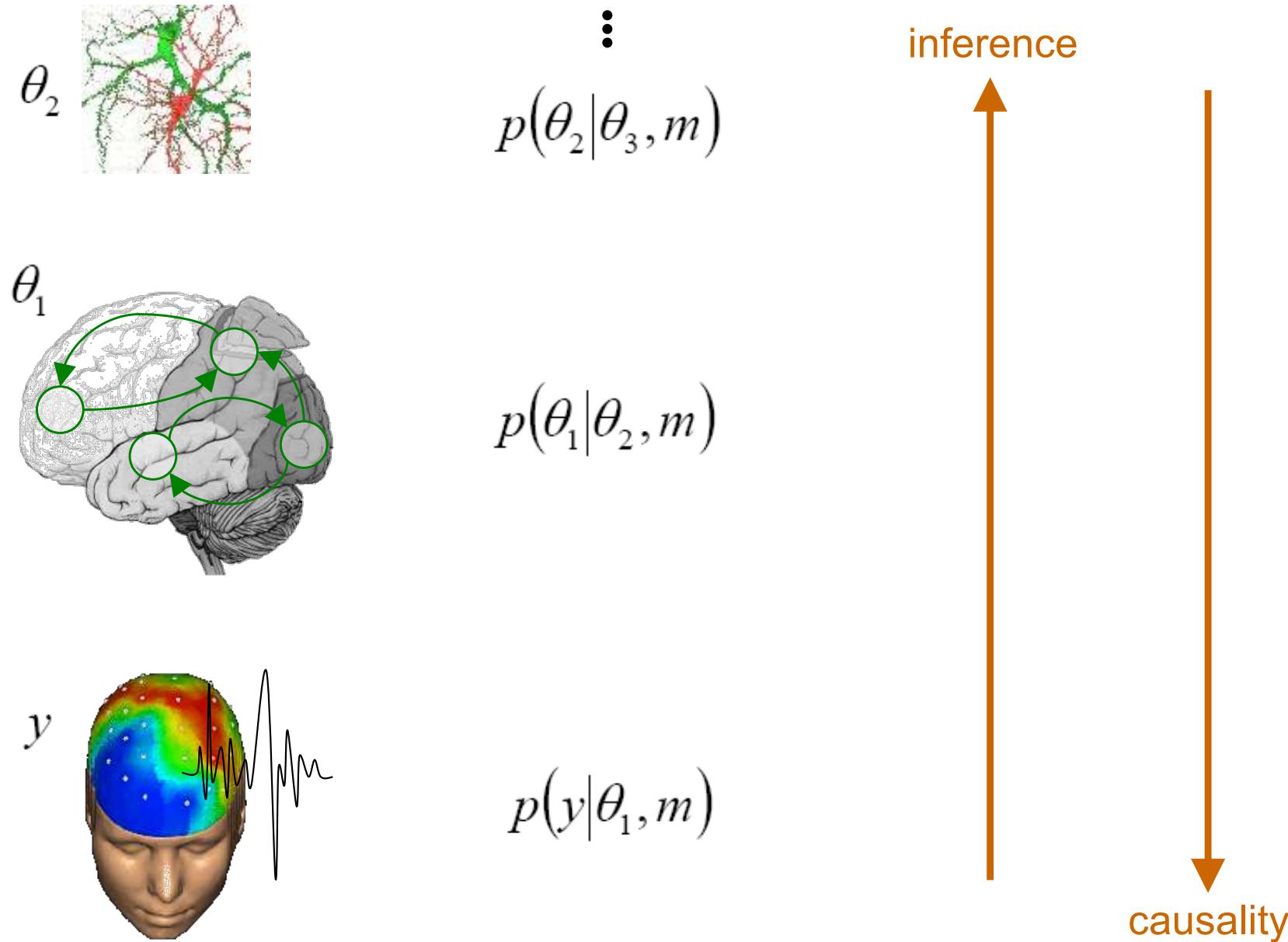
Model evidence:

$$p(y|m) = \int p(y|\theta, m)p(\theta|m)d\theta$$

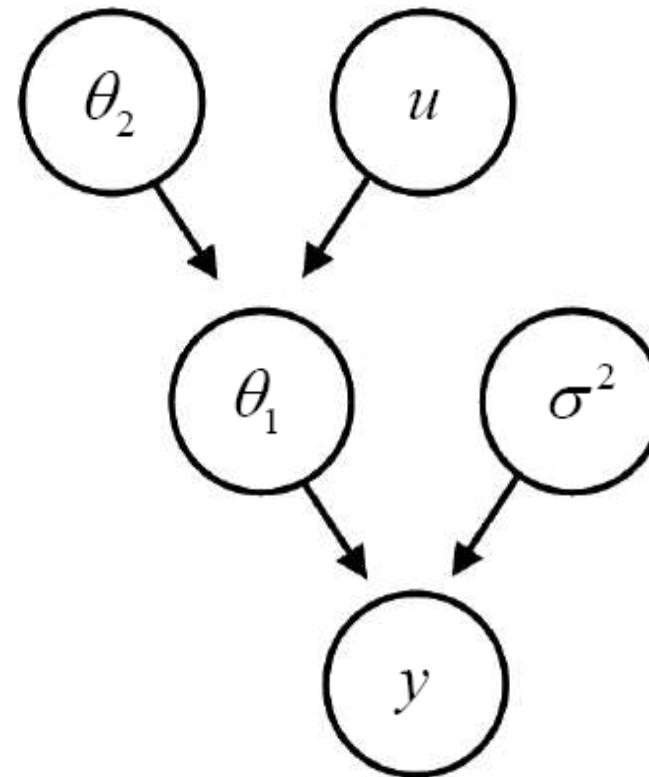
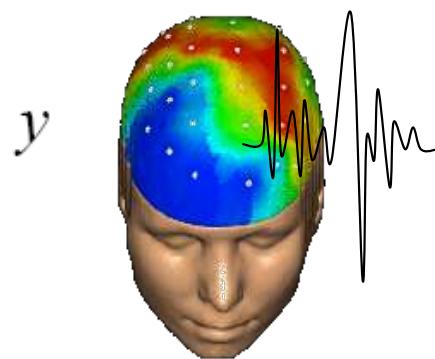
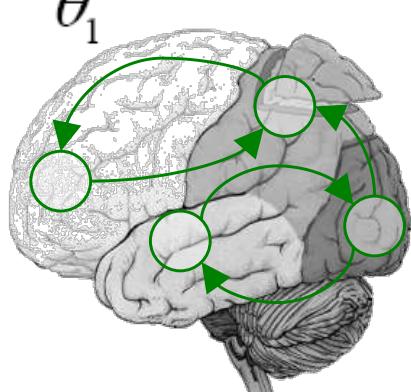
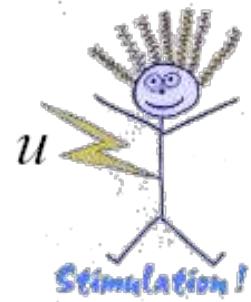
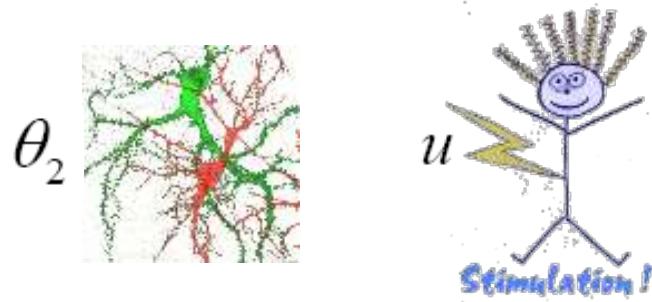
“Occam’s razor” :



Hierarchical models



Directed acyclic graphs (DAGs)



$$p(\theta_1 | \theta_2, u, m)$$

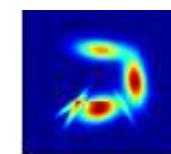
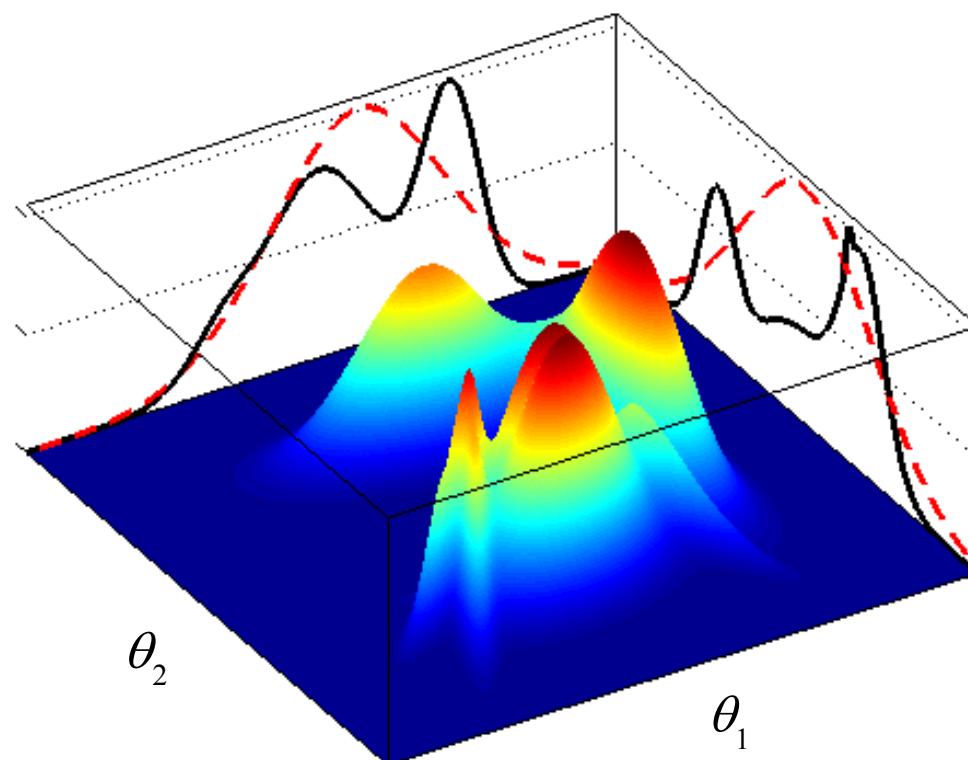
$$p(y | \theta_1, \sigma^2, m)$$

$$p(\theta | m) = \prod_j p(\theta_j | \text{par}(\theta_j), m)$$

Variational approximations (VB, EM, ReML)

$$\ln p(y|m) = \underbrace{\left\langle \ln p(y, \theta|m) \right\rangle_q + S(q)}_{\text{Free energy } F(q)} + KL(p(\theta|y, m); q(\theta))$$

→ **VB** : maximize the **free energy** $F(q)$ w.r.t. the **approximate posterior** $q(\theta)$ under some (e.g., *mean field*, *Laplace*) simplifying constraint



$$p(\theta_1, \theta_2 | y, m)$$



$$p(\theta_{1 \text{ or } 2} | y, m)$$



$$q(\theta_{1 \text{ or } 2})$$

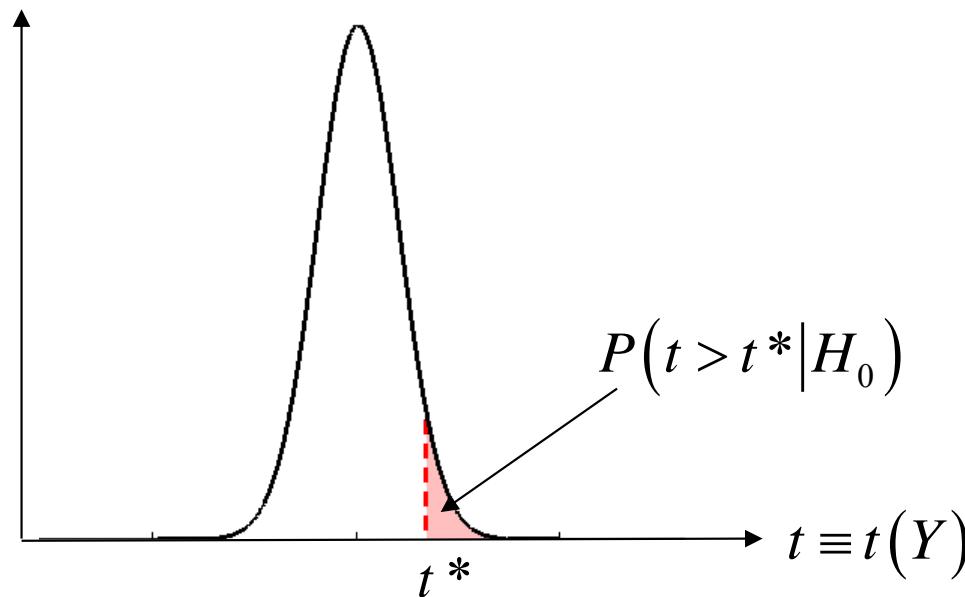
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Frequentist versus Bayesian inference

- define the null, e.g.: $H_0 : \theta = 0$

$$p(t|H_0)$$



- estimate parameters (obtain test stat.)

- apply decision rule, i.e.:

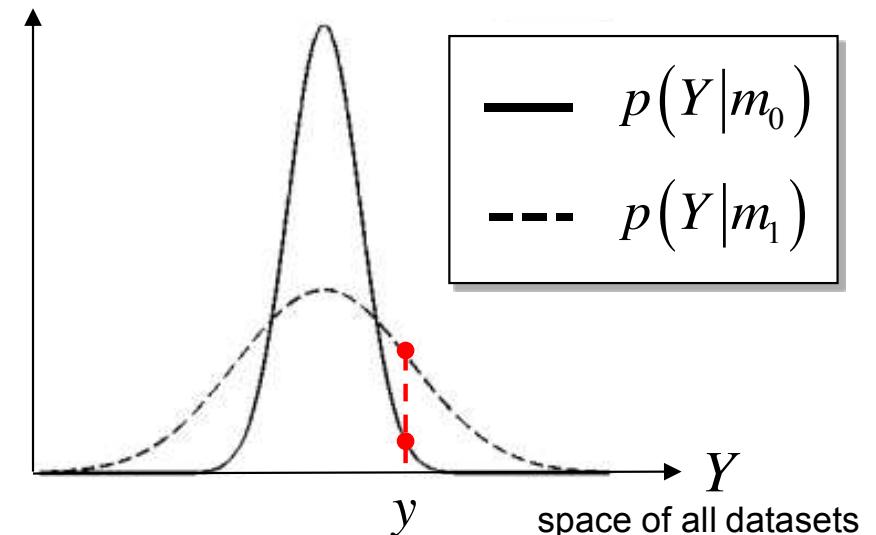
if $P(t > t^* | H_0) \leq \alpha$ then reject H_0

classical (null) hypothesis testing

- define two alternative models, e.g.:

$$m_0 : p(\theta|m_0) = \begin{cases} 1 & \text{if } \theta = 0 \\ 0 & \text{otherwise} \end{cases}$$

$$m_1 : p(\theta|m_1) = N(0, \Sigma)$$



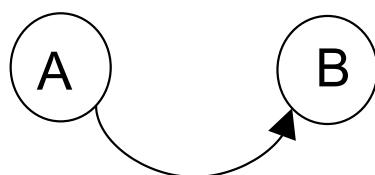
- apply decision rule, e.g.:

if $\frac{P(m_0|y)}{P(m_1|y)} \geq \alpha$ then accept m_0

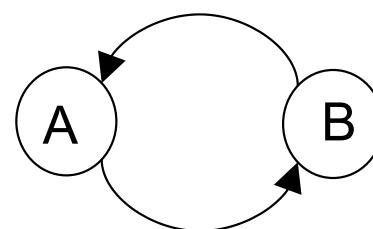
Bayesian Model Comparison

Family-level inference

$$P(m_1|y) = 0.04$$



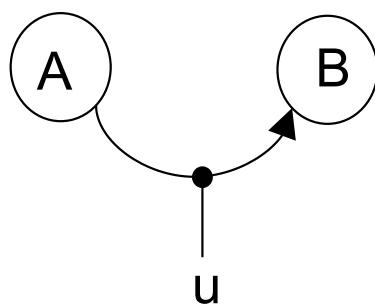
$$P(m_2|y) = 0.25$$



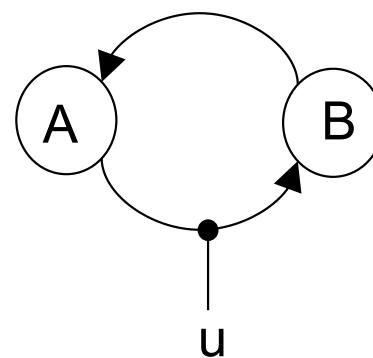
model selection error risk:

$$P(e=1|y) = 1 - \max_m P(m|y) \\ = 0.3$$

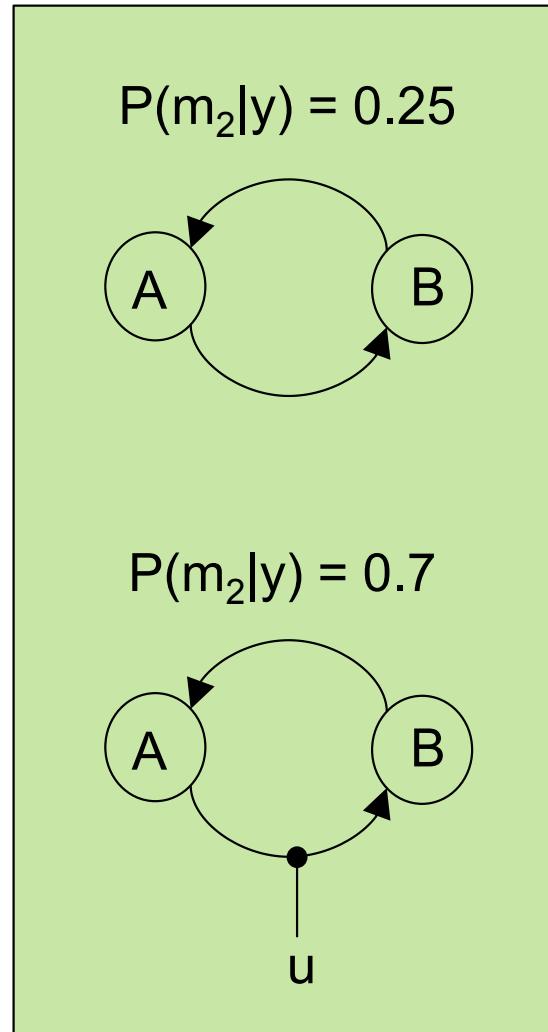
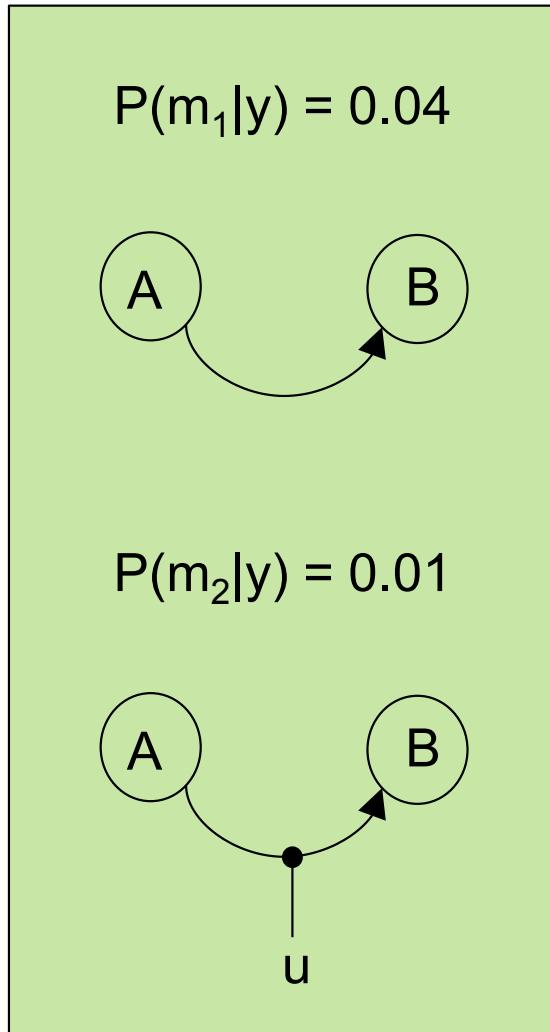
$$P(m_2|y) = 0.01$$



$$P(m_2|y) = 0.7$$



Family-level inference



model selection error risk:

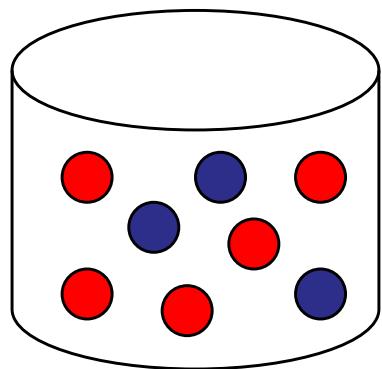
$$P(e=1|y) = 1 - \max_m P(m|y)$$
$$= 0.3$$

family inference
(pool statistical evidence)

$$P(f|y) = \sum_{m \in f} P(m|y)$$

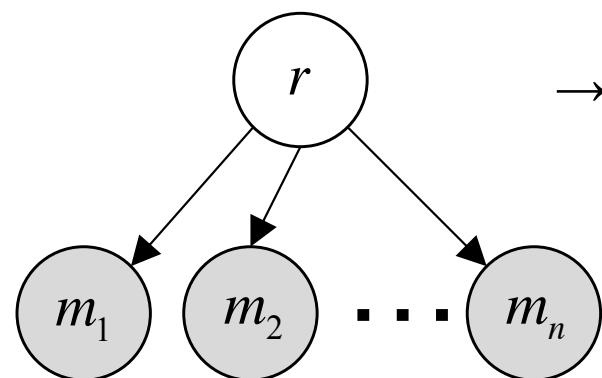
$$P(e=1|y) = 1 - \max_f P(f|y)$$
$$= 0.05$$

Sampling subjects as marbles in an urn



$\begin{cases} m_i = 1 & \rightarrow i^{\text{th}} \text{ marble is blue} \\ m_i = 0 & \rightarrow i^{\text{th}} \text{ marble is purple} \end{cases}$

r = proportion of blue marbles in the urn



→ (binomial) probability of drawing a set of n marbles:

$$p(m|r) = \prod_{i=1}^n r^{m_i} (1-r)^{1-m_i}$$

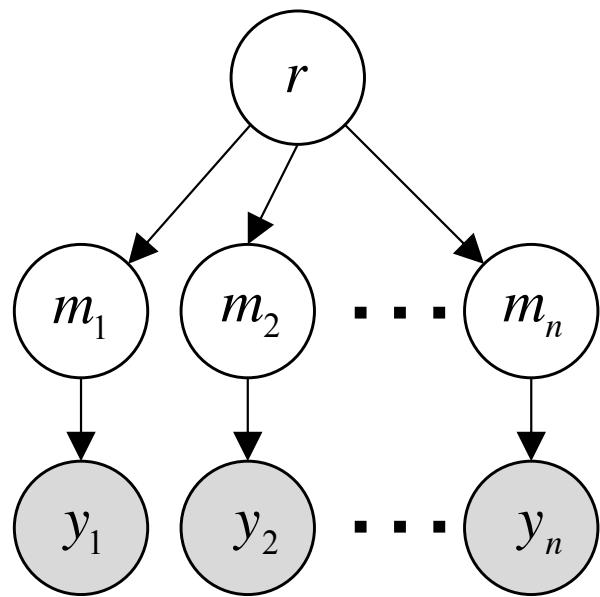
Thus, our belief about the proportion of blue marbles is:

$$p(r|m) \propto p(r) \prod_{i=1}^n r^{m_i} (1-r)^{1-m_i} \stackrel{p(r) \propto 1}{\Rightarrow} E[r|m] = \frac{1}{n} \sum_{i=1}^n m_i$$

Group-level model comparison

At least, we can measure how likely is the i^{th} subject's data under each model!


$$p(y_1|m_1) \ p(y_2|m_2) \ \dots \ p(y_i|m_i) \ \dots \ p(y_n|m_n)$$



$$p(r, m|y) \propto p(r) \prod_{i=1}^n p(y_i|m_i) p(m_i|r)$$

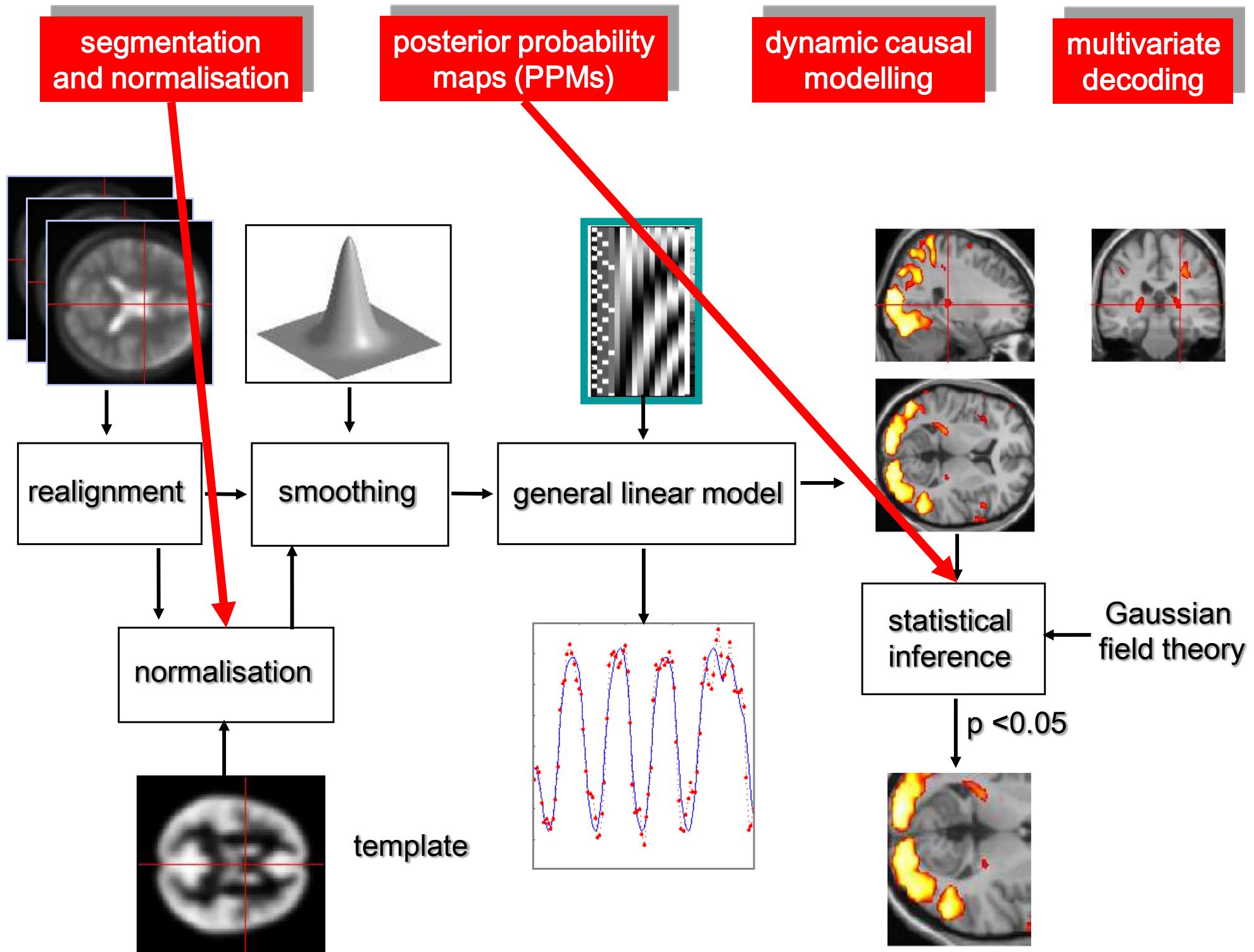
Our belief about the proportion of models is:

$$p(r|y) = \sum_m p(r, m|y)$$

Exceedance probability: $\varphi_k = P(r_k > r_{k' \neq k} | y)$

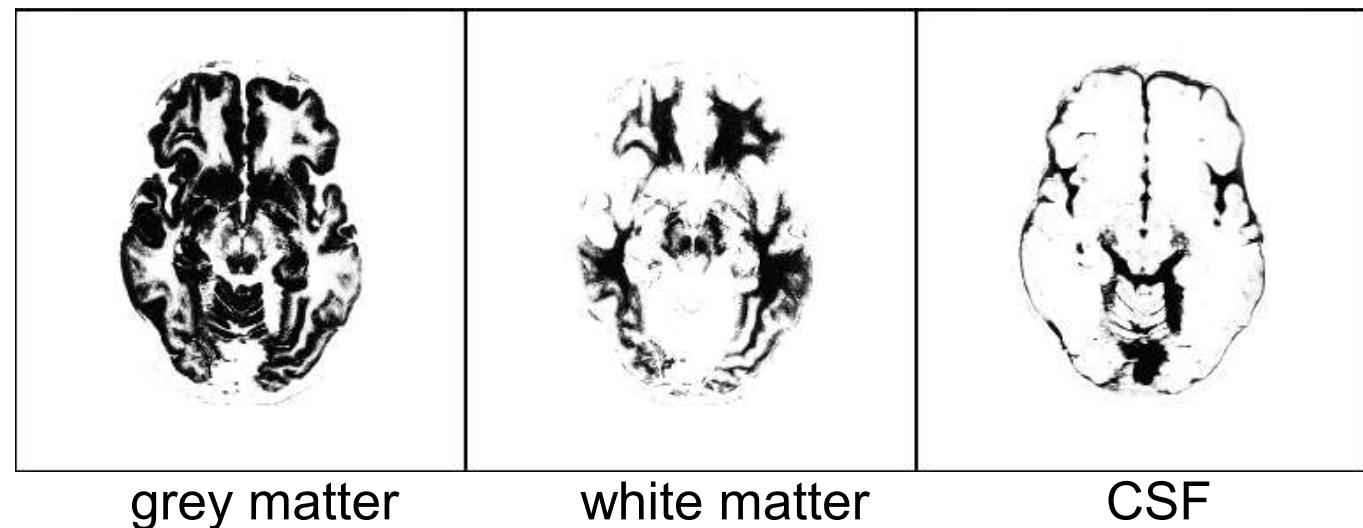
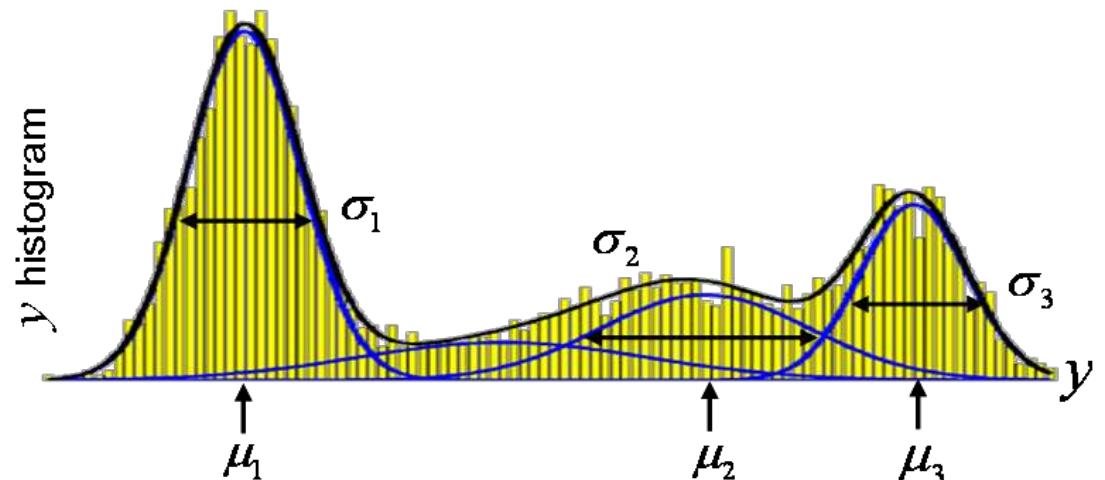
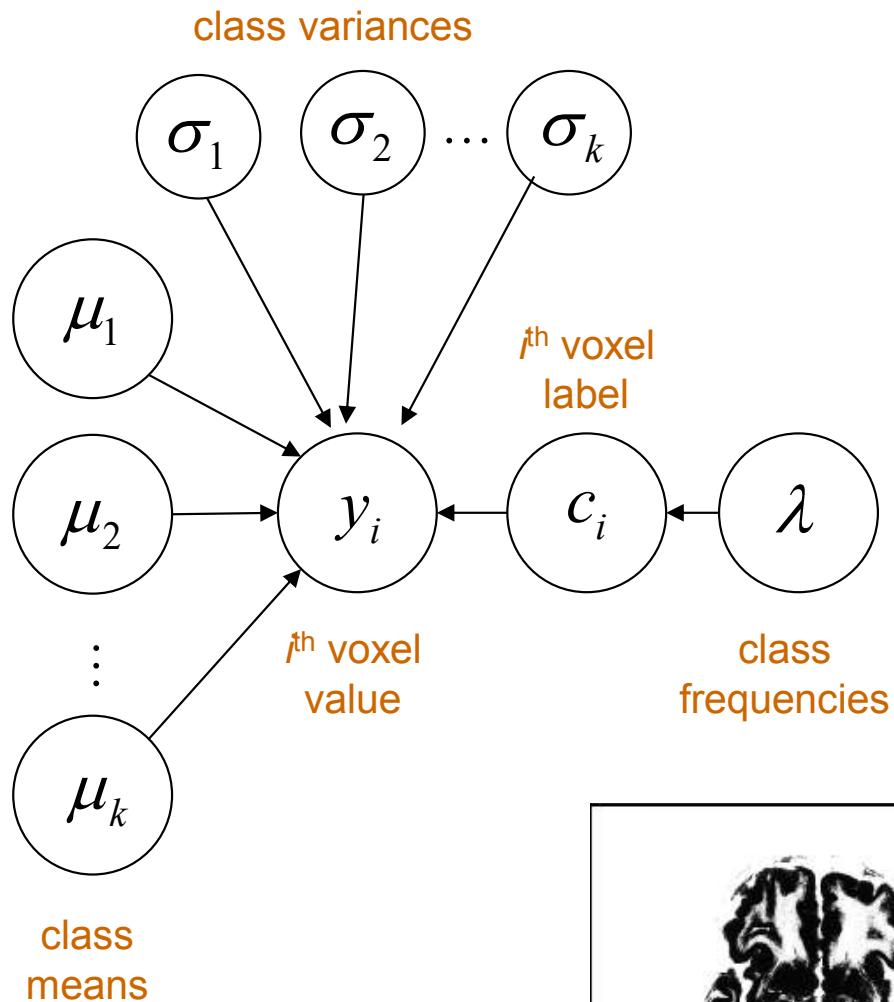
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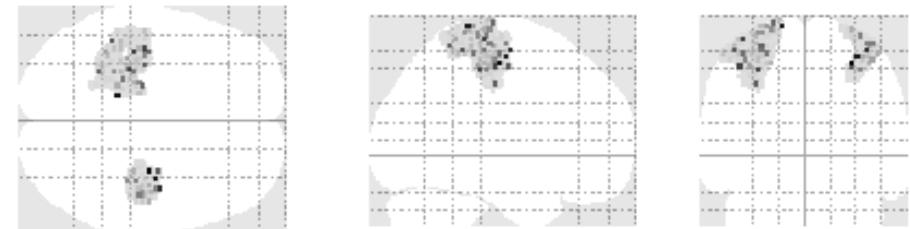
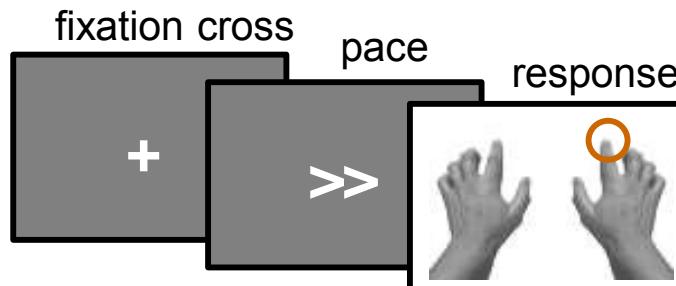
aMRI segmentation

mixture of Gaussians (MoG) model

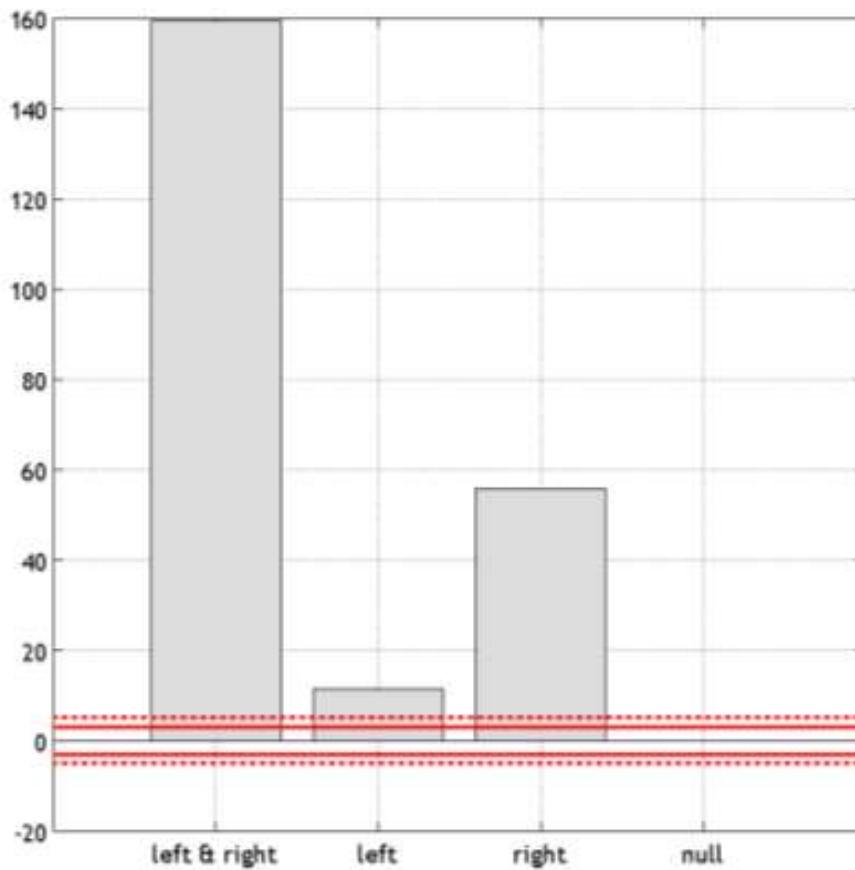


Decoding of brain images

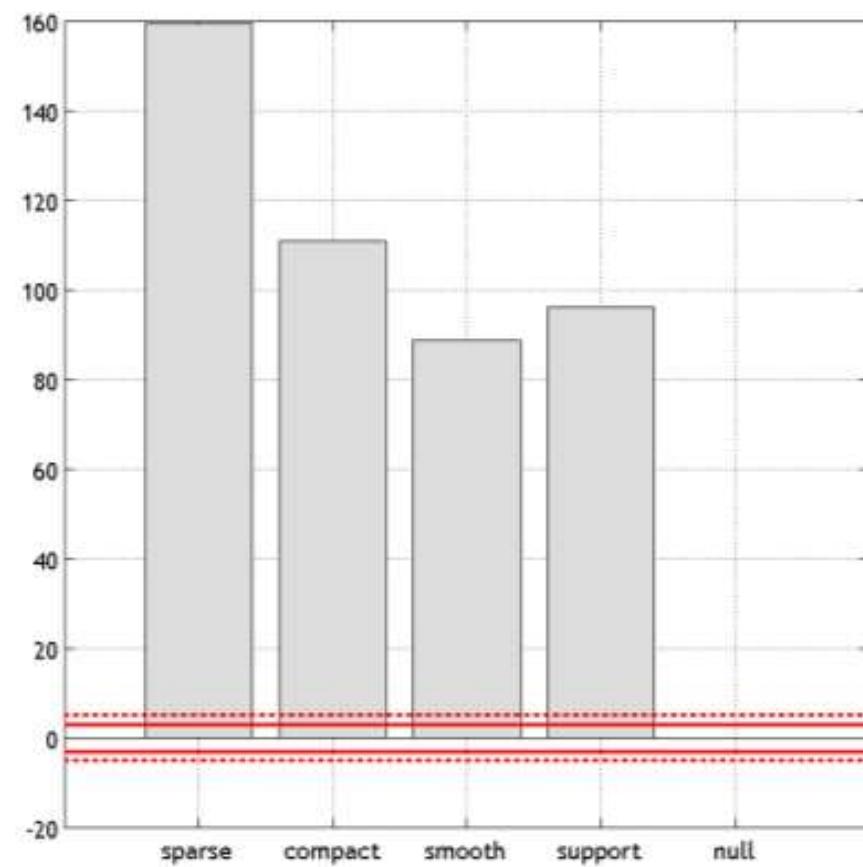
recognizing brain states from fMRI



log-evidence of X-Y sparse mappings:
effect of lateralization



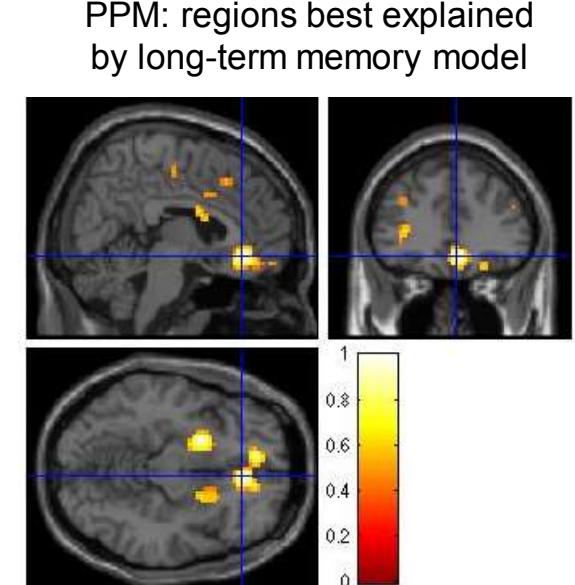
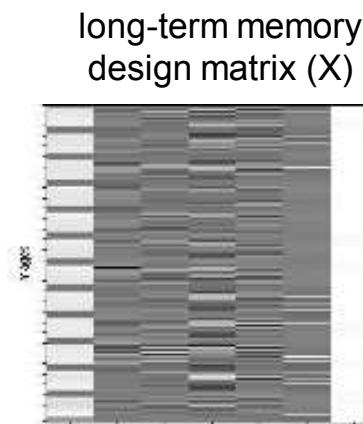
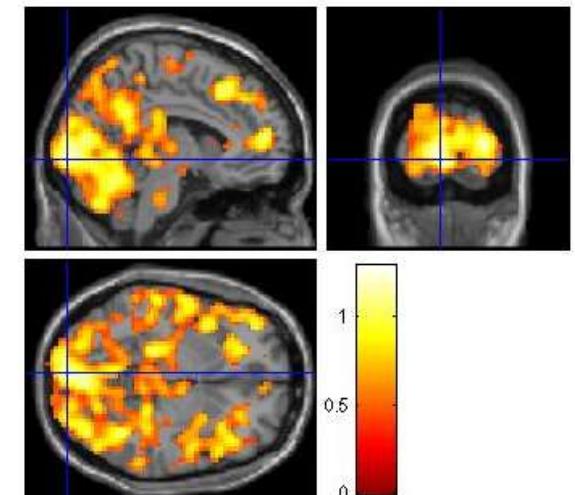
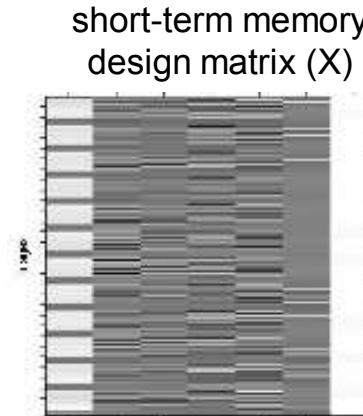
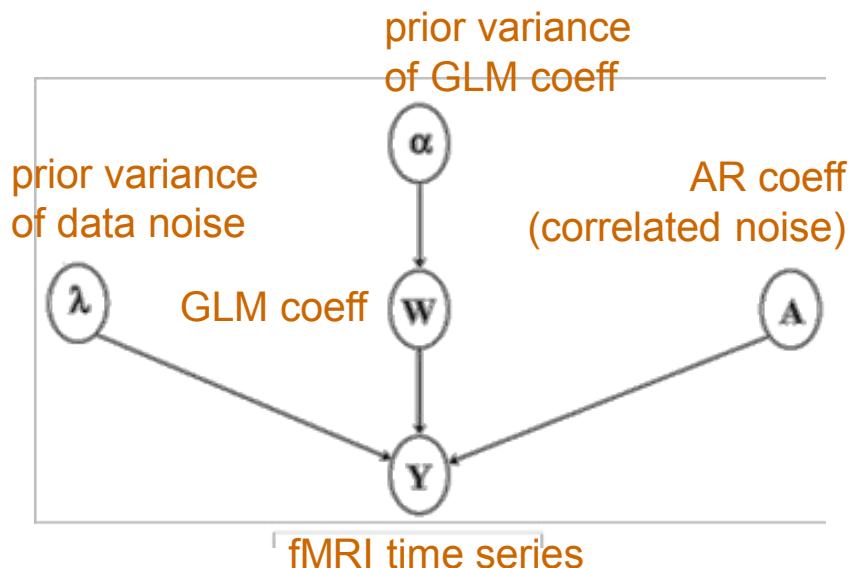
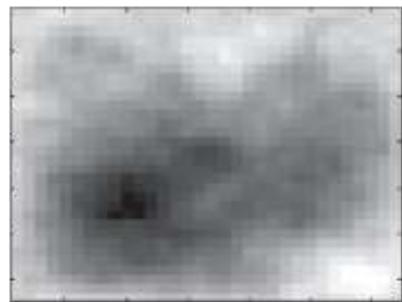
log-evidence of X-Y bilateral mappings:
effect of spatial deployment



fMRI time series analysis

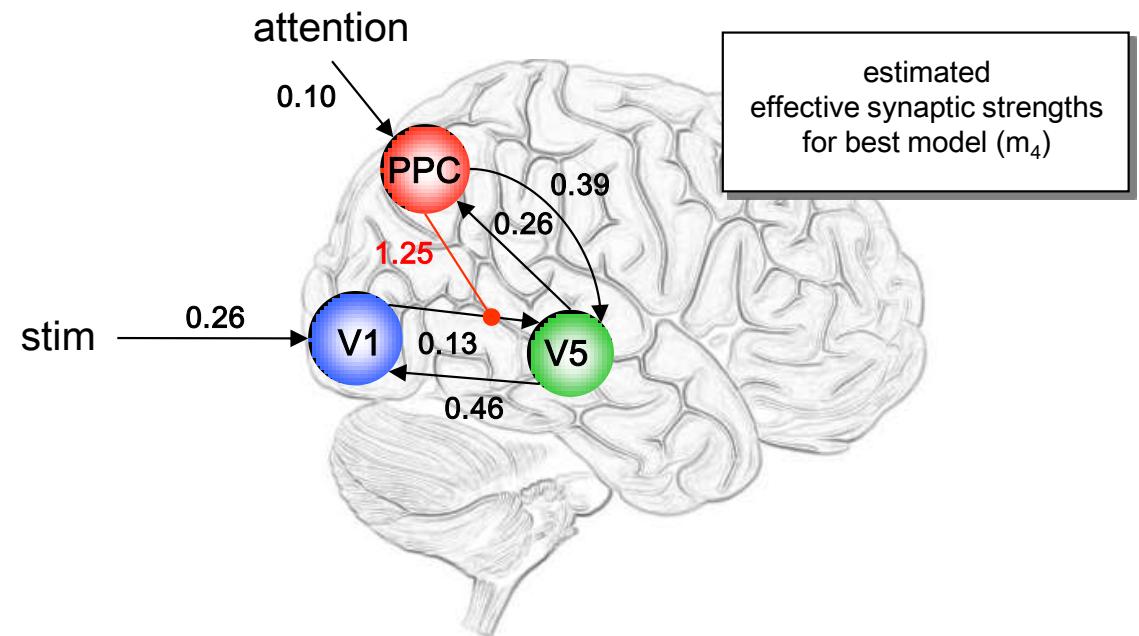
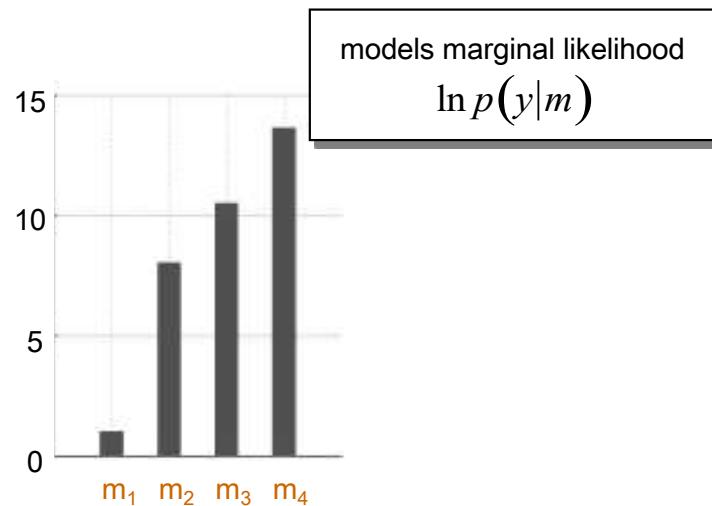
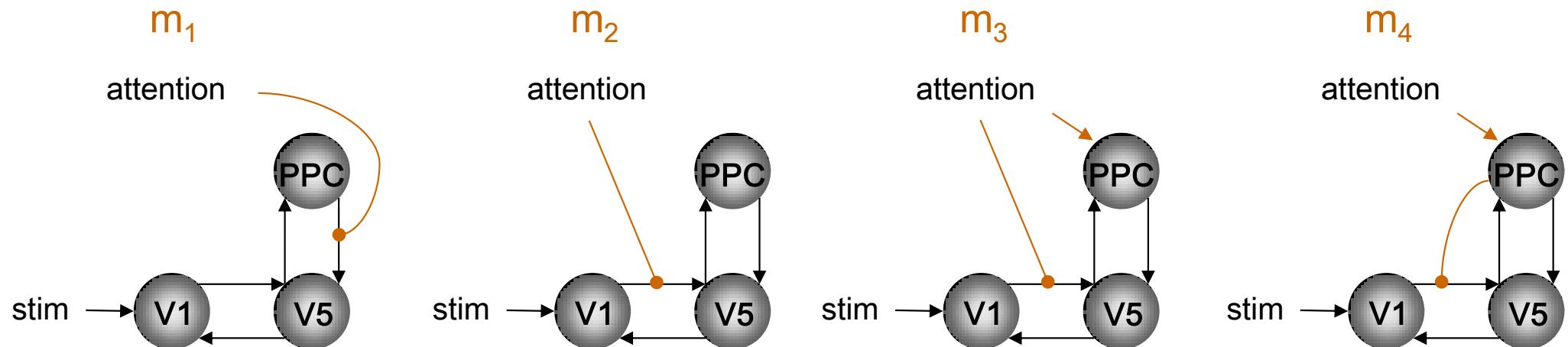
spatial priors and model comparison

$$\begin{matrix} & & 1 \\ & 2 & -8 & 2 \\ 1 & -8 & 20 & -8 & 1 \\ & 2 & -8 & 2 \\ & & 1 \end{matrix}$$

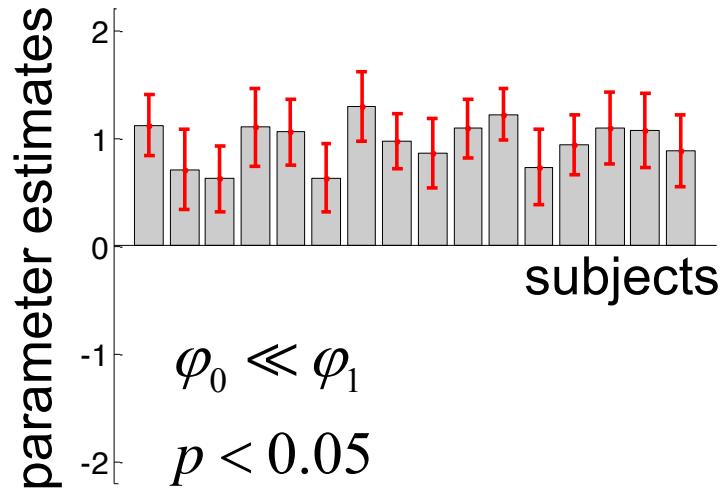


Dynamic Causal Modelling

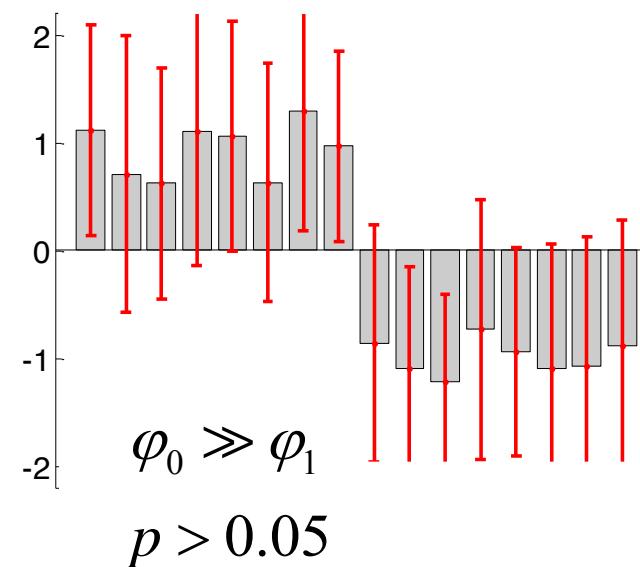
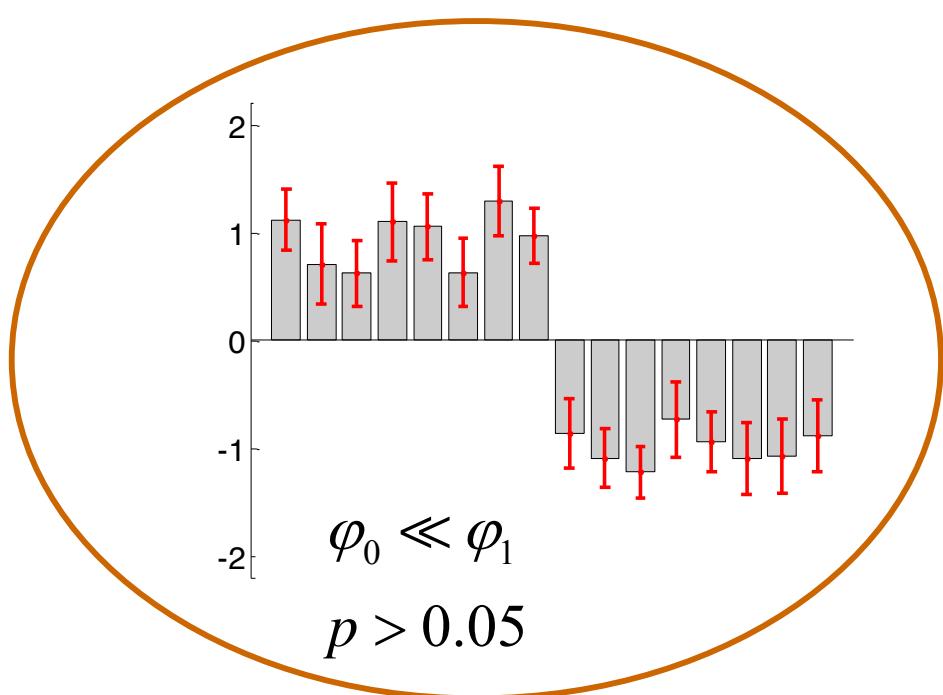
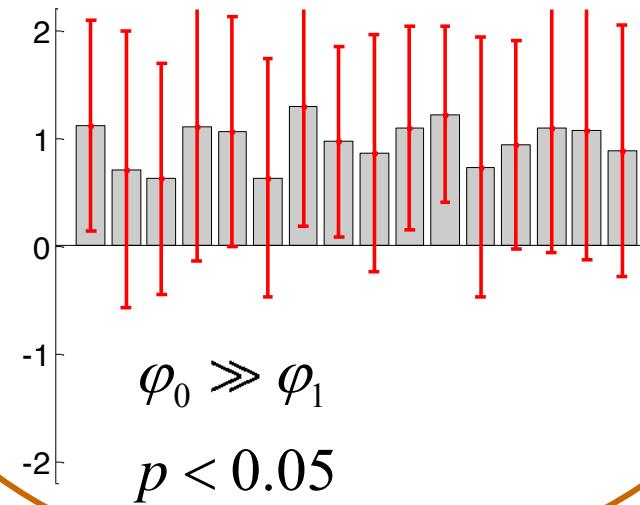
network structure identification



SPM: frequentist vs Bayesian RFX analysis



$\theta = 0 ?$



I thank you for your attention.

A note on statistical significance

lessons from the Neyman-Pearson lemma

- **Neyman-Pearson lemma:** the likelihood ratio (or Bayes factor) test

$$\Lambda = \frac{p(y|H_1)}{p(y|H_0)} \geq u$$

is the most powerful test of size $\alpha = p(\Lambda \geq u | H_0)$ to test the null.

- what is the threshold u , above which the Bayes factor test yields a error I rate of 5%?

