Dynamic Causal Modelling : Advanced Topics

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Zurich SPM Course, Feb 19th 2016



- Bayesian Model Selection
- i. Machinery
- ii. Statistics
- Non-vanilla options in DCM for fMRI
- Models in Models
- L. Computational Renderings of Behaviour in DCMS
- II. Clinical Translational Applications

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Generative model



- 1. enforces mechanistic thinking: how could the data have been caused? Where do we look next?
- 2. generate synthetic data (observations) by sampling from the prior can model explain certain phenomena at all?
- 3. inference about model structure: formal approach to disambiguating mechanisms $\rightarrow p(y|m)$
- 4. inference about parameters $\rightarrow p(\theta | y)$
- 5. A natural framework to test interventions \rightarrow adjusting the optimized state space

Parameter estimation: Bayesian inversion

Estimate neural & hemodynamic parameters such that the **MODELLED** and **MEASURED** BOLD signals are similar (model evidence is optimised), using variational EM under Laplace approximation

... Noise Assumption (Gaussian with temporal correlations) leads to a probabilistic model.So for one data point :





Parameter estimation: Bayesian inversion



Have Data Have Likelihood Specify Prior The Posterior:

$$p(\theta \mid y, m) = \frac{p(y \mid \theta, m) p(\theta, m)}{p(y \mid m)}$$

Marginal Likelihood – tricky integral... try it !

$$p(y \mid m) = \int p(y \mid \theta, m) p(\theta) d\theta$$

Instead – let's assume a partition over parameter space is possible

- 1. Split hyperparameter from parameters
 - 2. Assume some form of posterior

$$p(\theta, \lambda | y) \approx q(\theta, \lambda) = q(\theta)q(\lambda)$$

Idea: find an approximation $q(\theta)$ to the true posterior $p(\theta|y)$.

Often done by assuming a particular form for q and then optimizing its sufficient statistics (fixed form VB).



Free-energy approximation to marginal likelihood

$F(q) = lnp(y|m) - KL(q(\theta, \lambda), p(\theta, \lambda|y))$

Turned an integral problem into a simpler optimization (find max) where standard procedures can be applied

Maximise variational energies via gradient ascent

$$q(\theta) \propto \exp(I_{\theta}) = \exp\left[\left\langle \ln p(y,\theta,\lambda) \right\rangle_{q(\lambda)}\right]$$
$$q(\lambda) \propto \exp(I_{\lambda}) = \exp\left[\left\langle \ln p(y,\theta,\lambda) \right\rangle_{q(\theta)}\right]$$

Parameter estimation & model evidence: Variational Bayes



Parameter estimation & model evidence: Variational Bayes



Alternative Schemes for Parameter Estimation

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Gradient-based MCMC samplers for dynamic causal modelling



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ABSTRACT

In this technical note, we derive two MCMC (Markov chain Monte Carlo) samplers for dynamic causal models (DCMs). Specifically, we use (a) Hamiltonian MCMC (HMC-E) where sampling is simulated using Hamilton's equation of motion and (b) Langevin Monte Carlo algorithm (LMC-R and LMC-E) that simulates the Langevin diffusion of samples using gradients either on a Euclidean (E) or on a Riemannian (R) manifold. While LMC-R requires minimal tuning, the implementation of HMC-E is heavily dependent on its tuning parameters. These parameters are therefore optimised by learning a Gaussian process model of the time-normalised sample correlation matrix. This allows one to formulate an objective function that balances tuning parameter exploration and exploitation, furnishing an intervention-free inference scheme. Using neural mass models (NMMs)-a class of biophysically motivated DCMs-we find that HMC-E is statistically more efficient than LMC-R (with a Riemannian metric); yet both gradient-based samplers are far superior to the random walk Metropolis algorithm, which proves inadequate to steer away from dynamical instability.



Gradient-free MCMC methods for dynamic causal modelling

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ABSTRACT

Article history: Received 3 October 2014 Accepted 6 March 2015 Available online 14 March 2015 In this technical note we compare the performance of four gradient-free MCMC samplers (random walk Metropolis sampling, slice-sampling, adaptive MCMC sampling and population-based MCMC sampling with tempering) in terms of the number of independent samples they can produce per unit computational time. For the Bayesian inversion of a single-node neural mass model, both adaptive and population-based samplers are more efficient compared with random walk Metropolis sampler or slice-sampling; yet adaptive MCMC sampling is more promising in terms of compute time. Slice-sampling yields the highest number of independent samples from the target density – albeit at almost 1000% increase in computational time, in comparison to the most efficient algorithm (i.e., the adaptive MCMC sampler).

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Effects of Acute Tryptophan Depletion on Prefrontal-Amygdala Connectivity While Viewing Facial Signals of Aggression

Passamonti et al. Biological Psychiatry 2012

"Analysis of Effective Connectivity 2: DCM

For placebo, RFX-BMS indicated evidence favoring model C1.1. Driving inputs (all faces) entered the system via the amygdala alone, whereas the angry vs. neutral modulator affected bidirectional connections in all three pathways. Hence, during placebo, the effect of the task is distributed within internal PFC circuitry and across PFC-amygdala connections.

Under ATD, the expected and exceedance probabilities of C1.1 were reduced with increased expected and exceedance probabilities of the two models (C2.1, C3.1) in which the contextual modulator acted on two or one bidirectional connections. Furthermore, during ATD, another family of six models became more likely than under placebo, in which driving inputs "perturbed" the network via either the VLPFC or vACC alone.

To summarize, ATD reduced not only the number of PFC–amygdala pathways affected by processing angry faces but also the location where face information entered the network."

Given competing hypotheses on structure & functional mechanisms of a system, which model is the best?

Which model represents the best balance between model fit and model complexity?

For which model m does p(y|m) become maximal?



Pitt & Miyung (2002) TICS

Logarithm is a monotonic function



Maximizing log model evidence = Maximizing model evidence

Log model evidence = balance between fit and complexity

$$\log p(y \mid m) = accuracy(m) - complexity(m)$$

= log p(y | \theta, m) - complexity(m)
Akaike Information Criterion: AIC = log p(y | \theta, m) - p No. of data points
Bayesian Information Criterion: BIC = log p(y | \theta, m) - \frac{p}{2} log N

Penny et al. 2004a, *NeuroImage*

Bayesian Model Comparison

The model goodness: Negative Free Energy

$$F = \log p(y \mid m) - KL[q(\theta), p(\theta \mid y, m)]$$

Accuracy - Complexity

$$KL[q(\theta), p(\theta \mid m)]$$

= $\frac{1}{2} \ln |C_{\theta}| - \frac{1}{2} \ln |C_{\theta|y}| + \frac{1}{2} (\mu_{\theta|y} - \mu_{\theta})^T C_{\theta}^{-1} (\mu_{\theta|y} - \mu_{\theta})^T$



The complexity term of *F* is higher

the more independent the prior parameters (↑ effective DFs)

the more dependent the posterior parameters

the more the posterior mean deviates from the prior mean

To compare two models, we could just compare their log evidences.

But: the log evidence is just some number – not very intuitive!

A more intuitive interpretation of model comparisons is made possible by Bayes factors:

positive value, [0; ∞ [

$$B_{12} = \frac{p(y \mid m_1)}{p(y \mid m_2)}$$

Kass & Raftery classification:

Kass & Raftery 1995, J. Am. Stat. Assoc.

B ₁₂	p(m₁ y)	Evidence	
1 to 3	50-75%	weak	
3 to 20	75-95%	positive	
20 to 150	95-99%	strong	
≥ 150	≥ 99%	Very strong	

Model Comparison at the Group Level

- Prior to/ instead of inference on parameters
- Which of various mechanisms / models best explains my data
- Use model evidence

accounts for both accuracy and complexity of the model

allows for inference about structure (generalisability) of the model

Fixed Effects Model selection via

log Group Bayes factor:

$$BF_{1,2} = \sum_{k} \ln p(y|m_1) - \sum_{k} \ln p(y|m_2)$$

Random Effects Model selection via Model probability: $p(r \mid y, \alpha)$ $\langle r_k \rangle_q = \alpha_k / (\alpha_1 + ... + \alpha_K)$

Group Bayes factor (GBF) for 1...K subjects:

$$GBF_{ij} = \prod_{k} BF_{ij}^{(k)}$$

Average Bayes factor (ABF):

$$ABF_{ij} = \sqrt[K]{\prod_{k} BF_{ij}^{(k)}}$$

Problems:

- blind with regard to group heterogeneity
- sensitive to outliers

Random effects BMS for heterogeneous groups



Random effects BMS for heterogeneous groups



Random effects BMS for heterogeneous groups



Stephan et al. 2009a, NeuroImage

Inference about DCM parameters: Bayesian single subject analysis

- Gaussian assumptions about the posterior distributions of the parameters
- posterior probability that a certain parameter (or contrast of parameters) is above a chosen threshold γ:
- By default, γ is chosen as zero the prior ("does the effect exist?").



Inference about DCM parameters: Bayesian parameter averaging

FFX group analysis:

- Likelihood distributions from different subjects are independent •
- Under Gaussian assumptions, this is easy to compute •
- Simply 'weigh' each subject's contribution by your certainty of the parameter \bullet



RFX Approach: Analogous to 'random effects' analyses in SPM, 2nd level analyses can be applied to DCM parameters



Putting model and parameter space together

Bayesian Model Averaging (BMA)

- abandons dependence of parameter inference on a single model
- uses the entire model space considered (or an optimal family of models)
- computes average of each parameter, weighted by posterior model probabilities
- represents a particularly useful alternative
 - when none of the models (or model subspaces) considered clearly outperforms all others
 - when comparing groups for which the optimal model differs

$$p(\theta_n | y_{1..N})$$

= $\sum_m p(\theta_n | y_n, m) p(m | y_{1..N})$

NB: $p(m|y_{1..N})$ can be obtained by either FFX or RFX BMS

Penny et al. 2010, PLoS Comput. Biol.

Example 2: Brain Connectivity in Synesthesia

Study: van Leeuwen, den Ouden & Hagoort, 2011

- Specific sensory stimuli lead to unusual, additional experiences
- Grapheme-color synesthesia: color
- Involuntary, automatic; stable over time, prevalence ~4%
- Potential cause: aberrant cross-activation between
 - grapheme encoding area (letter-shape area)
 - color area V4
 - superior parietal lobule (SPL)



Hubbard, 2007

Can changes in effective connectivity explain synesthesia activity in V4?

Example 2: Brain Connectivity in Synesthesia

Competing Model Hypotheses

<u>Model 1</u> Grapheme color synesthesia induced by direct cross-activation in ventral-occipital cortex

Model 2 Disinhibition feedback hypothesis, aberrant feedback from multimodal region SPL, activating V4

Stimuli: Graphemes (G)

- Synesthesia-inducing graphemes (SG)
- Colored Control graphemes (CG)



Initially no winning model

Example 2: Brain Connectivity in Synesthesia



Relative model evidence predicts sensory experience



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Factorial structure of model specification

• Three dimensions of model specification:

- bilinear vs. nonlinear
- single-state vs. two-state (per region)
- deterministic vs. stochastic

	-				
	Мо	del options:			
		m	odulatory effects	bilinear	nonlinear
	📣 Dynamic Cau	sal Modelling			
	Model options:				
	n	nodulatory effects	bilin	ear	
		states per region	one	two	
namic	Causal Modelling				
option	9:				
	modulatory effects	biline	ar		
	states per region	one	e .		
	stochastic effects	no	yes		

Model

bilinear DCM



bilinear DCM

non-linear DCM



Two-dimensional Taylor series (around $x_0=0$, $u_0=0$):

$$\frac{dx}{dt} = f(x,u) \approx f(x_0,0) + \frac{\partial f}{\partial x}x + \frac{\partial f}{\partial u}u + \frac{\partial^2 f}{\partial x \partial u}ux + \frac{\partial^2 f}{\partial x^2}\frac{x^2}{2} + \dots$$

Bilinear state equation:

Nonlinear state equation:

$$\frac{dx}{dt} = \left(A + \sum_{i=1}^{m} u_i B^{(i)}\right) x + Cu$$

$$\frac{dx}{dt} = \left(A + \sum_{i=1}^{m} u_i B^{(i)} + \sum_{j=1}^{n} x_j D^{(j)}\right) x + Cu$$



$$\dot{x} = \Im x + Cu$$
$$\Im_{ij} = A_{ij} + uB_{ij}$$



Stochastic DCM

$$\frac{dx}{dt} = (A + \sum_{j} u_{j} B^{(j)}) x + Cv + \omega^{(x)}$$
$$v = u + \omega^{(v)}$$

- all states are represented in generalised coordinates of motion
- random state fluctuations w^(x) account for endogenous fluctuations, have unknown precision and smoothness
 → two hyperparameters
- fluctuations w^(v) induce uncertainty about how inputs influence neuronal activity
- can be fitted to "resting state" data but not necessarily
- DEM optimization scheme



Spectral DCM for ,Resting Stare'

Alternative Approach to Stochastic Data

- Examine 2nd order statistics in response to noise input
- deterministic model that generates predicted crossed spectra in a distributed neuronal network or graph
- finds the effective connectivity among hidden neuronal states that best explains the observed functional connectivity among hemodynamic responses
- advantage:
 - replaces an optimisation problem wrt. stochastic differential equations with a deterministic approach from linear systems theory → computationally very efficient
- disadvantages:
 - assumes stationarity (as do other rsfMRI methods)



Friston et al. 2014, NeuroImage

cross-spectra = inverse Fourier transform of crosscorrelation

cross-correlation = generalized form of correlation (at zero lag, this is the conventional measure of functional connectivity)



Oppenheimer & Shafer for Ref

Friston et al. 2014, NeuroImage

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Learning of dynamic audio-visual associations



den Ouden et al. 2010, J. Neurosci.

Hierarchical Bayesian learning model



prior on volatility

volatility

probabilistic association

observed events



Behrens et al. 2007, Nat. Neurosci.

Explaining RTs by different learning models



- 5 alternative learning models:
- categorical probabilities
- hierarchical Bayesian learner
- Rescorla-Wagner
- Hidden Markov models (2 variants)



den Ouden et al. 2010, J. Neurosci.

Prediction error (PE) activity in the putamen

PE during active sensory learning

PE during incidental sensory learning



4
3.5
3
2.5
2
1.5
1
1.5
0.5
0

den Ouden et al. 2009, *Cerebral Cortex*



O'Doherty et al. 2004, *Science*



PE = "teaching signal" for synaptic plasticity during learning

Could the putamen be regulating trial-by-trial changes of task-relevant connections?

Prediction errors control plasticity during adaptive cognition

- Modulation of visuomotor connections by striatal prediction error activity
- Influence of visual areas on premotor cortex:
 - stronger for surprising stimuli
 - weaker for expected stimuli



den Ouden et al. 2010, J. Neurosci.

Generative embedding (unsupervised): detecting patient subgroups



Brodersen et al. 2014, NeuroImage: Clinical

Generative embedding: DCM and variational Gaussian Mixture Models



- 42 controls vs. 41 schizophrenic patients
- fMRI data from working memory task (Deserno et al. 2012, J. Neurosci)

Brodersen et al. (2014) NeuroImage: Clinical

Detecting subgroups of patients in schizophrenia



Brodersen et al. (2014) NeuroImage: Clinical

Key methods papers: Advanced DCM for fMRI and BMS – part 1

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Thank you and the FIL Methods Group

& in particular

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